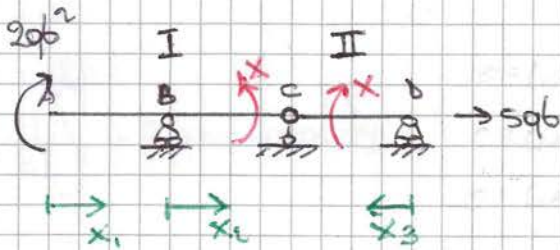


STRUTTURA IPERSTATICA

$$GDL = 3$$

$$GDU = 1(B) + 2(C) + 1(D) = 4$$

$$GDL < GDU$$



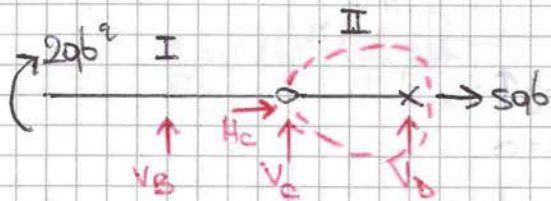
STRUTTURA ISOSTATICA

$$GDL = 3(I) + 3(II) = 6$$

$$GDU = 1(B) + 4(C) + 1(D) = 6$$

$$GDL = GDU$$

S<sub>0</sub> - SISTEMA REALE

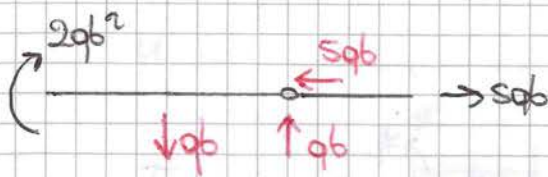


$$\begin{cases} R_x = 0 \\ R_y = 0 \\ \mathcal{M}_{z(O)} = 0 \end{cases} \begin{cases} H_C + Sqb = 0 \Rightarrow H_C = -Sqb \\ V_B + V_C + V_D = 0 \quad V_B = -V_C \\ 2qb^2 + V_B(4b) + V_C(2b) = 0 \quad [*] \end{cases}$$

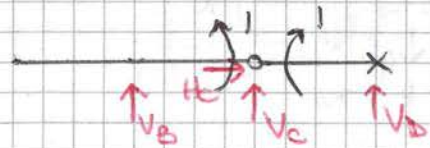
eq. aux

$$\begin{cases} \mathcal{M}_{z(C)}^{II} = 0 \\ \mathcal{M}_{z(C)}^{I} = 0 \end{cases} \begin{cases} V_D(2b) = 0 \Rightarrow V_D = 0 \end{cases}$$

$$[*] \quad \begin{aligned} 2qb^2 - 4bV_C + 2bV_C &= 0 \\ -2bV_C &= -2qb^2 \Rightarrow V_C = qb \\ V_B &= -qb \end{aligned}$$



S<sub>1</sub> - SISTEMA EQUILIBRATO



$$\begin{cases} R_x = 0 \\ R_y = 0 \\ \mathcal{M}_{z(O)} = 0 \end{cases} \begin{cases} H_C = 0 \\ V_B + V_C + V_D = 0 \quad [2] \\ V_B(4b) + V_C(2b) = 0 \quad [3] \end{cases}$$

eq. aux

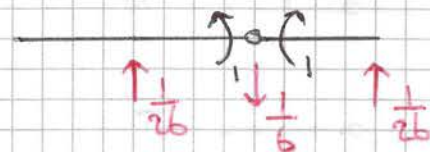
$$\begin{cases} \mathcal{M}_{z(C)}^{II} = 0 \\ \mathcal{M}_{z(C)}^{I} = 0 \end{cases} \begin{cases} V_D(2b) - 1 = 0 \Rightarrow V_D = \frac{1}{2b} \end{cases}$$

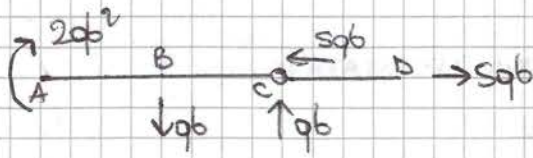
$$[2] \quad V_B + V_C + \frac{1}{2b} = 0 \quad V_B = -V_C - \frac{1}{2b}$$

$$[3] \quad -4bV_B - 2 + 2bV_C = 0 \Rightarrow -2bV_C = 2 - 4bV_B$$

$$V_C = -\frac{1}{b} + 2V_B$$

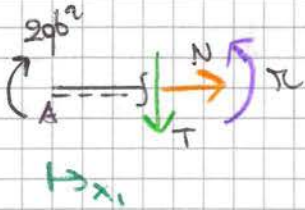
$$[2] \quad V_B = +\frac{1}{b} - \frac{1}{2b} = \frac{1}{2b}$$





A → B

$$0 \leq x_1 \leq 2b$$



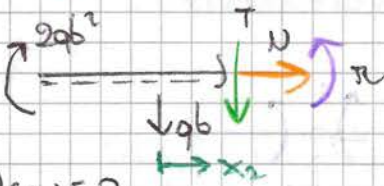
$$N(x_1) = 0$$

$$T(x_1) = 0$$

$$M(x_1) = 2qb^2$$

B → C

$$0 \leq x_2 \leq 2b$$



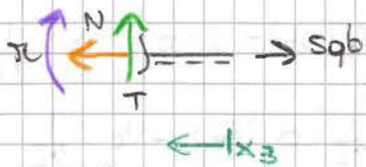
$$N(x_2) = 0$$

$$T(x_2) = -qb$$

$$M(x_2) = -qb x_2 + 2qb^2$$

C → D

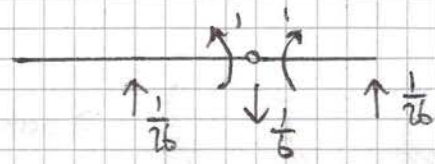
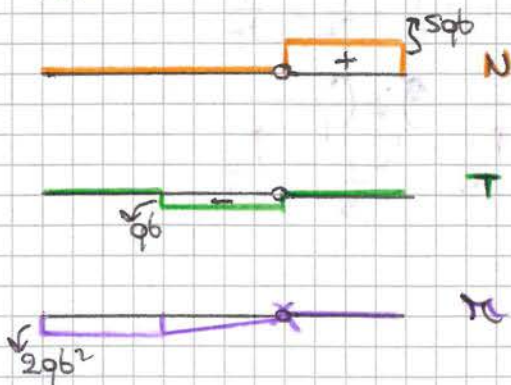
$$0 \leq x_3 \leq 2b$$



$$N(x_3) = sqb$$

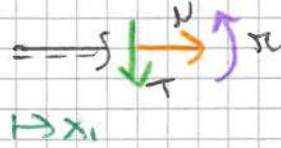
$$T(x_3) = 0$$

$$M(x_3) = 0$$



A → B

$$0 \leq x_1 \leq 2b$$



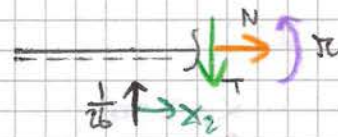
$$N(x_1) = 0$$

$$T(x_1) = 0$$

$$M(x_1) = 0$$

B → C

$$0 \leq x_2 \leq 2b$$



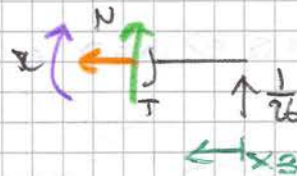
$$N(x_2) = 0$$

$$T(x_2) = \frac{1}{26}$$

$$M(x_2) = \frac{1}{26} x_2$$

C → D

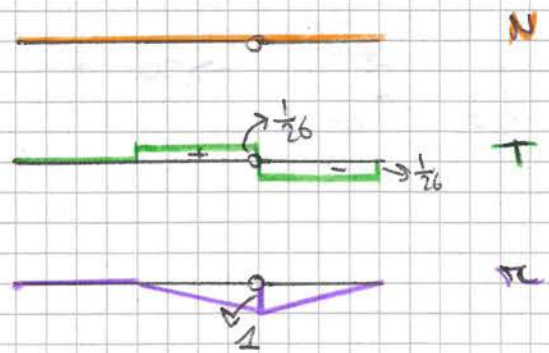
$$0 \leq x_3 \leq 2b$$



$$N(x_3) = 0$$

$$T(x_3) = -\frac{1}{26}$$

$$M(x_3) = \frac{1}{26} x_3$$



P.L.V.

$$\delta U_e = \delta U_i$$

$$\delta U_e = 1 \Delta q_e = 0$$

$$\delta U_i = \int_S N_1 \epsilon_i + \int_S T_1 \delta_1 + \int_S \pi_1 x_i \Rightarrow \delta U_i = \int_S \pi_1 \left( \frac{\pi_0 + \int \pi_1}{EI} \right)$$

A → B

$$\pi_0 = 2qb^2$$

$$\pi_1 = 0$$

$$\pi_1 \cdot \pi_0 = 0$$

$$\pi_1^2 = 0$$

B → C

$$\pi_0 = -qb x_2 + 2qb^2$$

$$\pi_1 = \frac{1}{2b} x_2$$

$$\pi_1 \cdot \pi_0 = -\frac{1}{2} q x_2^2 + qb x_2$$

$$\pi_1^2 = \frac{1}{4b^2} x_2^2$$

C → D

$$\pi_0 = 0$$

$$\pi_1 = \frac{1}{2b} x_3$$

$$\pi_1 \cdot \pi_0 = 0$$

$$\pi_1^2 = \frac{1}{4b^2} x_3^2$$

$$\delta U_i = \frac{1}{EI} \int_0^{2b} -\frac{1}{2} q x_2 + qb x_2 dx_2 + \int_0^{2b} \frac{X}{EI} \left( \frac{1}{4b^2} x_2^2 \right) dx_2 + \int_0^{2b} \frac{X}{EI} \left( \frac{1}{4b^2} x_3^2 \right) dx_3$$

$$= \frac{1}{EI} \left[ -\frac{1}{2} q \frac{x_2^3}{3} + qb \frac{x_2^2}{2} \right]_0^{2b} + \frac{X}{EI} \left[ \frac{1}{4b^2} \frac{x_2^3}{3} \right]_0^{2b} + \left[ \frac{X}{EI} \left( \frac{1}{4b^2} \frac{x_3^3}{3} \right) \right]_0^{2b}$$

$$= \frac{1}{EI} \left[ -\frac{1}{2} q \frac{(2b)^3}{3} + qb \frac{(2b)^2}{2} \right] + \frac{X}{EI} \left[ \frac{1}{3 \cdot 4b^2} (2b)^3 \right] + \frac{X}{EI} \left[ \frac{1}{4b^2} \frac{(2b)^3}{3} \right]$$

$$= \frac{1}{EI} \left[ -\frac{4}{3} qb^3 + 2qb^3 \right] + \frac{X}{EI} \left[ \frac{2b}{3} \right] + \frac{X}{EI} \left[ \frac{2b}{3} \right]$$

$$\delta U_i = \frac{1}{EI} \left[ \frac{2}{3} qb^3 + \frac{4b}{3} X \right] \Rightarrow \delta U_i = 0 \quad \frac{1}{EI} \left[ \frac{2}{3} qb^3 + \frac{4b}{3} X \right] = 0$$

$$\frac{4b}{3} X = -\frac{2}{3} qb^3 \quad X = -\frac{1}{2} qb^2$$

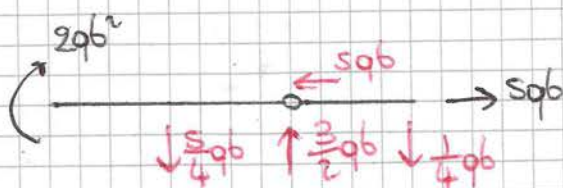
REAZIONI VINCOLARI

$$H_c = H_{c0} + X H_{c1} \Rightarrow H_c = -5qb$$

$$V_c = V_{c0} + X V_{c1} \Rightarrow V_c = qb + \left( -\frac{1}{2} qb^2 \right) \left( -\frac{1}{b} \right) = qb + \frac{1}{2} qb = \frac{3}{2} qb$$

$$V_B = V_{B0} + X V_{B1} \Rightarrow V_B = -qb + \left( -\frac{1}{2} qb^2 \right) \left( \frac{1}{2b} \right) = -qb - \frac{1}{4} qb = -\frac{5}{4} qb$$

$$V_D = V_{D0} + X V_{D1} \Rightarrow V_D = 0 + \left( -\frac{1}{2} qb^2 \right) \left( \frac{1}{2b} \right) = -\frac{1}{4} qb$$



## AZIONI INTERNE

A → B

$$N(x_1) = N_0(x_1) + \sum N_1(x_1)$$

$$N(x_1) = 0$$

$$T(x_1) = T_0(x_1) + \sum T_1(x_1)$$

$$T(x_1) = 0$$

$$\pi(x_1) = \pi_0(x_1) + \sum \pi_1(x_1)$$

$$\pi(x_1) = 2qb^2$$

B → C

$$N(x_2) = N_0(x_2) + \sum N_1(x_2)$$

$$N(x_2) = 0$$

$$T(x_2) = T_0(x_2) + \sum T_1(x_2)$$

$$T(x_2) = -qb + \left(-\frac{1}{2}qb^2\right)\left(\frac{1}{2b}\right)$$

$$T(x_2) = -qb - \frac{1}{4}qb = -\frac{5}{4}qb$$

$$\pi(x_2) = \pi_0(x_2) + \sum \pi_1(x_2)$$

$$\pi(x_2) = -qb x_2 + 2qb^2 + \left(-\frac{1}{2}qb^2\right)\left(\frac{1}{2b} x_2\right)$$

$$= -qb x_2 + 2qb^2 - \frac{1}{4}qb x_2$$

$$= -\frac{5}{4}qb x_2 + 2qb^2$$

C → D

$$N(x_3) = N_0(x_3) + \sum N_1(x_3)$$

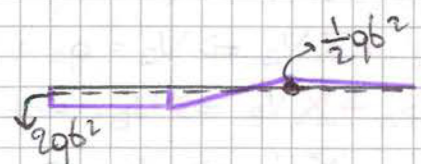
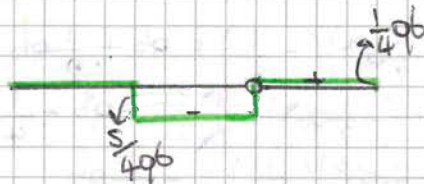
$$N(x_3) = 5qb$$

$$T(x_3) = T_0(x_3) + \sum T_1(x_3)$$

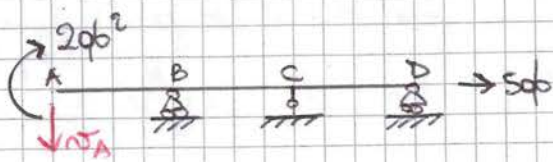
$$T(x_3) = 0 - \frac{1}{2}qb^2\left(-\frac{1}{2b}\right) = +\frac{1}{4}qb$$

$$\pi(x_3) = \pi_0(x_3) + \sum \pi_1(x_3)$$

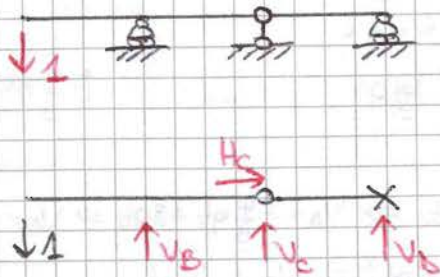
$$\pi(x_3) = 0 - \frac{1}{2}qb^2\left(\frac{1}{2b} x_3\right) = -\frac{1}{4}qb x_3$$



° CALCOLO COMPONENTE DI SPACAMENTO DA



S<sub>2</sub>



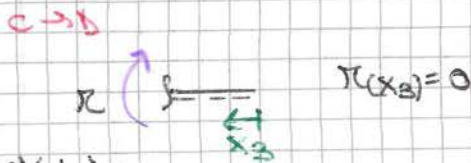
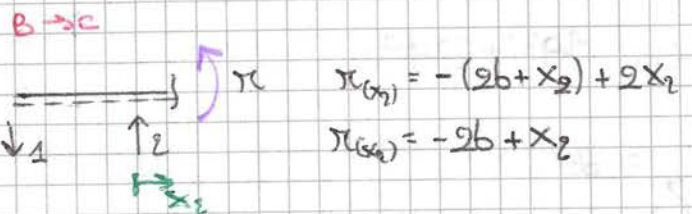
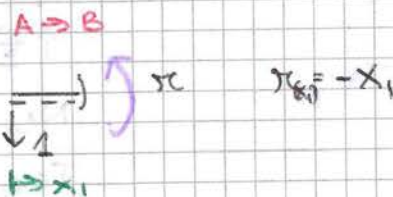
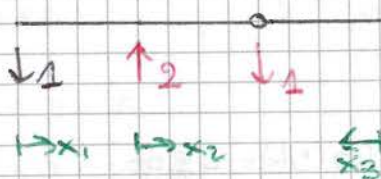
$$\begin{cases} R_x = 0 \\ R_y = 0 \\ \mathcal{M}_{z(0)} = 0 \end{cases} \begin{cases} H_c = 0 \\ V_B + V_C + 1 = 0 \quad [2] \\ V_C(2b) + V_B(4b) - 1(6b) = 0 \quad [3] \end{cases}$$

eq aux

$$\begin{cases} \text{II} \\ \mathcal{M}_{z(c)} = 0 \end{cases} \begin{cases} V_D(2b) = 0 \Rightarrow V_D = 0 \end{cases}$$

[2]  $V_B = 1 - V_C \Rightarrow V_B = 1 + 1 = 2$

[3]  $2bV_C + 4b - 4bV_C - 6b = 0$   
 $-2bV_C - 2b = 0 \Rightarrow V_C = -1$



P.L.V

$\delta V_e = \delta V_i$

$\delta V_e = 1 \cdot \delta v_A = 1 \delta A$

$\delta V_i = \int_S \mathcal{M}_e X$

$= \int_0^{2b} -X_1 \left( \frac{2qb^2}{EI} \right) dx_1 + \int_0^{2b} (X_2 - 2b) \left( -\frac{5}{4} X_2 qb + 2qb^2 \right) \left( \frac{1}{EI} \right) dx_2$

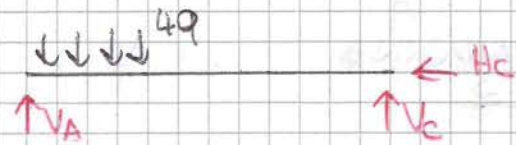
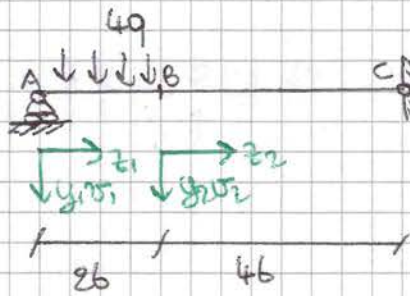
$= \left[ -\frac{X_1^2}{2} \left( \frac{2qb^2}{EI} \right) \right]_0^{2b} + \int_0^{2b} \left( -\frac{5}{4} X_2^2 qb + 2qb^2 X_2 + \frac{5}{2} X_2 qb^2 - 4qb^3 \right) \frac{1}{EI} dx_2$

$= \left[ -4b^2 \left( \frac{qb^2}{EI} \right) \right] + \left[ -\frac{5}{4} \frac{X_2^3}{3} qb + \frac{X_2^2}{2} (2qb^2) + \frac{X_2^2}{2} \left( \frac{5qb^2}{2} \right) - 4qb^3 X_2 \right]_0^{2b} \left( \frac{1}{EI} \right)$

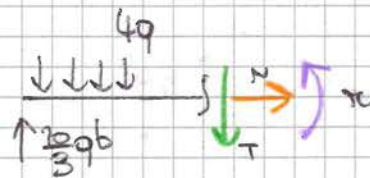
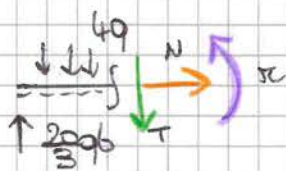
$= -\frac{4qb^4}{EI} + \left( -\frac{5}{4} \left( \frac{8b^3}{3} \right) (qb) + \frac{4b^2}{2} (2qb^2) + \frac{4b^2}{2} \left( \frac{5qb^2}{2} \right) - 8qb^4 \right) \left( \frac{1}{EI} \right)$

$= -\frac{4qb^4}{EI} + (4qb^4 - \frac{10}{3} qb^4 + 5qb^4 - 8qb^4) \left( \frac{1}{EI} \right) = -\frac{19}{3} \frac{qb^4}{EI}$

TRACCIA 1 - ESERCIZIO 2 - ESATTE 27/06/2013



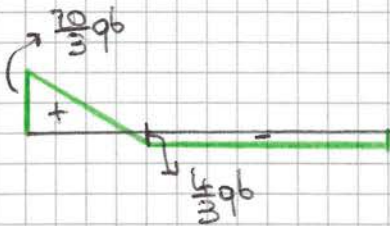
$$\begin{cases} R_x = 0 \\ R_y = 0 \\ \pi_{z(A)} = 0 \end{cases} \begin{cases} H_c = 0 \\ V_A + V_c - 4q(2b) = 0 \Rightarrow V_A = -V_c + 8qb \Rightarrow V_A = -\frac{4}{3}qb + 8qb \Rightarrow V_A = \frac{20}{3}qb \\ 4q(2b)(b) - V_c(6b) = 0 \Rightarrow V_c(6b) = 8qb^2 \Rightarrow V_c = \frac{4}{3}qb \end{cases}$$



$$N(z_1) = 0$$

$$T(z_1) = \frac{20}{3}qb - 4qz_1$$

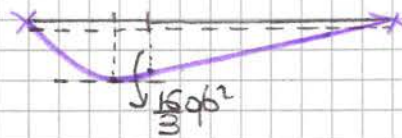
$$\begin{aligned} \pi(z_1) &= -4q \frac{z_1^2}{2} + \frac{20}{3}qb z_1 \\ &= -2qz_1^2 + \frac{20}{3}qb z_1 \end{aligned}$$



$$N(z_2) = 0$$

$$T(z_2) = \frac{20}{3}qb - 4q(2b) = -\frac{4}{3}qb$$

$$\begin{aligned} \pi(z_2) &= -4q(2b)(b+z_2) + \frac{20}{3}qb(2b+z_2) \\ \pi(z_2) &= -8qb^2 - 8qbz_2 + \frac{40}{3}qb^2 + \frac{20}{3}qbz_2 \\ &= -8qb^2 + \frac{40}{3}qb^2 - \frac{4}{3}qbz_2 \\ &= \frac{16}{3}qb^2 - \frac{4}{3}qbz_2 \end{aligned}$$



$$\pi'(z_1) = -4qz_1 + \frac{20}{3}qb$$

$$\pi'(z_1) = 0 \Rightarrow z_1 = \frac{20}{3}b \cdot \frac{1}{4} = \frac{5}{3}b$$

per  $z_1 = \frac{5}{3}b$  punto di minimo

Eq. LINEA ELASTICA

A → B

$$\sigma''(z_1) = -\frac{\pi}{EI} \Rightarrow \sigma''(z_1) = \frac{1}{EI} (2qz_1^2 - \frac{20}{3}qbz_1)$$

$$\sigma'(z_1) = \frac{1}{EI} (\frac{2}{3}qz_1^3 - \frac{10}{3}qbz_1^2) + A_1 \Rightarrow \sigma'(z_1) = \frac{1}{EI} (\frac{2}{3}qz_1^3 - \frac{10}{3}qbz_1^2) + A_1$$

$$\sigma(z_1) = \frac{1}{EI} (\frac{2}{3}q \frac{z_1^4}{4} - \frac{10}{3}qb \frac{z_1^3}{3}) + A_1 z_1 + A_2 \Rightarrow \sigma(z_1) = \frac{1}{EI} (\frac{1}{6}qz_1^4 - \frac{10}{9}qbz_1^3) + A_1 z_1 + A_2$$

B → C

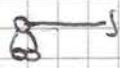
$$v''''(z_2) = -\frac{q}{EI} \Rightarrow v''(z_2) = \frac{1}{EI} \left( -\frac{16}{3}qb^2 + \frac{4}{3}qbz_2 \right)$$

$$v'(z_2) = \frac{1}{EI} \left( -\frac{16}{3}qb^2z_2 + \frac{2}{3}qbz_2^2 \right) + B_1 \Rightarrow v'(z_2) = \frac{1}{EI} \left( -\frac{16}{3}qb^2z_2 + \frac{2}{3}qbz_2^2 \right) + B_1$$

$$v(z_2) = \frac{1}{EI} \left( -\frac{8}{3}qb^2z_2^2 + \frac{2}{9}qbz_2^3 \right) + B_1z_2 + B_2 \Rightarrow v(z_2) = \frac{1}{EI} \left( -\frac{8}{3}qb^2z_2^2 + \frac{2}{9}qbz_2^3 \right) + B_1z_2 + B_2$$


COSTANTI  $A_1; A_2; B_1; B_2$

IN A

 **INFERISCE**  $\left\{ \begin{array}{l} \text{SPOSTAMENTO} \updownarrow \Rightarrow v(z_1=0) = 0 \end{array} \right.$


CARRELLI

IN B

 **INFINE**  $\left\{ \begin{array}{l} \text{UGUALE ROTAZIONE} \curvearrowright v'(z_1=2b) = v'(z_2=0) \\ \text{UGUALE SPOSTAMENTO} \updownarrow v(z_1=2b) = v(z_2=0) \end{array} \right.$

SALESTURA

IN C

 **INFERISCE**  $\left\{ \begin{array}{l} \text{SPOSTAMENTO} \updownarrow v(z_2=4b) = 0 \end{array} \right.$

CERNIERA

CONDIZIONE IN A

$v(z_1=0) = 0 \Rightarrow A_2 = 0$

CONDIZIONI IN B

$v'(z_1=2b) = v'(z_2=0)$

$$\frac{1}{EI} \left( \frac{2}{3}q \cdot 8b^3 - \frac{10}{3}qb \cdot 4b^2 \right) + A_1 = B_1 \Rightarrow B_1 = \frac{1}{EI} \left( \frac{16}{3}qb^3 - \frac{40}{3}qb^3 \right) + A_1 \Rightarrow B_1 = \frac{1}{EI} \left( -\frac{24}{3}qb^3 \right) + A_1$$

$$B_1 = -\frac{1}{EI} \cdot 8qb^3 + A_1$$

$v(z_1=2b) = v(z_2=0)$

$$\frac{1}{EI} \left( \frac{1}{3}q \cdot 16b^4 - \frac{10}{9}qb \cdot 8b^3 \right) + A_1(2b) = B_2 \Rightarrow B_2 = \frac{1}{EI} \left( \frac{8}{3}qb^4 - \frac{80}{9}qb^4 \right) + 2b(A_1)$$

$$B_2 = \frac{1}{EI} \left( -\frac{56}{9}qb^4 \right) + 2b(A_1)$$

CONDIZIONE IN C

$v(z_2=4b) = 0$

$$\frac{1}{EI} \left( -\frac{8}{3}qb^2 \cdot 16b^2 + \frac{2}{9}qb \cdot 64b^3 \right) + B_1(4b) + B_2 = 0$$

$$\frac{1}{EI} \left( -\frac{128}{3}qb^4 + \frac{128}{9}qb^4 \right) - \frac{32qb^4}{EI} + 4b(A_1) - \frac{56qb^4}{9EI} + 2b(A_1) = 0$$

$$\frac{1}{EI} \left( -\frac{256}{9}qb^4 - 32qb^4 - \frac{56}{9}qb^4 \right) + 6bA_1 = 0 \Rightarrow 6bA_1 = \frac{600}{9} \frac{qb^4}{EI} \Rightarrow A_1 = \frac{100}{9} \frac{qb^3}{EI}$$

$$A_1 = \frac{100}{9} \frac{qb^3}{EI} ; A_2 = 0 ; B_1 = \frac{qb^3}{EI} (-8 + \frac{100}{9}) = \frac{28}{9} \frac{qb^3}{EI} ; B_2 = \frac{qb^4}{EI} (-\frac{56}{9} + \frac{200}{9}) = + \frac{16}{9} \frac{qb^4}{EI}$$

$$\underline{v'(z_1)} = \frac{1}{EI} \left( \frac{2}{3} qz_1^3 - \frac{10}{3} qbz_1^2 \right) + \frac{100}{9} \frac{qb^4}{EI} ; \underline{v'(z_2)} = \frac{1}{EI} \left( -\frac{16}{3} qb^2z_2 + \frac{2}{3} qbz_2^2 + \frac{28}{9} qb^3 \right)$$

$$\underline{v(z_1)} = \frac{1}{EI} \left( \frac{1}{6} qz_1^4 - \frac{10}{9} qbz_1^3 + \frac{100}{9} qb^3z_1 \right) ; \underline{v(z_2)} = \frac{1}{EI} \left( -\frac{8}{3} qb^2z_2^2 + \frac{2}{9} qbz_2^3 + \frac{28}{9} qb^3z_2 + 16qb^4 \right)$$

• ROTAZIONE DEL PUNTO C ;  $\varphi_c$

$$\varphi_c = v'(z_2 = 4b)$$

$$v'(z_2 = 4b) = \frac{1}{EI} \left( -\frac{16}{3} qb^2 \cdot 4b + \frac{2}{3} qb (4b)^2 + \frac{28}{9} qb^3 \right)$$

$$= \frac{1}{EI} \left( -\frac{64}{3} qb^3 + \frac{32}{3} qb^3 + \frac{28}{9} qb^3 \right)$$

$$= \frac{1}{EI} \left( -\frac{32}{3} qb^3 + \frac{28}{9} qb^3 \right)$$

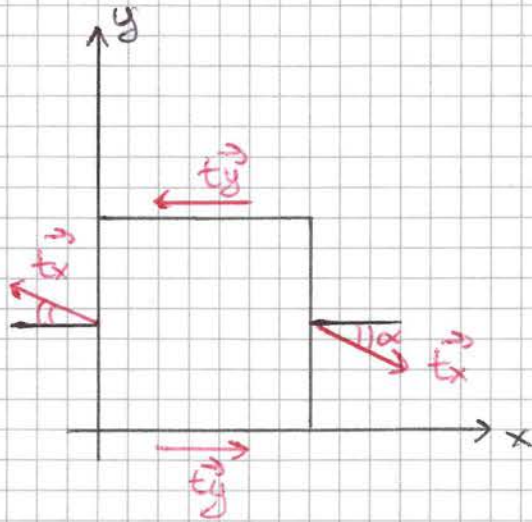
$$\varphi_c = \frac{1}{EI} \left( -\frac{68}{9} qb^3 \right)$$

• SPOSTAMENTO VERTICALE DEL PUNTO B,  $v_B$

$$v_B = v(z_2 = 0)$$

$$v(z_2 = 0) = 16 \frac{qb^4}{EI}$$

ESERCIZIO 3 - TRACCIA 1 - ESATRE 27/06/2023



$$\alpha = -30^\circ$$

$$\sin \alpha = -\frac{1}{2}$$

$$\cos \alpha = \frac{\sqrt{3}}{2}$$

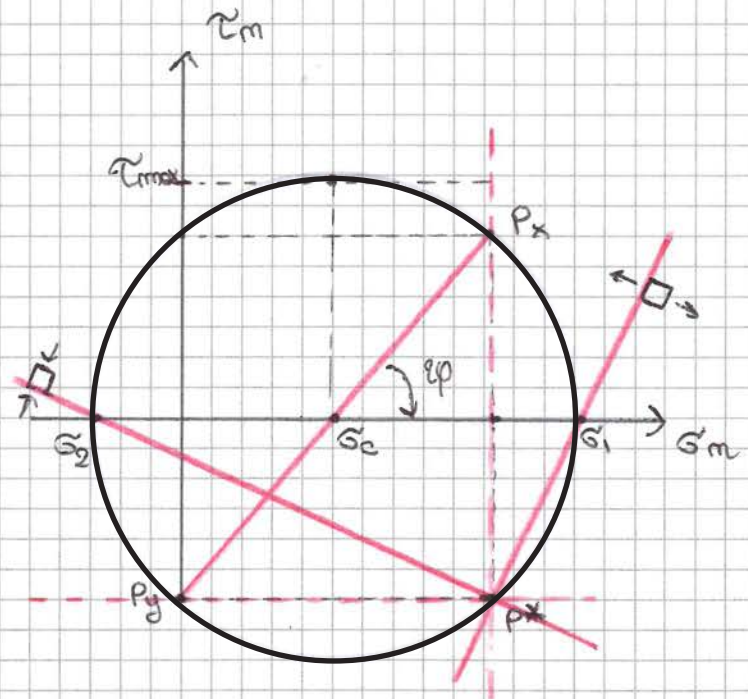
$$|\tau_x| = 60 \text{ MPa}$$

$$\sigma_x = |\tau_x| \cos \alpha = 60 \cdot \frac{\sqrt{3}}{2} = 30\sqrt{3} \text{ MPa} = 51,961 \text{ MPa}$$

$$\tau_{xy} = |\tau_x| \sin \alpha = 60 \left(-\frac{1}{2}\right) = -30 \text{ MPa}$$

$$\tau_{yx} = \tau_{xy} = -30 \text{ MPa}$$

$$\underline{\underline{\sigma}} = \begin{bmatrix} 51,961 & -30 & 0 \\ -30 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



CERCHIO DI MOHR

$$P_x (\sigma_x ; \tau_{xy}) \Rightarrow \tau_{xy} \downarrow$$

$$P_y (\sigma_y ; -\tau_{yx}) \Rightarrow \tau_{yx} \uparrow$$

$$P_x = (51,961 ; 30) ; P_y = (0 ; -30)$$

$$C \left( \frac{\sigma_x + \sigma_y}{2} ; 0 \right) = (25,980 ; 0)$$

$$R = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = \sqrt{(25,980)^2 + (30)^2}$$

$$= \sqrt{674,960 + 900} = \sqrt{1574,96} = 39,685$$

$$\tau_{max} = R = 39,685 \text{ MPa}$$

$$\sigma_1 = \sigma_c + R = 25,980 + 39,685 = 65,665 \text{ MPa}$$

$$\sigma_2 = \sigma_c - R = 25,980 - 39,685 = -13,705$$

$$\varphi = ?$$

$$\tan 2\varphi = \frac{\tau_{xy}}{\sigma_x - \sigma_c} = \frac{-30}{25,981} = -1,154$$

$$\arctan(-1,154) = -49,089 = 2\varphi \Rightarrow \varphi = -24,544^\circ$$