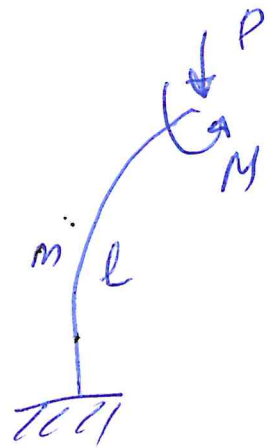
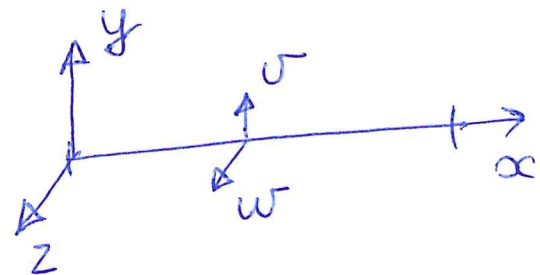


# Nikolai

$$EI_1, EI_2, l, m$$

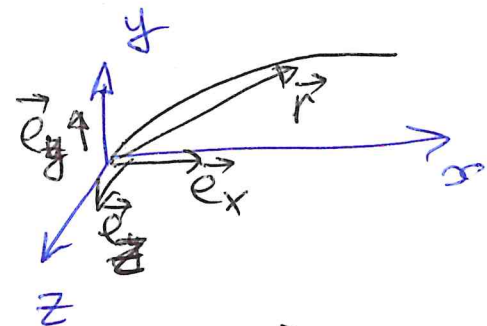


$$\begin{cases} EI_1 v^{IV} + Mw''' + Pv'' = 0 / -m\ddot{v} \\ EI_2 w^{IV} - Mw''' + Pw'' = 0 / -m\ddot{w} \end{cases}$$



1. Il criterio statico:

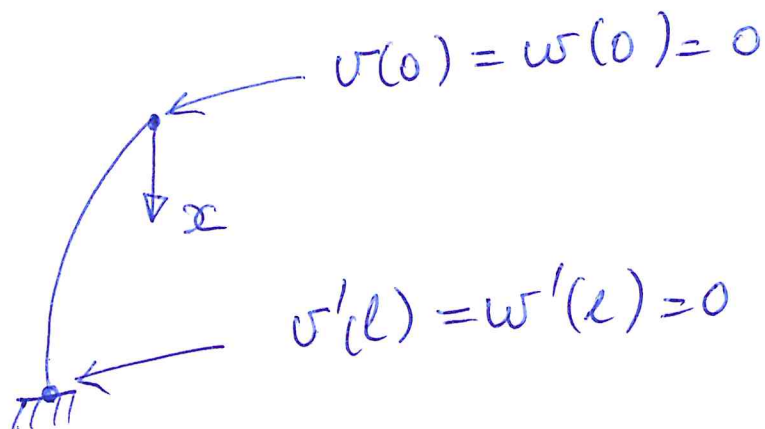
$$\begin{cases} EI_1 v^{IV} + Mw''' + Pv'' = 0 \\ EI_2 w^{IV} - Mw''' + Pw'' = 0 \end{cases}$$



$$\vec{r} = x\vec{e}_x + v\vec{e}_y + w\vec{e}_z$$

invece:

$$\begin{cases} EI_1 v'' + Mw' + Pv = 0 \\ EI_2 w'' - Mw' + Pw = 0 \end{cases}$$



$$v(x) = V e^{\lambda x}, \quad w(x) = W e^{\lambda x}$$

$\Rightarrow$  l'eq. per  $\lambda \dots$

$$v(x) \sim \sin, \cos \dots$$

$$\begin{cases} v = c_1 \cos d_1 x + c_2 \sin d_1 x + c_3 \cos d_2 x + c_4 \sin d_2 x \\ w = c_1 \sin d_1 x - c_2 \cos d_1 x + c_3 \sin d_2 x + c_4 \cos d_2 x \end{cases}$$

1.  $v = c_1 \cos d_1 x, \quad w = c_1 \sin d_1 x$

$$-d_1^2 EI_1 \underline{c_1 \cos d_1 x} + M d_1 \underline{c_1 \sin d_1 x} + P \underline{c_1 \cos d_1 x} = 0$$

$$EI_1 v'' + M w' + P v = 0$$

$$\left( -d_1^2 EI_1 + M d_1 + P \right) c_1 \cos d_1 x = 0$$

$$-d_1^2 EI_1 + M d_1 + P = 0 \quad \leftarrow d_1$$

$$-d_1^2 EI_2 \underline{c_1 \sin d_1 x} - M d_1 \underline{c_1 (-\sin d_1 x)} + P \underline{c_1 \sin d_1 x} = 0$$

$$-d_1^2 EI_2 + M d_1 + P = 0$$

$$\Rightarrow \boxed{EI_1 = EI_2 = EI}$$

$$\Rightarrow \underline{\underline{-d_1^2 EI + M d_1 + P = 0}}$$

$d_1$  e  $d_2$  :

$$\underline{-EI d^2 + M d + P = 0}$$

$$d^2 - \bar{M} d - \bar{P} = 0$$

$$\bar{M} = \frac{M}{EI}$$

$$\left| d_{1,2} = \frac{M \pm \sqrt{M^2 + 4P}}{2} \right|$$

$$\bar{P} = \frac{P}{EI}$$

$C_1, C_2, C_3, C_4 - ?$

$$\left[ \begin{array}{l} v(x) = C_1 \cos d_1 x + C_2 \sin d_1 x + C_3 \cos d_2 x + C_4 \sin d_2 x \\ w(x) = + C_1 \sin d_1 x - C_2 \cos d_1 x + C_3 \sin d_2 x + C_4 \cos d_2 x \end{array} \right]$$

$$v(0) = w(0) = 0$$

$$C_1 + C_3 = 0$$

$$-C_2 - C_4 = 0 \rightarrow C_2 + C_4 = 0$$

$$v'(l) = w'(l) = 0$$

$$\underline{-C_1 d_1 \sin d_1 l + C_2 d_1 \cos d_1 l - C_3 d_2 \sin d_2 l + C_4 \overset{d_2}{\cancel{\cos d_2 l}} = 0}$$

$$\underline{C_1 d_1 \cos d_1 l + C_2 d_1 \sin d_1 l + C_3 d_2 \cos d_2 l + C_4 d_2 \sin d_2 l = 0}$$

$\Rightarrow$  per  $C_1$ ...

$$A c = 0 \quad c = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ -d_1 \sin d_1 l & d_1 \cos d_1 l & -d_2 \sin d_2 l & d_2 \cos d_2 l \\ d_1 \cos d_1 l & d_1 \sin d_1 l & d_2 \cos d_2 l & d_2 \sin d_2 l \end{bmatrix}$$

$$\boxed{\det A = 0}$$

$$\det A = 0 \quad \boxed{d_1^2 + d_2^2 = 2d_1 d_2 \cos(d_1 - d_2)l}$$

$$d_1, d_2: \quad \frac{d^2 - \bar{M}d - \bar{P} = 0}{}$$

$$d_{1,2} = \frac{\bar{M} \pm \sqrt{\bar{M}^2 + 4\bar{P}}}{2}$$

$$\bar{M} = \frac{M}{EI}$$

$$\bar{P} = \frac{P}{EI}$$

$$\frac{d_1 d_2 = -\bar{P}}{}$$

$$\begin{aligned} (x-x_1)(x-x_2) &= x^2 + px + q = 0 \\ &= x^2 + px + q \end{aligned}$$

$$x_1 x_2 = q$$

$$x_1 + x_2 = -p$$

$$\frac{d_1 - d_2 = \sqrt{\bar{M}^2 + 4\bar{P}}}{}$$

$$\frac{d_1^2 + d_2^2 = \bar{M}^2 + 2\bar{P}}{}$$

$$\bar{M}^2 + 2\bar{P} = -2\bar{P} \cos \sqrt{\bar{M}^2 + 4\bar{P}} l$$

$$\Rightarrow \cos \sqrt{\bar{M}^2 + 4\bar{P}} l = - \left( 1 + \frac{\bar{M}^2}{2\bar{P}} \right)$$

$$|\cos| \leq 1 \quad \left| 1 + \frac{\bar{M}^2}{2\bar{P}} \right| > 1$$

$$= 1 \quad \underline{\bar{M} = 0!}$$

$$\Rightarrow \exists \underline{P_c} \quad \underline{M=0} \quad (?)$$

$\Rightarrow$  Il criterio dinamico

$$\begin{cases} EI_1 v^{IV} + M w^{III} + P v'' + m \ddot{v} = 0 \\ EI_2 w^{IV} - M v^{III} + P w'' + m \ddot{w} = 0 \end{cases}$$

le condizioni al contorno

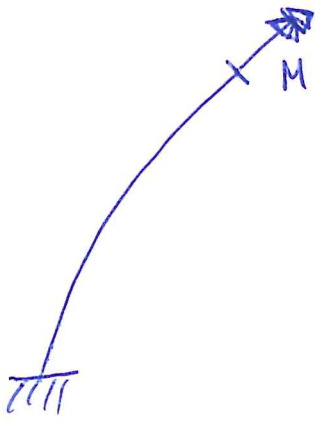
$$x=0, \quad v = w = 0$$

$$v' = w' = 0$$

$$x=l \dots \dots$$

$$\underline{x=l}$$

a)

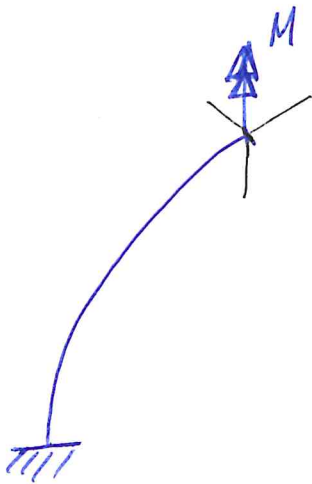


$$\begin{cases} EI_1 v'''' + Pv' - Mw'' = 0 \\ EI_2 w'' + Pw' + Mw'' = 0 \end{cases}$$

$$M_y = M_z = 0 \Rightarrow$$

$$\begin{cases} v'' = 0, w'' = 0 \end{cases}$$

b)



$$\begin{cases} - \\ - \end{cases}$$

$$\begin{cases} EI_1 v'' - Mw' = 0 \\ EI_2 w'' + Mv' = 0 \end{cases}$$

$$v(x,t) = \bar{V}(\bar{x}) l e^{i\omega A t}$$

$$w(x,t) = \bar{W}(\bar{x}) l e^{i\omega A t} \sqrt{\frac{EI_2}{EI_1}}$$

$$A = \sqrt{\frac{EI_1}{m e^4}}, \quad \bar{x} = x/l$$

$$\Rightarrow \begin{cases} V'''' - M_0 W'''' + \beta^2 V'' - \omega^2 V = 0 \\ W'''' + M_0 V'''' + \frac{\beta^2}{k^2} W'' - \frac{\omega^2}{k^2} W = 0 \end{cases}$$

$$M_0 = \frac{m e}{\sqrt{EI_1 EI_2}}, \quad \beta^2 = \frac{P e^2}{EI_1}, \quad k = \sqrt{\frac{I_2}{I_1}} \quad I_2 \geq I_1 \Rightarrow \underline{k \geq 1}$$

$$V(\bar{x}) = \sum_{n=0} V_n \bar{x}^n$$

$$W(\bar{x}) = \sum_{n=0} W_n \bar{x}^n$$

$V_n, W_n - ?$

$$V'(0) = W'(0) = 0$$

$$V(0) = W(0) = 0$$

$\Rightarrow$

$$V_0, V_1 = 0$$

$$W_0, W_1 = 0$$

$V_2, V_3, W_2, W_3$

$$V(\bar{x}) \approx V_2 \bar{x}^2 + V_3 \bar{x}^3 \dots$$

$$W(\bar{x}) \approx W_2 \bar{x}^2 + W_3 \bar{x}^3 \dots$$

$$A \begin{bmatrix} V_2 \\ V_3 \\ W_2 \\ W_3 \end{bmatrix} = 0 \Rightarrow \underline{\underline{\det A = 0}}$$

$$\det A = F(\underbrace{\beta}_P, \underbrace{M_0}_M, k, \omega) = 0$$