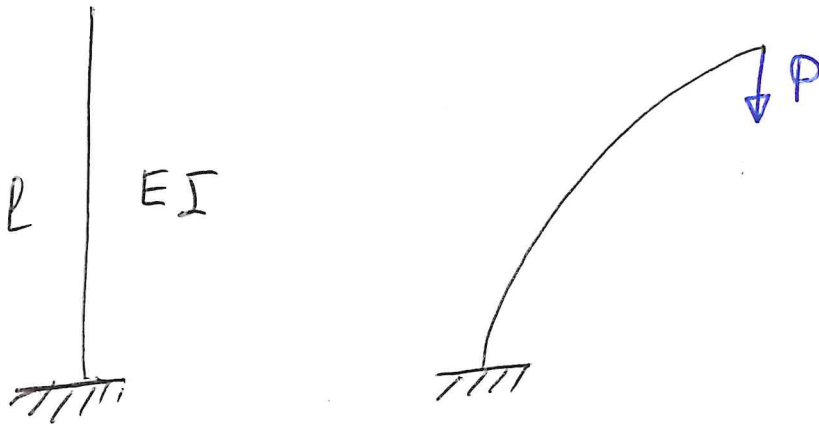


Nonlinear analysis

-1-

Nothing is small



$$P_c = \frac{\pi^2 EI}{4l^2}$$

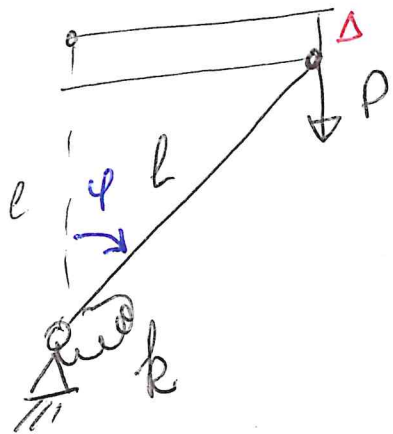
Linearized theory gives a value of critical force and a mode of deformation.

Nonlinear theory should give us also the non-trivial solution.

real

"real beams"

Reminder



Total potential energy

$$\Pi = U - V$$

Elastic energy $U = \frac{1}{2} k \phi^2$

Work of P is given by $V = P \Delta$

$$\Delta = l - l \cos \phi$$

So Π became

$$\Pi = \frac{1}{2} k \phi^2 - P l (1 - \cos \phi)$$

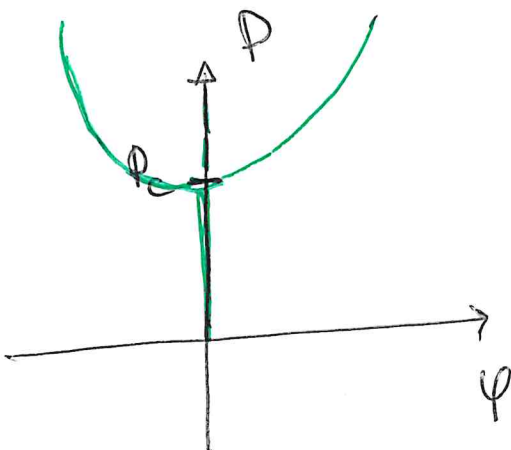
Equilibrium : $\frac{d\Pi}{d\phi} = 0$ $k\phi - Pl \sin \phi = 0$

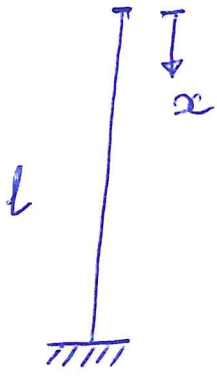
Two solutions : 1. Trivial $\phi = 0$

2. Non-trivial

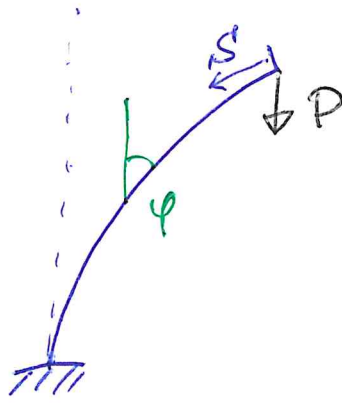
$$P = \frac{k}{l} \frac{\phi}{\sin \phi}$$

$$P_c = \frac{k}{l}$$





initial



current state

s - arc-length

0 ≤ s ≤ l

Angle φ = φ(s)

Curvature κ = φ'(s)

Constitutive equation $M \sim \kappa$

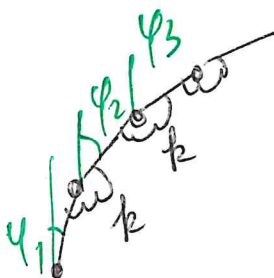
Elastic energy
$$U = \frac{1}{2} \int_0^l EI \kappa^2 ds$$

strain (deformation) energy density

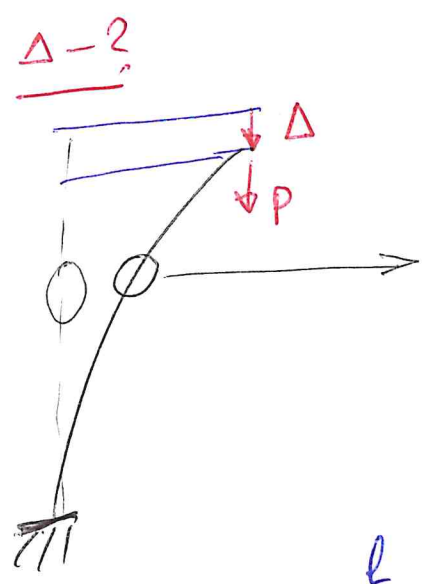
$\frac{1}{2} EI \kappa^2$

Discrete analog

$$U = \sum_{i=1}^N \frac{1}{2} k (\psi_{i+1} - \psi_i)^2$$



V - ? Former case $V = P\Delta$



$$d\Delta(s) = ds - ds \cos \varphi(s)$$

$$\Delta = l - \int_0^l \cos \varphi(s) ds$$

$$V = P \int_0^l [1 - \cos \varphi(s)] ds$$

As a result, we get Π in the form

$$\Pi = \frac{1}{2} \int_0^l EI \kappa^2 ds - P \int_0^l [1 - \cos \varphi(s)] ds$$

$$\Pi = \int_0^l \left[\frac{1}{2} EI \varphi'(s)^2 - P (1 - \cos \varphi(s)) \right] ds$$

Equilibrium equation

$\delta \Pi = 0$ /instead of $\frac{d\Pi}{d\varphi} = 0$

$$\delta \Pi = \int_0^l [EI \varphi'(s) \delta \varphi'(s) - P \sin \varphi(s) \delta \varphi(s)] ds$$

Integrating by parts we get

$$\delta \Pi = \int_0^l [-EI \varphi''(s) \delta \varphi(s) - P \sin \varphi(s) \delta \varphi(s)] ds + EI \varphi'(s) \delta \varphi(s) \Big|_0^l$$

Boundary conditions :

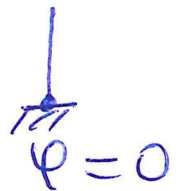
\Rightarrow Equilibrium equation

$-EI \varphi''(s) - P \sin \varphi(s) = 0$

+ natural boundary condition

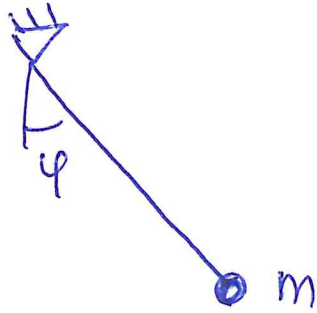
$EI \varphi'(l) = 0$

+ kinematic (essential) BC : $\varphi(0) = 0$



$\Rightarrow \delta \varphi(0) = 0$

Note:



Pendulum has
the same equation!

$$\varphi = \varphi(t)$$

$$\underline{EI\varphi'' + P\sin\varphi = 0}$$

$$\varphi'' + \beta^2 \sin\varphi = 0$$

$$\beta^2 = \frac{P}{EI}$$

First observations: two solutions

1. trivial $\varphi = 0$

2. non-trivial $\varphi \neq 0$?

$$\varphi'' + \beta^2 \sin\varphi = 0 \quad | \times \varphi'$$

$$\varphi''\varphi' + \beta^2 \sin\varphi \varphi' = 0$$

$$\left(\frac{1}{2}\varphi'^2\right)' - \beta^2 (\cos\varphi)' = 0$$

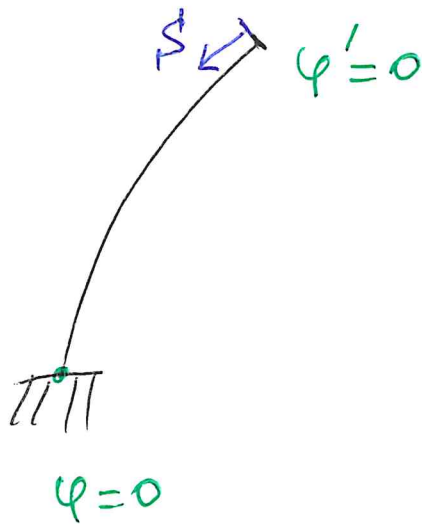
$$\left[\frac{1}{2}\varphi'^2 - \beta^2 \cos\varphi\right]' = 0$$

\Rightarrow

$$\frac{1}{2} \psi'^2 - \beta^2 \cos \psi = C, \quad \underline{C = \text{const}}$$

unknown.

first integral of eq. equations

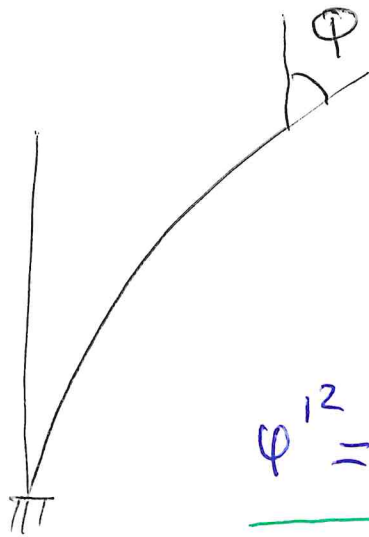


s=0 at the end

$$\frac{1}{2} \underbrace{\psi'(0)^2}_0 - \beta^2 \cos \psi(0) = C$$

$$C = -\beta^2 \cos \psi(0)$$

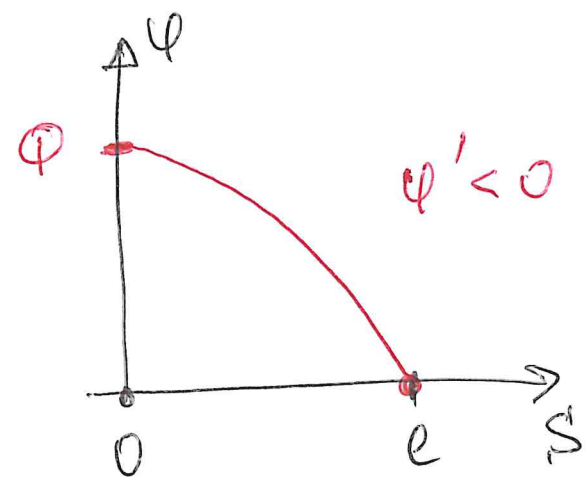
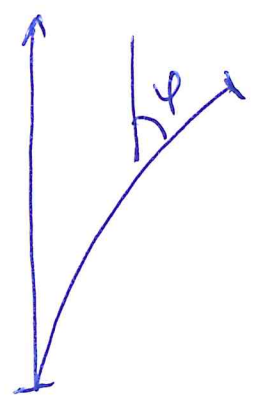
$$\underline{\underline{\Phi = \psi(0)}}$$



$$\frac{1}{2} \psi'^2 - \beta^2 \cos \psi = -\beta^2 \cos \Phi$$

$$\underline{\underline{\psi'^2 = \beta^2 [\cos \psi - \cos \Phi]}}$$

$$\psi' = \underline{\pm} \beta \sqrt{\cos \psi - \cos \Phi}$$



$$\Rightarrow \varphi' = -\beta \sqrt{\cos \varphi - \cos \varphi}$$

$$\frac{d\varphi}{ds} = -\beta \sqrt{\cos \varphi - \cos \varphi}$$

$$-\frac{d\varphi}{\beta \sqrt{\cos \varphi - \cos \varphi}} = ds$$

$$-\int_{\varphi}^{\varphi(s)} \frac{d\varphi}{\beta \sqrt{\cos \varphi - \cos \varphi}} = s$$

$$\cos \varphi = \cos^2 \frac{\varphi}{2} - \sin^2 \frac{\varphi}{2} = 1 - 2 \sin^2 \frac{\varphi}{2} \quad -9-$$

$$\cos \varphi = 1 - 2 \sin^2 \frac{\varphi}{2}$$

$$\cos \varphi - \cos \varphi = 2 \sin^2 \frac{\varphi}{2} - 2 \sin^2 \frac{\varphi}{2}$$

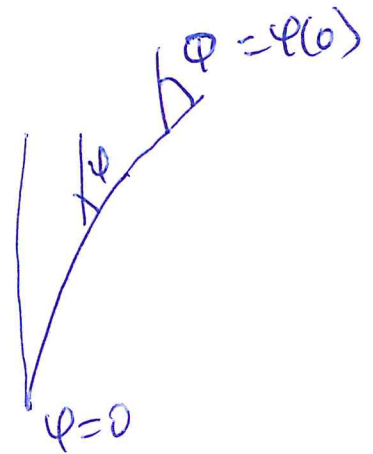
$$-\int_{\varphi}^{\varphi(s)} \frac{d\varphi}{\sqrt{2} \beta \sqrt{\sin^2 \frac{\varphi}{2} - \sin^2 \frac{\varphi}{2}}} = s$$

$$\underline{\varphi(s) \leq \varphi}$$

$$\int_{\varphi(s)}^{\varphi} \frac{d\varphi}{\beta \sqrt{2} \sqrt{\sin^2 \frac{\varphi}{2} - \sin^2 \frac{\varphi}{2}}} = s$$

BC: $\varphi(l) = 0$: at $s=l$ $\varphi=0$

$$\int_0^{\varphi} \frac{d\varphi}{\beta \sqrt{2} \sqrt{\sin^2 \frac{\varphi}{2} - \sin^2 \frac{\varphi}{2}}} = l$$



$$p = \sin \frac{\varphi}{2}, \quad p^2 = \sin^2 \frac{\varphi}{2}$$

$$\eta : \quad \underline{\sin \frac{\varphi}{2} = p \sin \eta}$$

φ varies from 0 until φ

$\sin \eta$ varies from 0 until 1

η varies from 0 until $\frac{\pi}{2}$

$$d\varphi \rightarrow d\eta$$

$$d \sin \frac{\varphi}{2} = \frac{1}{2} \cos \frac{\varphi}{2} d\varphi$$

$$d \sin \frac{\varphi}{2} = d(p \sin \eta) = p \cos \eta d\eta$$

$$\underline{\frac{1}{2} \cos \frac{\varphi}{2} d\varphi = p \cos \eta d\eta}$$

$$\underline{d\varphi = \frac{p \cos \eta d\eta}{\cos \frac{\varphi}{2}} = \frac{2p \cos \eta d\eta}{\sqrt{1 - \sin^2 \frac{\varphi}{2}}}}$$

$$= \underline{\frac{2p \cos \eta d\eta}{\sqrt{1 - p^2 \sin^2 \eta}}}$$

$$l = \frac{1}{2\beta} \int_0^{\pi/2} \frac{2p \cos \eta}{\sqrt{1-p^2 \sin^2 \eta}} d\eta = \frac{1}{\beta} \frac{1}{\sqrt{1-p^2 \sin^2 \eta}} d\eta$$

$$l = \frac{1}{\beta} \int_0^{\pi/2} \frac{d\eta}{\sqrt{1-p^2 \sin^2 \eta}}$$

$$\beta l = \int_0^{\pi/2} \frac{d\eta}{\sqrt{1-p^2 \sin^2 \eta}} \equiv K(p)$$

$K(p)$ is the elliptic integral of first kind

$$\beta l = K(p)$$

\sim dependence of $P(\beta)$ on $\phi = \max_s \phi$

$$\beta l = K(p)$$

$$\beta^2 = \frac{P}{EI}$$

$$\Phi \rightarrow p \equiv \sin \frac{\Phi}{2}$$

$$P = K^2(p) \frac{EI}{l^2}$$

if $\psi \ll 1$, $\Phi \ll 1$, $\eta \ll 1$

Linear
theory

$$\sin \frac{\psi}{2} = \sin \frac{\Phi}{2} \sin \eta$$

$$\int_0^{\pi/2} \frac{d\eta}{\sqrt{1 - p^2 \sin^2 \eta}} \approx \int_0^{\pi/2} d\eta = \frac{\pi}{2}$$

$$\beta l = \frac{\pi}{2} \Rightarrow$$

$$P_c = \frac{\pi^2}{4} \frac{EI}{l^2}$$

$$P = \frac{4}{\pi^2} P_c K^2(p)$$

$$P \sim \Phi \quad \text{or} \quad P \sim V = \max_S U(S)$$

-13-

