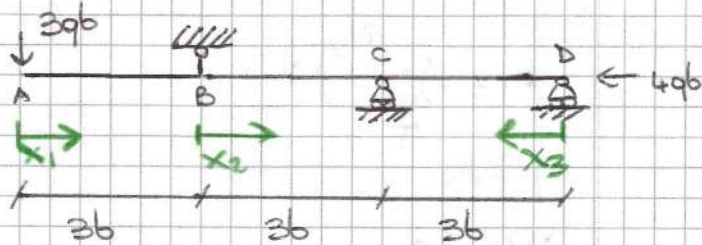


Esercizio N° 1 - Traccia 1 - Esame 18.07.2023

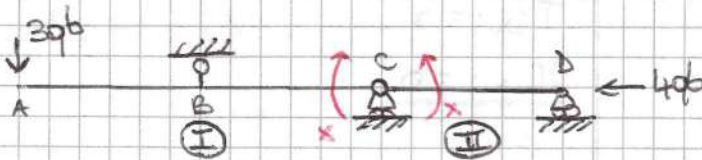


STRUTTURA IPERSTATICA

$$GDL = 3$$

$$GDU = 2(B) + 1(C) + 1(D) = 4$$

$$GDL < GDU$$



STRUTTURA ISOSTATICA

$$GDL = 6$$

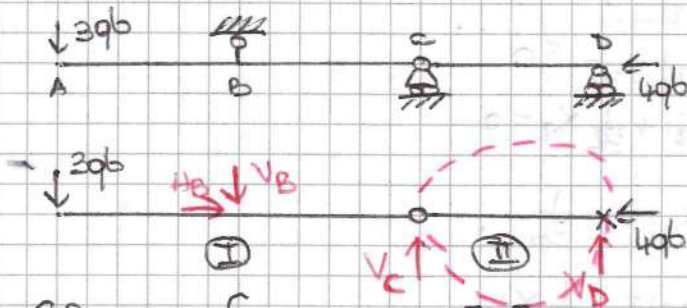
$$GDU = 2(B) + 3(C) + 1(D) = 6$$

$$GDL = GDU$$

Eq. di congruenza

$$\Delta \varphi_c = 0$$

S₀ - SISTEMA REALE



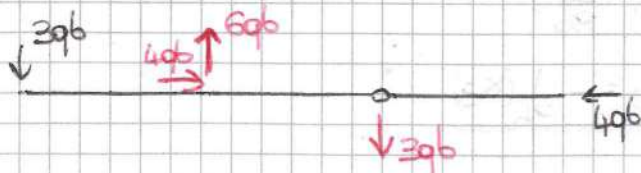
$$\begin{cases} R_x = 0 \\ R_y = 0 \\ \mathcal{M}_{z(c)} = 0 \end{cases} \begin{cases} H_B - 4qb = 0 \quad [1] \\ 3qb + V_B - V_C - V_D = 0 \quad [2] \\ 3qb(3b) + V_B(6b) - V_C(3b) = 0 \quad [3] \end{cases}$$

$$\begin{cases} \mathcal{M}_{z(c)} = 0 \\ \mathcal{M}_{z(c)} = 0 \end{cases} \begin{cases} V_D(3b) = 0 \Rightarrow \underline{V_D = 0} \end{cases}$$

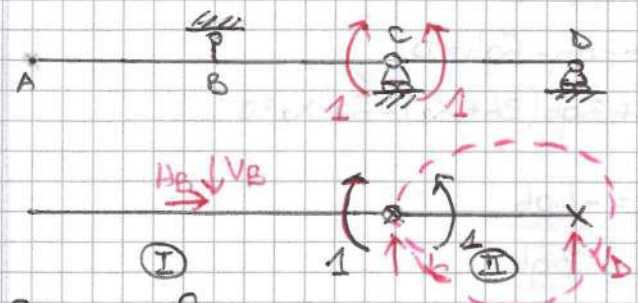
$$[1] \underline{H_B = 4qb}$$

$$[2] V_B = V_C - 3qb \Rightarrow \underline{V_B = -6qb}$$

$$[3] 27qb^2 + 6bV_C - 18qb^2 - 3bV_C = 0 \\ 3bV_C = -9qb^2 \Rightarrow \underline{V_C = -3qb}$$



S₁ - SISTEMA EQUILIBRATO

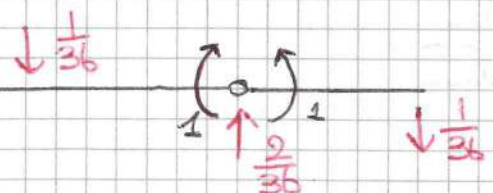


$$\begin{cases} R_x = 0 \\ R_y = 0 \\ \mathcal{M}_{z(c)} = 0 \end{cases} \begin{cases} H_B = 0 \\ V_B - V_C - V_D = 0 \quad [2] \\ V_B(6b) - V_C(3b) = 0 \quad [3] \end{cases}$$

$$\begin{cases} \mathcal{M}_{z(c)} = 0 \\ \mathcal{M}_{z(c)} = 0 \end{cases} \begin{cases} V_D(3b) + 1 = 0 \Rightarrow \underline{V_D = -\frac{1}{3b}} \end{cases}$$

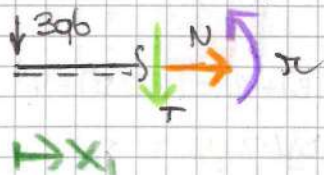
$$[2] V_B = V_C - \frac{1}{3b} \Rightarrow \underline{V_B = \frac{1}{3b}}$$

$$[3] V_C = 2V_B \Rightarrow \underline{V_C = \frac{2}{3b}}$$



AZIONI INTERNE

$A \rightarrow B \quad 0 \leq x_1 \leq 3b$

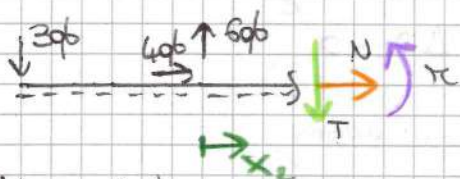


$N(x_1) = 0$

$T(x_1) + 3qb = 0 \Rightarrow T(x_1) = -3qb$

$\pi(x_1) + 3qb(x_1) = 0 \Rightarrow \pi(x_1) = -3qb x_1$

$B \rightarrow C \quad 0 \leq x_2 \leq 3b$



$N(x_2) + 4qb = 0$

$T(x_2) + 3qb - 6qb = 0$

$\pi(x_2) + 3qb(3b + x_2) - 6qb x_2 = 0$

$N(x_2) = -4qb$

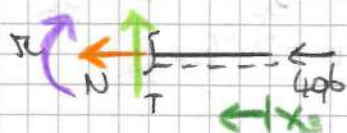
$T(x_2) = 3qb$

$\pi(x_2) + 9qb^2 + 3qb x_2 - 6qb x_2 = 0$

$\pi(x_2) + 9qb^2 - 3qb x_2 = 0$

$\pi(x_2) = 3qb x_2 - 9qb^2$

$C \rightarrow D \quad 0 \leq x_3 \leq 3b$

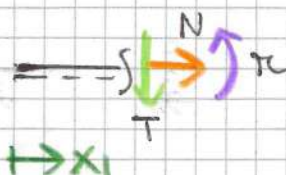


$N(x_3) + 4qb = 0 \Rightarrow N(x_3) = -4qb$

$T(x_3) = 0$

$\pi(x_3) = 0$

$A \rightarrow B \quad 0 \leq x_1 \leq 3b$

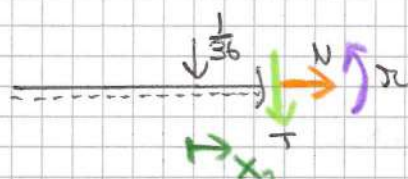


$N(x_1) = 0$

$T(x_1) = 0$

$\pi(x_1) = 0$

$B \rightarrow C \quad 0 \leq x_2 \leq 3b$



$N(x_2) = 0$

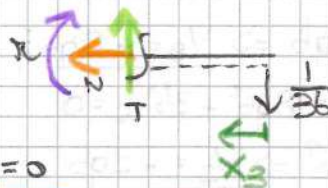
$T(x_2) + \frac{1}{36} = 0$

$\pi(x_2) + \frac{1}{36} x_2 = 0$

$T(x_2) = -\frac{1}{36}$

$\pi(x_2) = -\frac{1}{36} x_2$

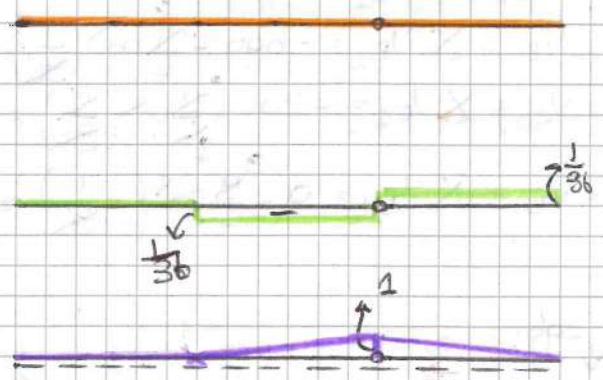
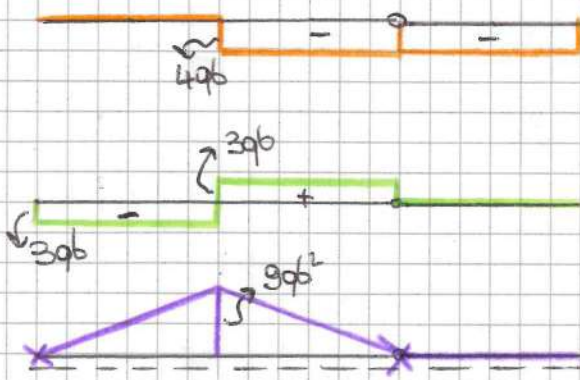
$C \rightarrow D \quad 0 \leq x_3 \leq 3b$



$N(x_3) = 0$

$T(x_3) = \frac{1}{36}$

$\pi(x_3) = -\frac{1}{36} x_3$



P.L.V

$$\mathcal{L}V_e = \mathcal{L}V_i$$

$$\mathcal{L}V_e = 1 \cdot \Delta\varphi_c = 0$$

$$\mathcal{L}V_i = \int_S N \epsilon_i + \int_S T \delta_i + \int_S \pi_1 \chi_i \Rightarrow \mathcal{L}V_i = \int_S \pi_1 \left(\frac{\pi_0 + X \pi_1}{EI} \right)$$

A → B

$$\pi_0 = -3qb x_1 \quad \pi_1 = 0$$

$$\pi_1 \cdot \pi_0 \quad \pi_1^2$$

$$0 \quad 0$$

B → C

$$\pi_0 = 3qb x_2 - 9qb^2 \quad \pi_1 = -\frac{1}{36} x_2$$

$$\pi_1 \cdot \pi_0 \quad \pi_1^2$$

$$-9x_2^2 + 3qb x_2 \quad + \frac{1}{962} x_2^2$$

C → D

$$\pi_0 = 0 \quad \pi_1 = -\frac{x_3}{36}$$

$$\pi_1 \cdot \pi_0 \quad \pi_1^2$$

$$0 \quad \frac{x_3^2}{962}$$

$$\mathcal{L}V_i = \int_0^{36} \frac{-9x_1^2 + 3qb x_1}{EI} dx_1 + X \int_0^{36} \frac{1}{962} x_2^2 \left(\frac{1}{EI} \right) dx_2 + X \int_0^{36} \frac{x_3^2}{962} \left(\frac{1}{EI} \right) dx_3$$

$$= \frac{1}{EI} \left[-9 \frac{x_1^3}{3} + 3qb \frac{x_1^2}{2} \right]_0^{36} + \frac{X}{EI} \left[\frac{1}{962} \left(\frac{x_2^3}{3} \right) \right]_0^{36} + \frac{X}{EI} \left[\frac{1}{962} \left(\frac{x_3^3}{3} \right) \right]_0^{36}$$

$$= \left[-9 \left(\frac{9 \cdot 36^3}{3} \right) + 3qb \left(\frac{9 \cdot 36^2}{2} \right) \right] + X \left[\frac{1}{962} \left(\frac{27 \cdot 36^3}{3} \right) \right] + X \left[\frac{1}{962} \left(\frac{27 \cdot 36^3}{3} \right) \right]$$

$$= -9qb^3 + \frac{27}{2} qb^3 + X(6) + X(6)$$

$$\mathcal{L}V_i = \frac{9}{2} qb^3 + 26X \Rightarrow 26X + \frac{9}{2} qb^3 = 0 \Rightarrow X = -\frac{9}{2} qb^3 \left(\frac{1}{26} \right)$$

$$X = -\frac{9}{4} qb^2$$

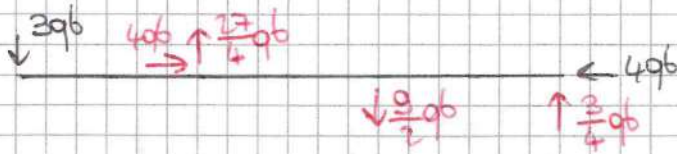
REAZIONI VINCOLE

$$H_B = H_{B0} + \sum H_{B1} = 4qb$$

$$V_B = V_{B0} + \sum V_{B1} = -6qb - \frac{9}{4}qb^2 \left(\frac{1}{3b} \right) = -\frac{27}{4}qb$$

$$V_C = V_{C0} + \sum V_{C1} = -3qb - \frac{9}{4}qb^2 \left(\frac{2}{3b} \right) = -\frac{9}{2}qb$$

$$V_D = V_{D0} + \sum V_{D1} = 0 - \frac{9}{4}qb^2 \left(-\frac{1}{3b} \right) = \frac{3}{4}qb$$



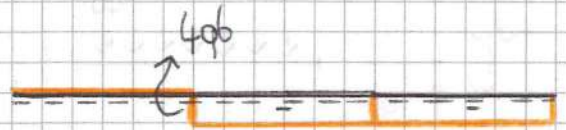
AZIONI INTERNE

A → B

$$N(x_1) = N_0(x_1) + \sum N_1(x_1) = 0$$

$$T(x_1) = T_0(x_1) + \sum T_1(x_1) = -3qb$$

$$\pi(x_1) = \pi_0(x_1) + \sum \pi_1(x_1) = -3qb x_1$$



B → C

$$N(x_2) = -4qb$$

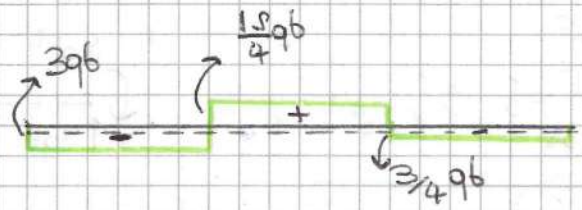
$$T(x_2) = 3qb - \frac{9}{4}qb^2 \left(-\frac{1}{3b} \right)$$

$$= 3qb + \frac{3}{4}qb = \frac{15}{4}qb$$

$$\pi(x_2) = 3qb x_2 - 9qb^2 - \frac{9}{4}qb^2 \left(-\frac{1}{3} x_2 \right)$$

$$= 3qb x_2 - 9qb^2 + \frac{3}{4}qb x_2$$

$$= \frac{15}{4}qb x_2 - 9qb^2$$

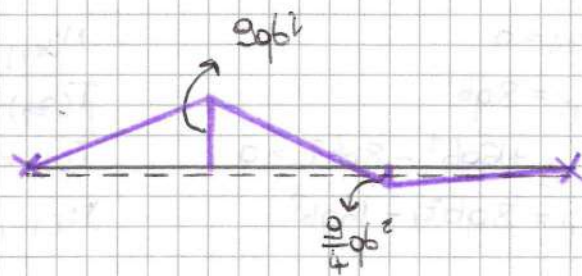


C → D

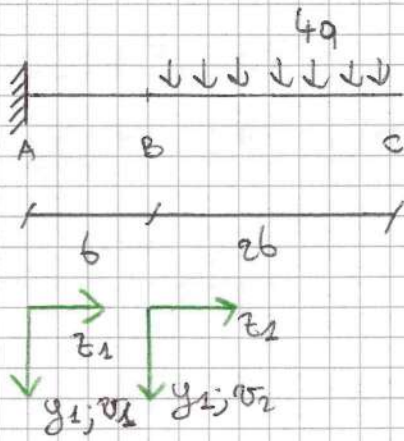
$$N(x_3) = -4qb$$

$$T(x_3) = -\frac{9}{4}qb^2 \left(\frac{1}{3b} \right) = -\frac{3}{4}qb$$

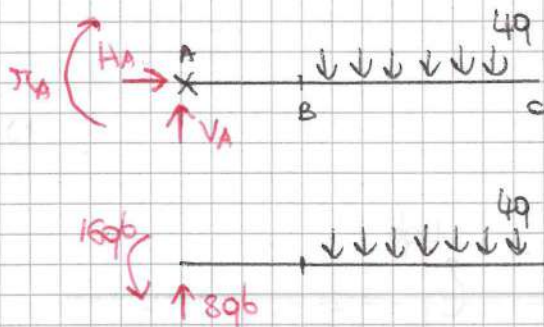
$$\pi(x_3) = -\frac{9}{4}qb^2 \left(-\frac{x_3}{3b} \right) = +\frac{3}{4}qb x_3$$



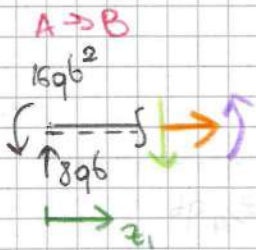
TRACCIA 1 - ESERCIZIO 2 - ESAT 18.07.2023



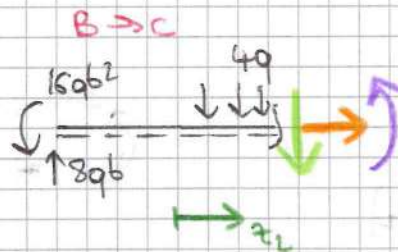
$$\begin{cases} R_x = 0 \\ R_y = 0 \\ \mathcal{M}_{(HA)} = 0 \end{cases} \quad \begin{cases} H_A = 0 \\ V_A - 4q(2b) = 0 \Rightarrow V_A = 8qb \\ \mathcal{M}_A + 4q(2b)(2b) = 0 \Rightarrow \mathcal{M}_A = -16qb^2 \end{cases}$$



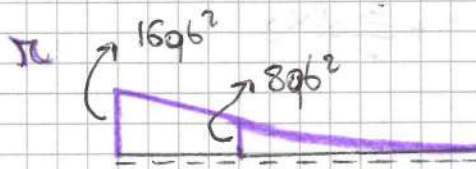
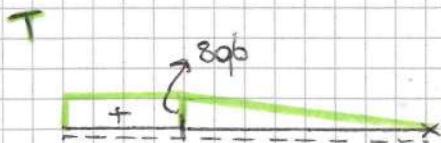
AZIONI INTERNE



$$\begin{aligned} N(z_1) &= 0 \\ T(z_1) &= 8qb \\ \mathcal{M}(z_1) + 16qb^2 - 8qbz_1 &= 0 \\ \mathcal{M}(z_1) &= 8qbz_1 - 16qb^2 \end{aligned}$$



$$\begin{aligned} N(z_2) &= 0 \\ T(z_2) - 8qb + 4qz_2 &= 0 \\ T(z_2) &= 8qb - 4qz_2 \\ \mathcal{M}(z_2) + 16qb^2 - 8qb(b+z_2) + 4q\left(\frac{z_2^2}{2}\right) &= 0 \\ \mathcal{M}(z_2) + 16qb^2 - 8qb^2 - 8qbz_2 + 2qz_2^2 &= 0 \\ \mathcal{M}(z_2) &= 8qbz_2 - 2qz_2^2 - 8qb^2 \end{aligned}$$



Eq. LINEA ELASTICA

A → B

$$v''(z_1) = -\frac{q}{EI} \Rightarrow v''(z_1) = \frac{1}{EI} (-8qbz_1 + 16qb^2)$$

$$v'(z_1) = \frac{1}{EI} \left(-8qb \frac{z_1^2}{2} + 16qb^2 z_1 \right) + A_1 \Rightarrow v'(z_1) = \frac{1}{EI} (-4qbz_1^2 + 16qb^2 z_1) + A_1$$

$$v(z_1) = \frac{1}{EI} \left(-4qb \frac{z_1^3}{3} + 16qb^2 \frac{z_1^2}{2} \right) + A_1 z_1 + A_2 \Rightarrow v(z_1) = \frac{1}{EI} \left(-\frac{4}{3}qbz_1^3 + 8qb^2 z_1^2 \right) + A_1 z_1 + A_2$$

B → C

$$v''(z_2) = -\frac{q}{EI} \Rightarrow v''(z_2) = \frac{1}{EI} (-8qbz_2 + 2qz_2^2 + 8qb^2)$$

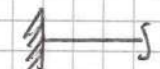
$$v'(z_2) = \frac{1}{EI} \left(-8qb \frac{z_2^2}{2} + 2q \frac{z_2^3}{3} + 8qb^2 z_2 \right) + B_1$$

$$= \frac{1}{EI} \left(-4qbz_2^2 + \frac{2}{3}qz_2^3 + 8qb^2 z_2 \right) + B_1$$

$$v(z_2) = \frac{1}{EI} \left(-4qb \frac{z_2^3}{3} + \frac{2}{3}q \frac{z_2^4}{4} + 8qb^2 \frac{z_2^2}{2} \right) + B_1 z_2 + B_2$$


$$v(z_2) = \frac{1}{EI} \left(-\frac{4}{3}qbz_2^3 + \frac{1}{6}qz_2^4 + 4qb^2 z_2^2 \right) + B_1 z_2 + B_2$$

COSTANTI A_1, A_2, B_1, B_2

A)  INCASTRO

IMPERISSIBILE

$$\left\{ \begin{array}{l} \text{SPOSTAMENTO} \updownarrow \Rightarrow v(z_1)(A) = 0 \\ \text{ROTAZIONE} \curvearrowleft \Rightarrow v'(z_1)(A) = 0 \end{array} \right.$$

B)  SALDATA

ITFONE

$$\left\{ \begin{array}{l} \text{SPOSTAMENTO} \updownarrow \Rightarrow v(z_1)(B) = v(z_2)(B) \\ \text{ROTAZIONE} \curvearrowleft \Rightarrow v'(z_1)(B) = v'(z_2)(B) \end{array} \right.$$

CONDIZIONI IN A

$$v'(z_1)(A) = 0 \Rightarrow A_1 = 0$$

$$v(z_1)(A) = 0 \Rightarrow A_2 = 0$$

CONDIZIONI IN B

$$v'(z_1)(B) = v'(z_2)(B)$$

$$\frac{1}{EI} [-4qb(b^2) + 16qb^2(b)] = \frac{1}{EI} (0) + B_1 \Rightarrow B_1 = \frac{12qb^3}{EI}$$

$$v(z_1)(B) = v(z_2)(B)$$

$$\frac{1}{EI} \left[-\frac{4}{3}qb(b^3) + 8qb^2(b^2) \right] = B_2 \Rightarrow B_2 = \frac{20qb^4}{3EI}$$

$$v'(z_1) = \frac{1}{EI} (16qb^2 z_1 - 4qbz_1^2)$$

$$v(z_1) = \frac{1}{EI} \left(8qb^2 z_1^2 - \frac{4}{3}qbz_1^3 \right)$$

$$v'(z_2) = \frac{1}{EI} \left(\frac{2}{3}qz_2^3 + 8qb^2 z_2 - 4qbz_2^2 + 12qb^3 \right)$$

$$v(z_2) = \frac{1}{EI} \left(\frac{1}{6}qz_2^4 + 4qb^2 z_2^2 - \frac{4}{3}qbz_2^3 + 12qb^3 z_2 + \frac{20qb^4}{3} \right)$$

ROTAZIONE NEL PUNTO C, φ_c

$$\varphi_c = \vartheta'_{(x_2=2b)}$$

$$\varphi_c = \frac{1}{EI} \left[\frac{2}{3}q(8b^3) + 8qb^2(2b) - 4qb(4b^2) + 12qb^3 \right]$$

$$= \frac{1}{EI} \left[\frac{16}{3}qb^3 + \cancel{16qb^3} - \cancel{16qb^3} + 12qb^3 \right]$$

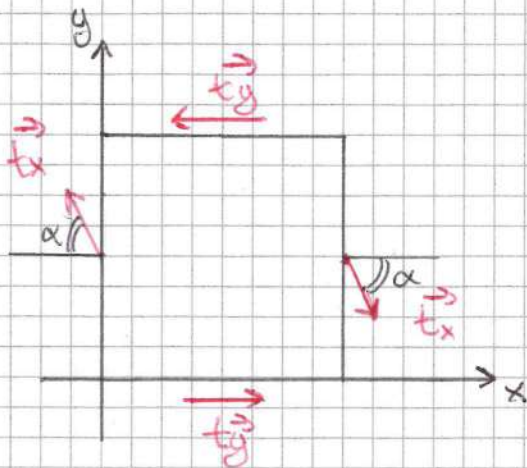
$$= \frac{1}{EI} (52qb^3)$$

SPOSTAMENTO VERTICALE NEL PUNTO B, v_B

$$\vartheta_B = \vartheta'_{(x_2=0)}$$

$$v_B = \frac{1}{EI} \left(\frac{70}{3}qb^4 \right)$$

Esercizio 3 - TRONCO 1 - ESAME 18.07.2023



$$\alpha = -60^\circ$$

$$\sin \alpha = -\frac{\sqrt{3}}{2}$$

$$\cos \alpha = \frac{1}{2}$$

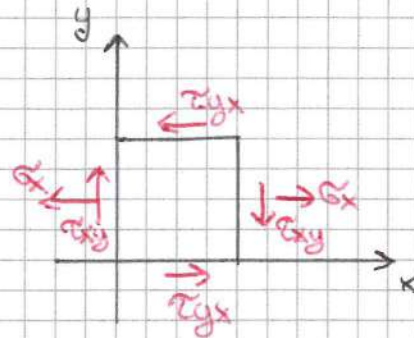
$$|t_x| = 30 \text{ MPa}$$

$$\sigma_x = |t_x| \cos \alpha = 30 \cdot \frac{1}{2} = \underline{15 \text{ MPa}}$$

$$\tau_{xy} = |t_x| \sin \alpha = 30 \left(-\frac{\sqrt{3}}{2}\right) = -15\sqrt{3} \text{ MPa} = \underline{-25,981 \text{ MPa}}$$

$$\tau_{xy} = \tau_{yx} = \underline{-25,981 \text{ MPa}}$$

$$\sigma = \begin{bmatrix} 15 & -25,981 & 0 \\ -25,981 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



CERCHIO DI MOHR

$$P_x(\sigma_x; \tau_{xy}) \Rightarrow \tau_{xy} \uparrow$$

$$P_y(\sigma_y; -\tau_{yx}) \Rightarrow \tau_{yx} \downarrow$$

$$P_x(15; 25,981); P_y(0; -25,981)$$

$$c\left(\frac{\sigma_x + \sigma_y}{2}; 0\right) = (7,5; 0)$$

$$R = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = \sqrt{(7,5)^2 + (25,981)^2}$$

$$= \sqrt{56,25 + 675,012} = \sqrt{731,262} = 27,042 \text{ MPa}$$

$$\tau_{\max} = R = \underline{27,042 \text{ MPa}}$$

$$\sigma_1 = \sigma_c + R = 7,5 + 27,042 = \underline{34,542 \text{ MPa}}$$

$$\sigma_2 = \sigma_c - R = 7,5 - 27,042 = \underline{-19,542 \text{ MPa}}$$

$$\varphi = ?$$

$$\tan 2\varphi = \frac{\tau_{xy}}{\sigma_x - \sigma_c} = \frac{-25,981}{7,5} = -3,464$$

$$\arctan(-3,464) = -73,897 = 2\varphi \Rightarrow \varphi = -36,95^\circ$$

