



Università degli Studi di Cagliari

Facoltà di Ingegneria e Architettura

Dipartimento di Ingegneria Civile, Ambientale e Architettura

Magistrale Ingegneria Civile 2 anno a.a. 2021/22

Instabilità delle strutture e calcolo a rottura

> **Lezione 16**

Instabilità dell'arco

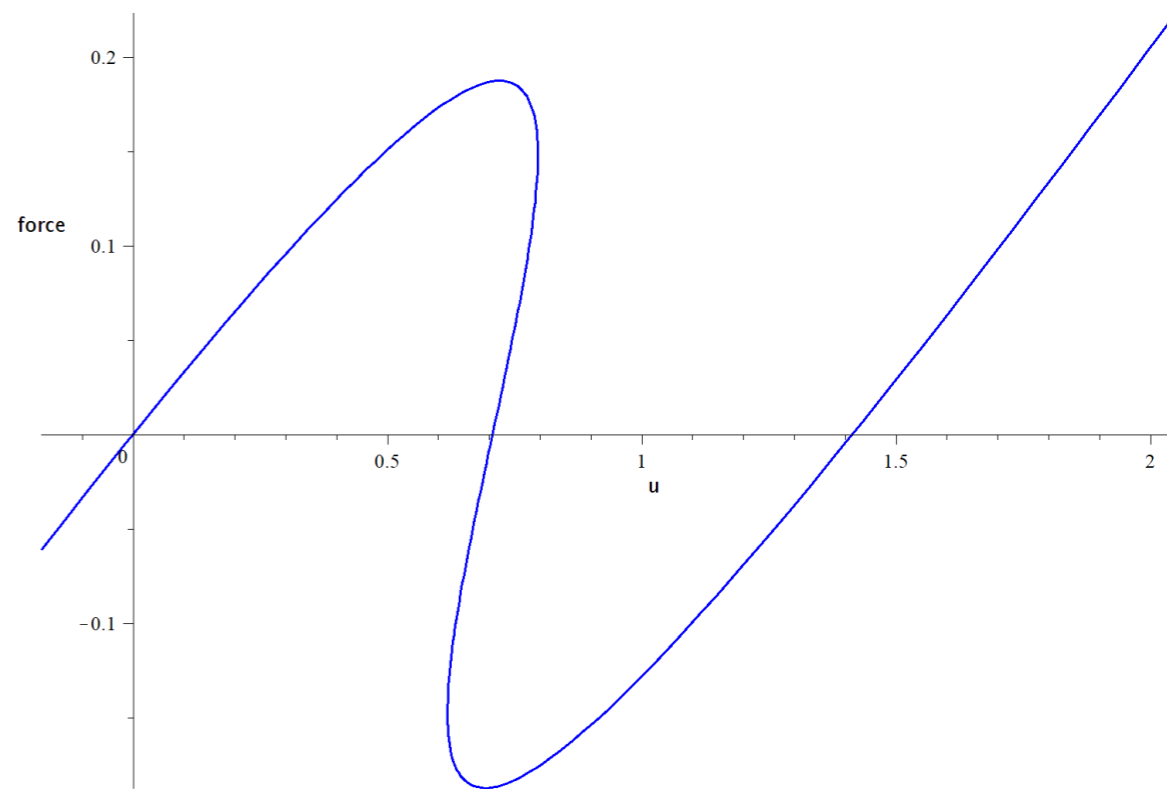
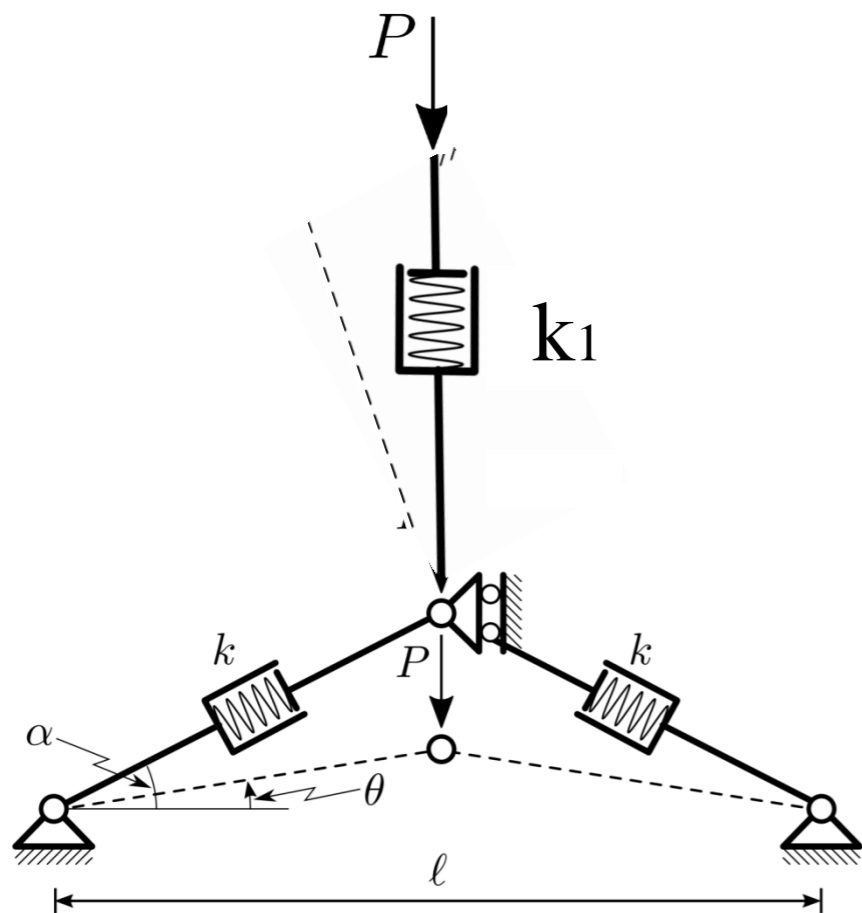
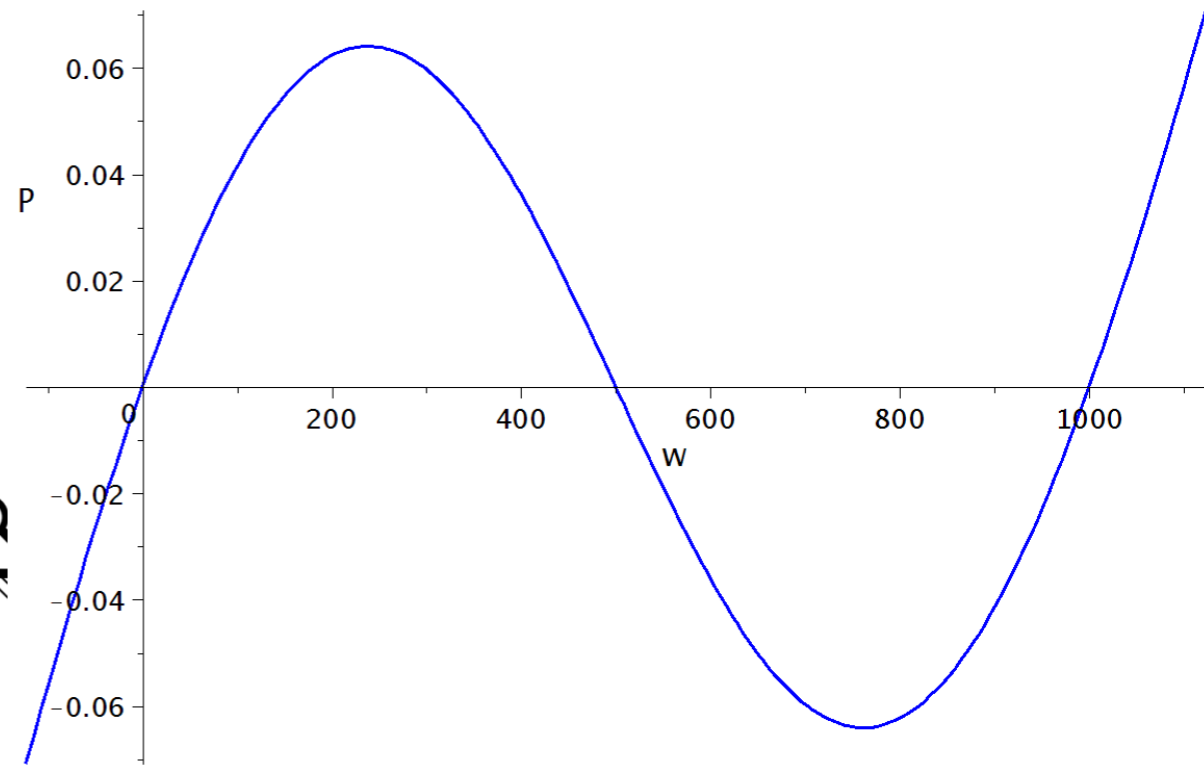
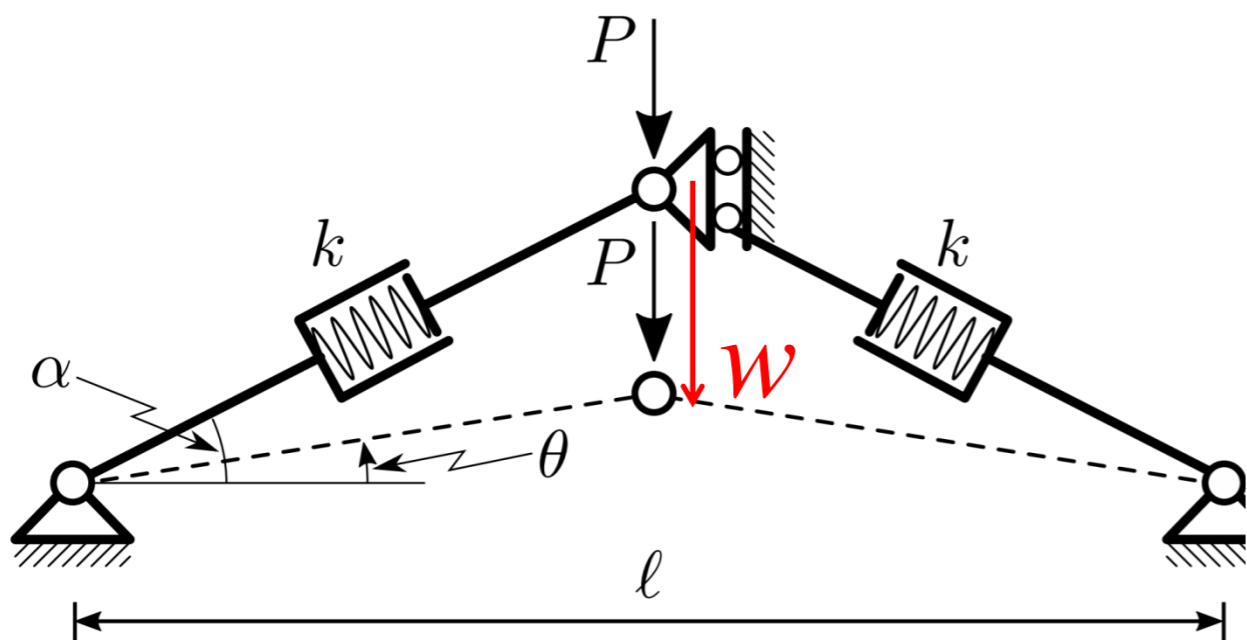
Victor Eremeev

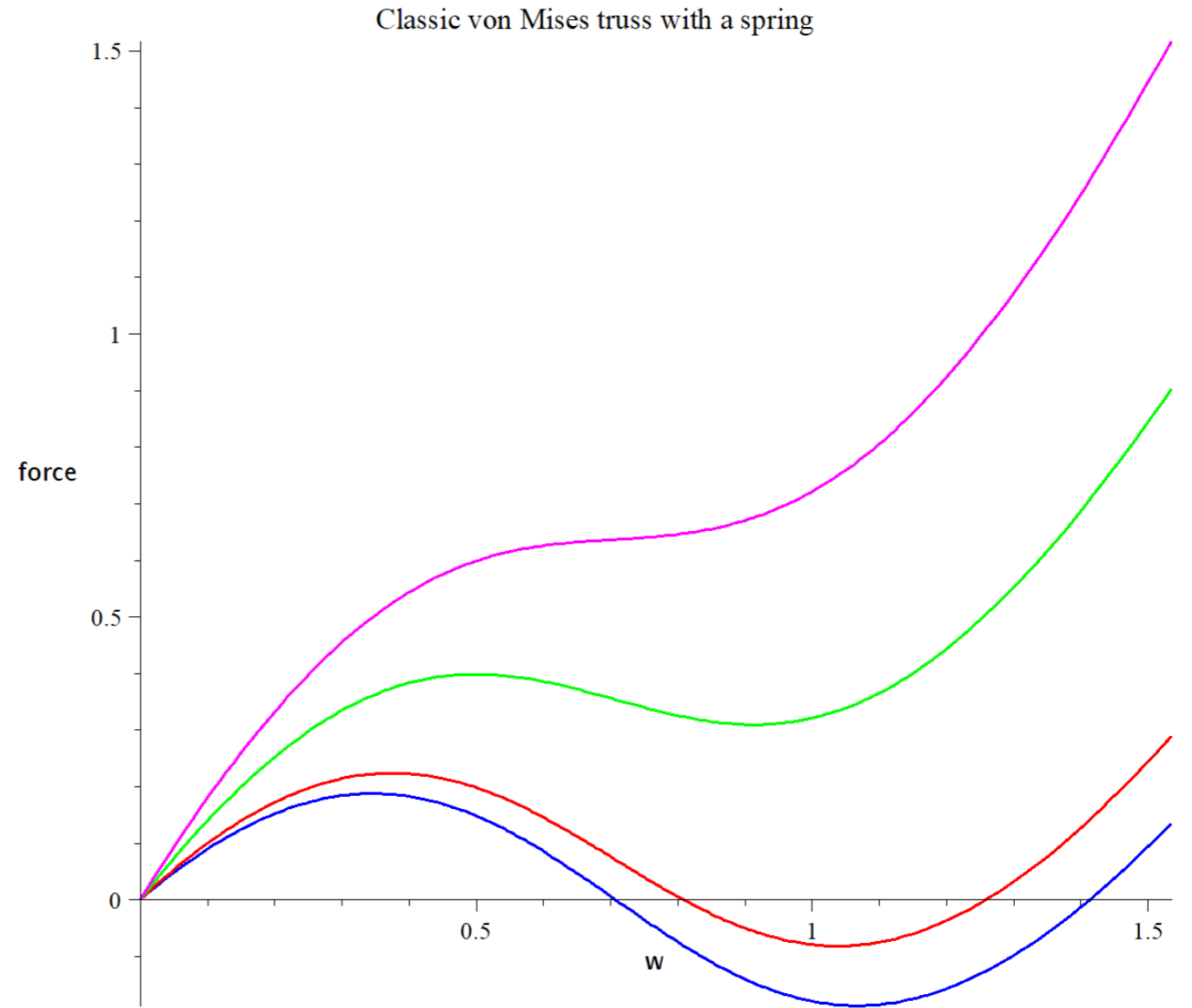
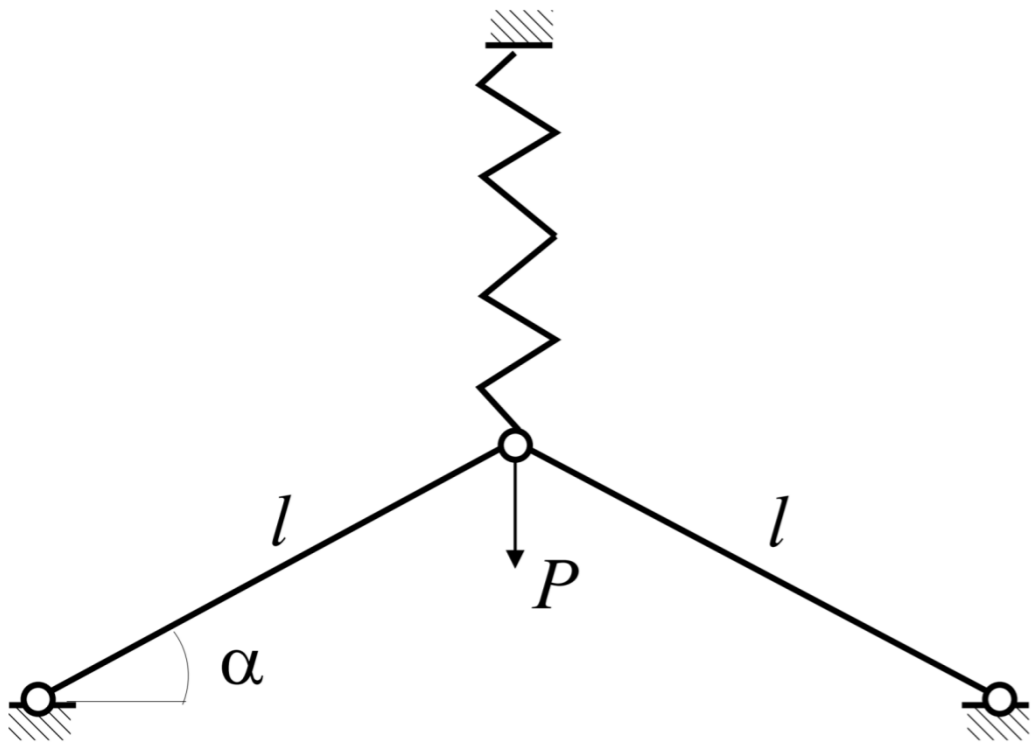
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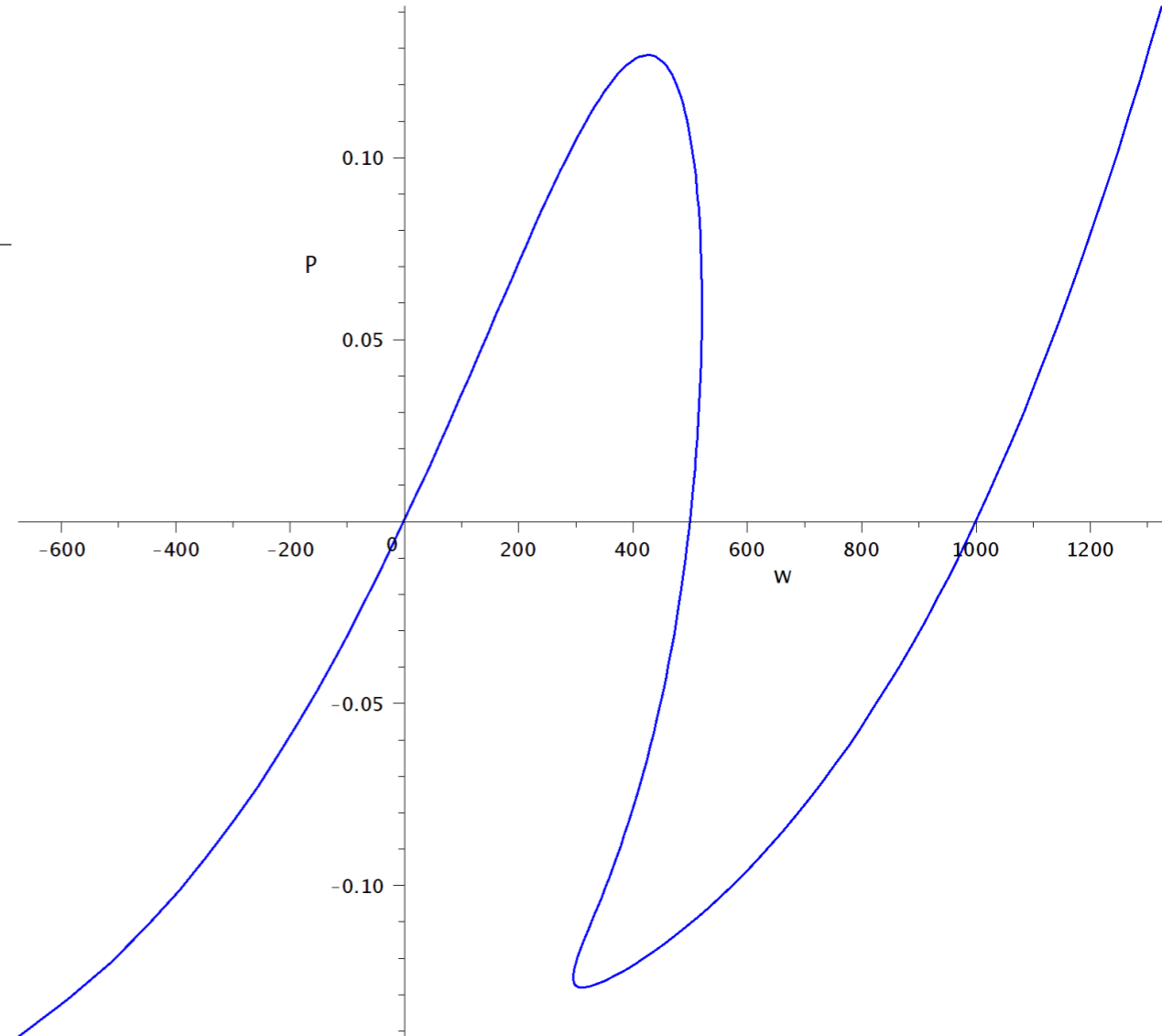
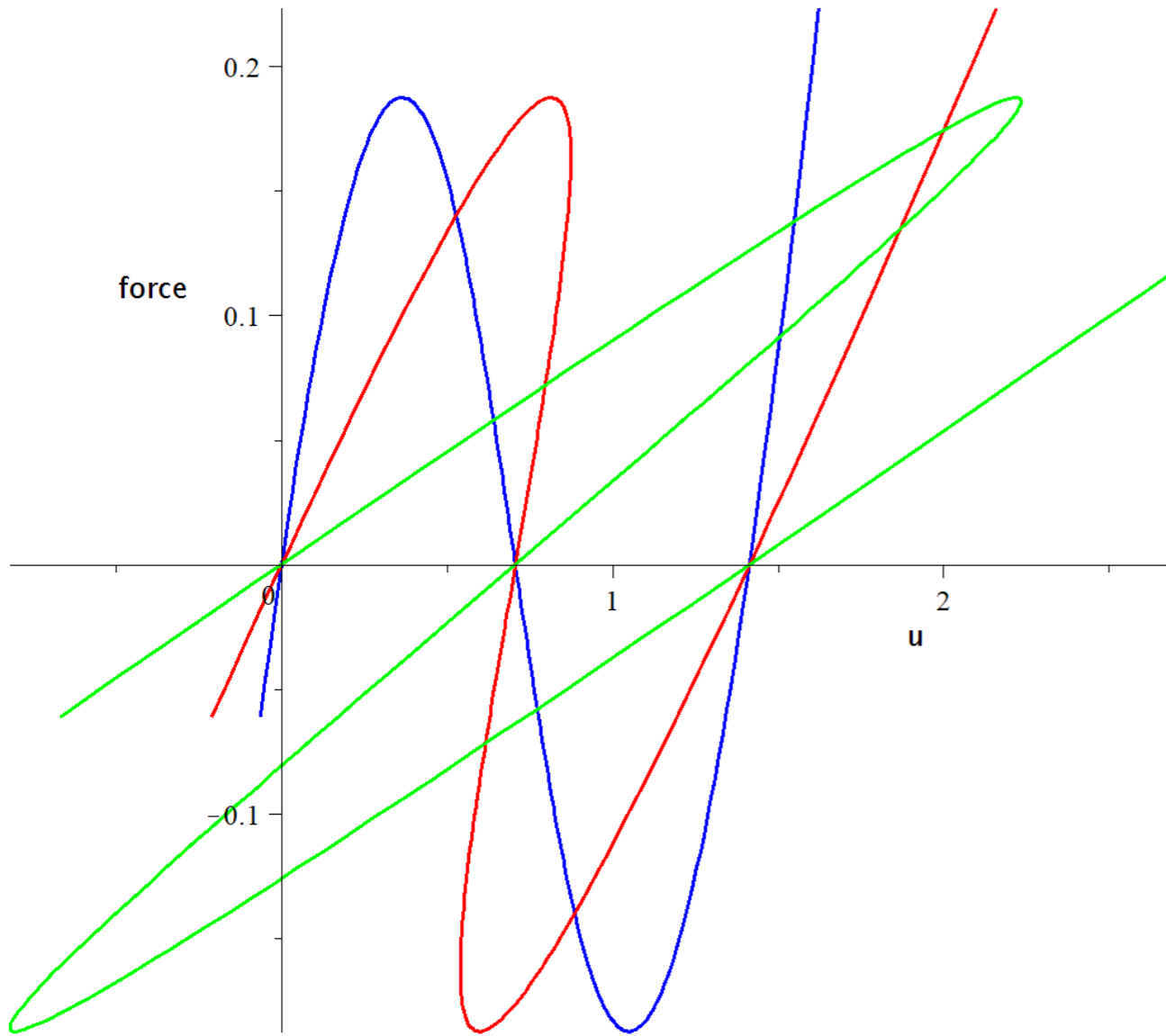
Lo snap-through e snap-back dell'arco a tre cerniere







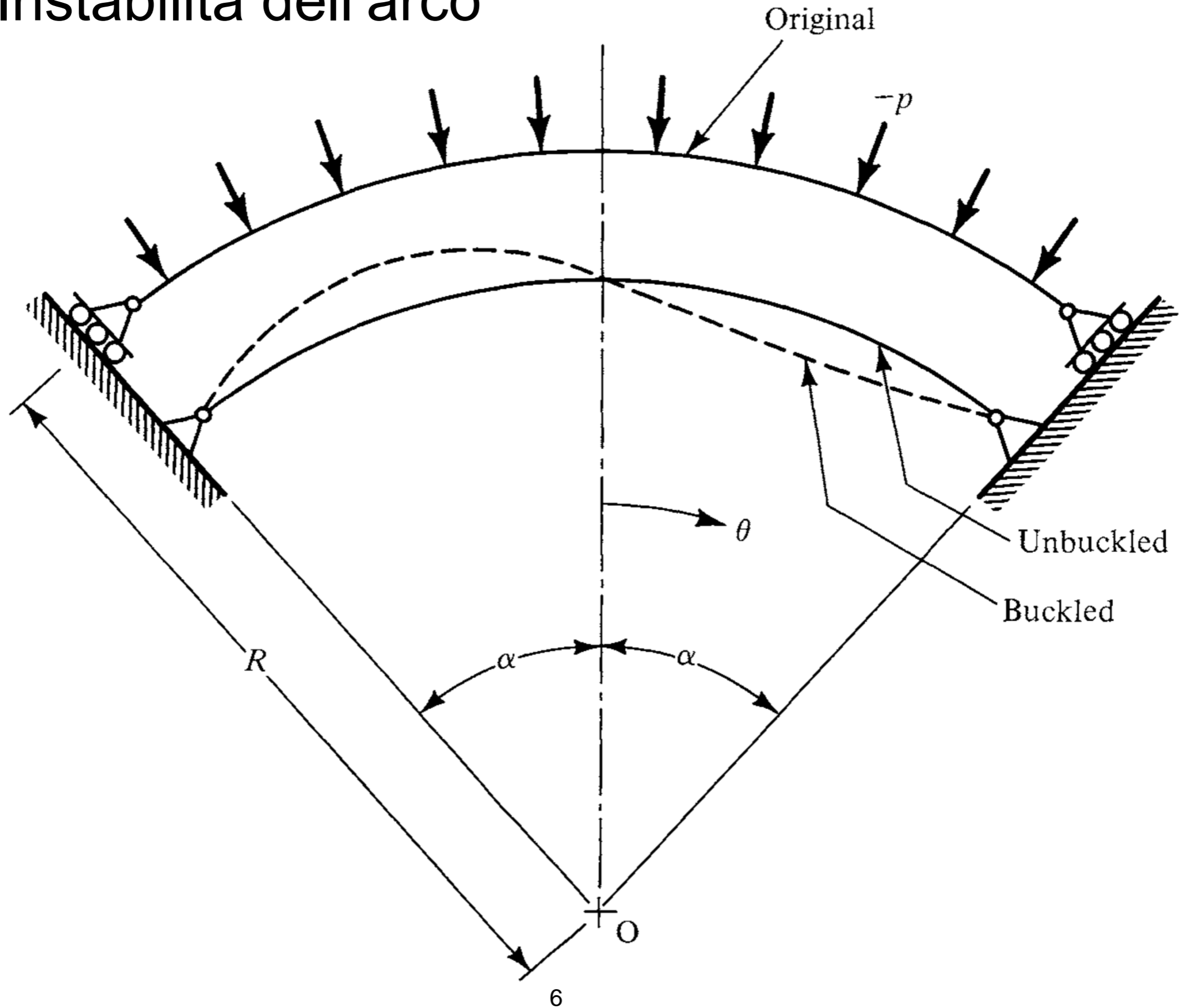
Lo snap-back dell'arco



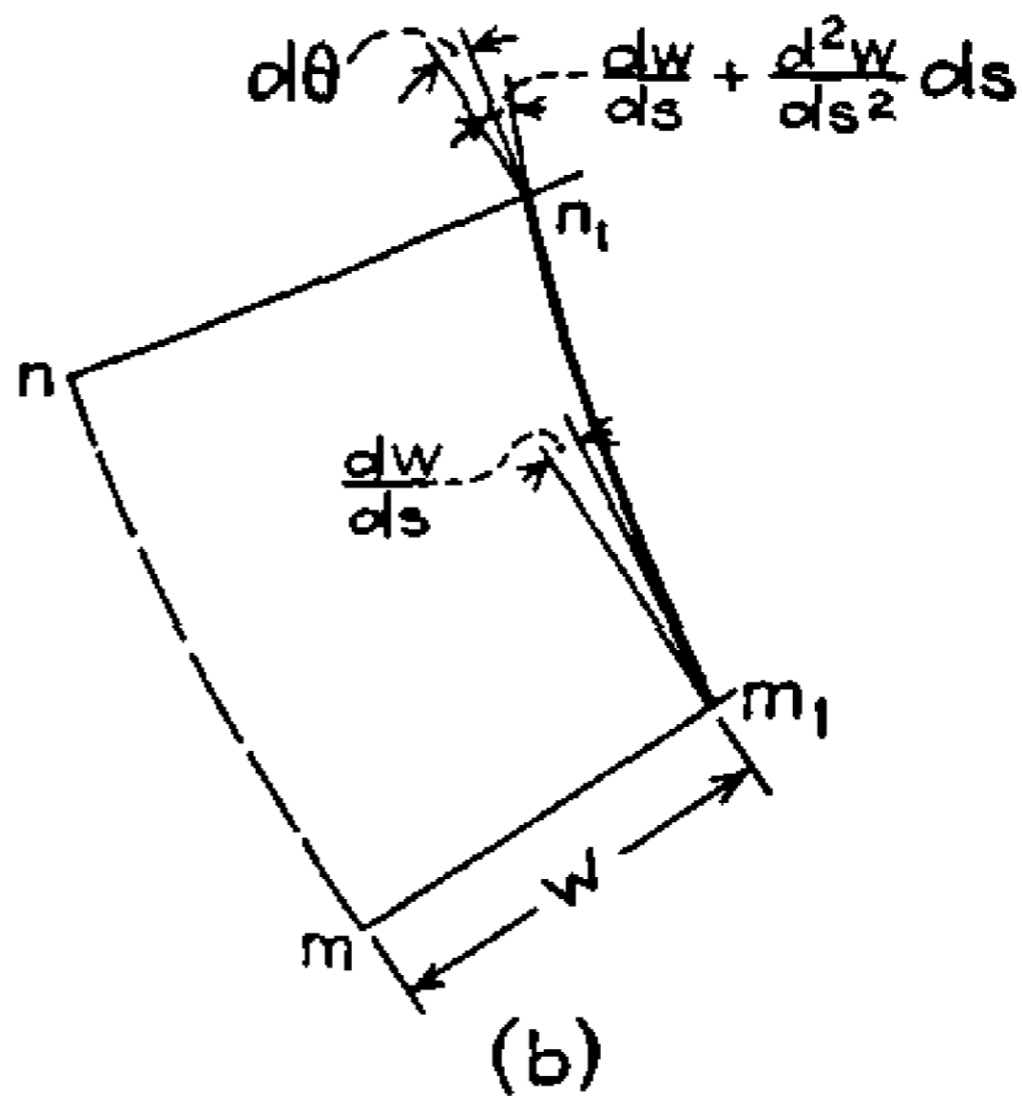
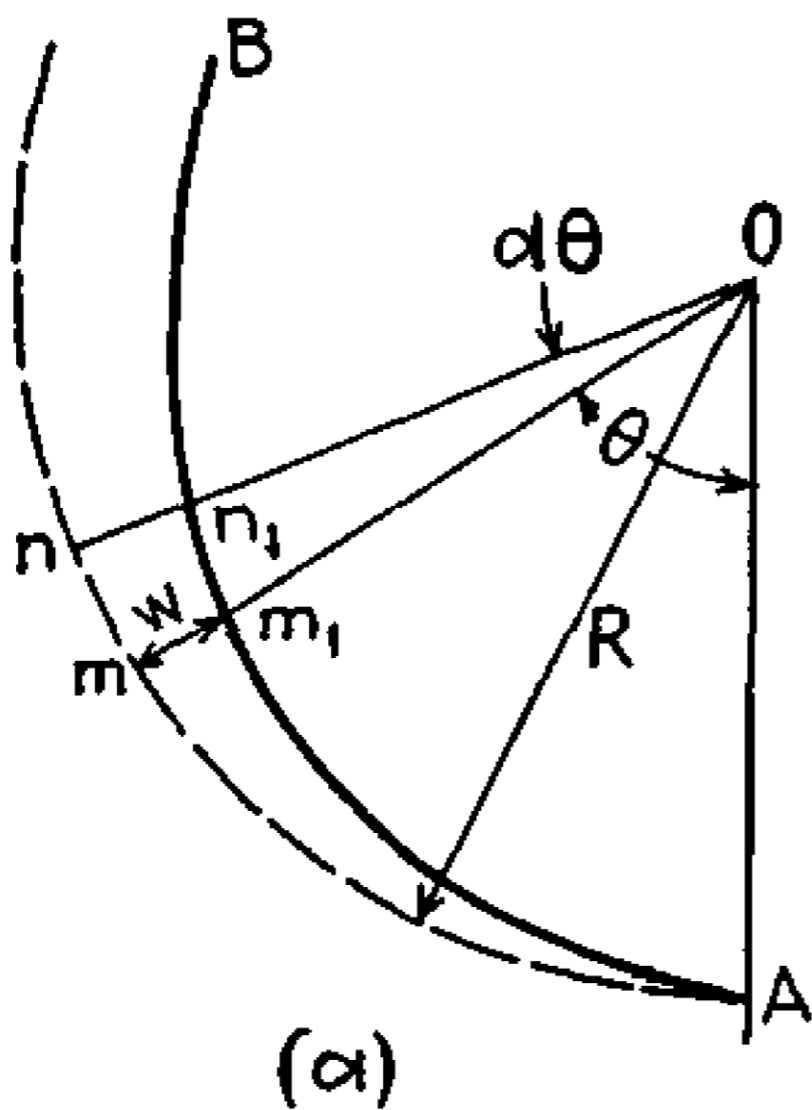
Instabilità dell'arco

Teoria Linearizzata del buckling

Instabilità dell'arco



l'equazione di equilibrio



$$ds = R d\theta$$

$$\frac{d\theta}{ds} = \frac{1}{R}$$

$$\frac{1}{\rho} = \frac{d\theta + \Delta d\theta}{ds + \Delta ds}$$

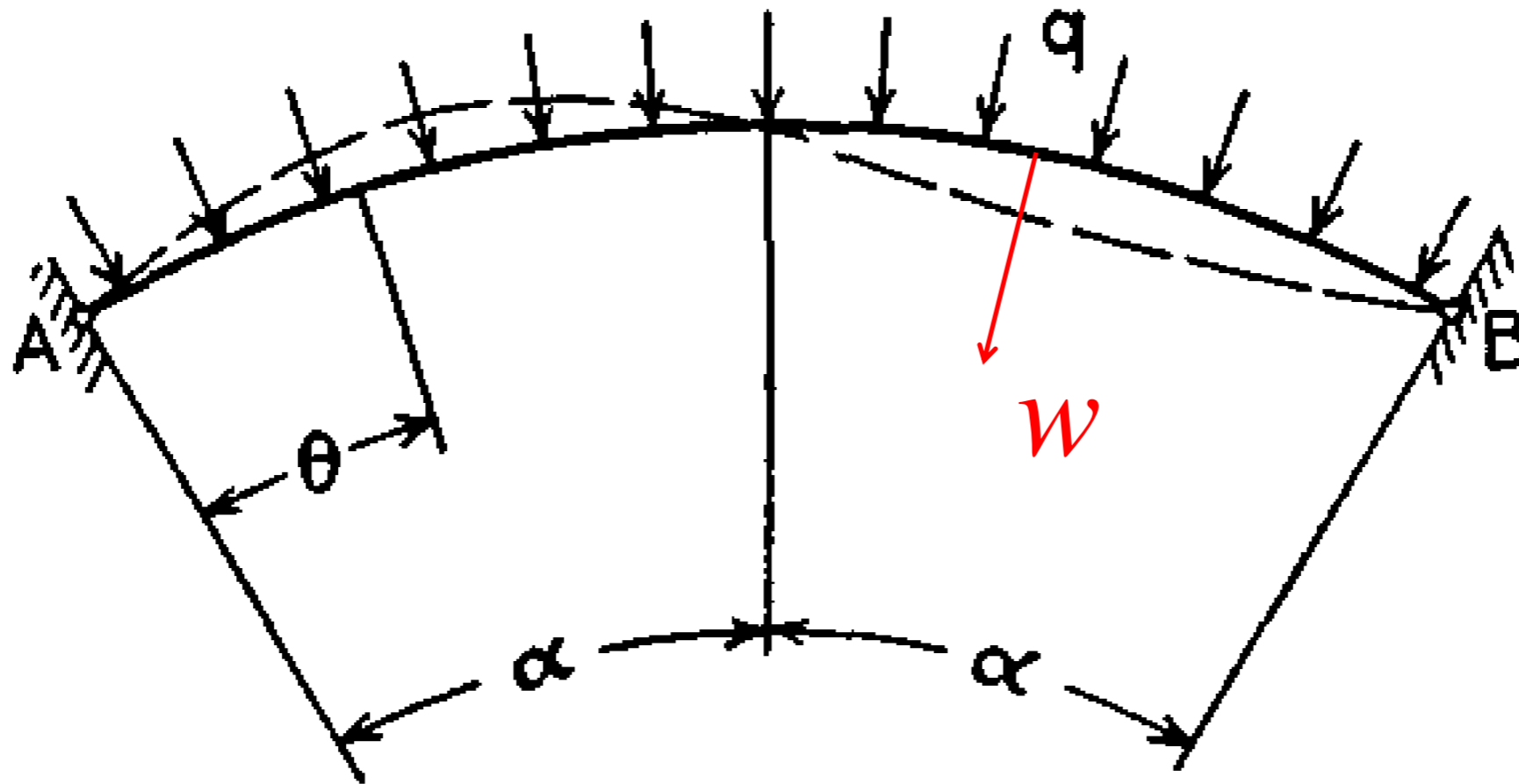
l'equazione di equilibrio

$$EI \left(\frac{1}{\rho} - \frac{1}{R} \right) = -M$$

$$\frac{1}{\rho} = \frac{1}{R} \left(1 + \frac{w}{R} \right) + \frac{d^2w}{ds^2}$$

$$\frac{d^2w}{ds^2} + \frac{w}{R^2} = -\frac{M}{EI}$$

$$\frac{d^2w}{d\theta^2} + w = -\frac{MR^2}{EI}$$



$$\frac{d^2w}{d\theta^2} + w = -\frac{R^2 S w}{EI} \quad S = qR$$

$$\frac{d^2w}{d\theta^2} + w = -\frac{R^2 S w}{EI}$$

$$k^2 = 1 + \frac{qR^3}{EI}$$

$$\frac{d^2w}{d\theta^2} + k^2 w = 0$$

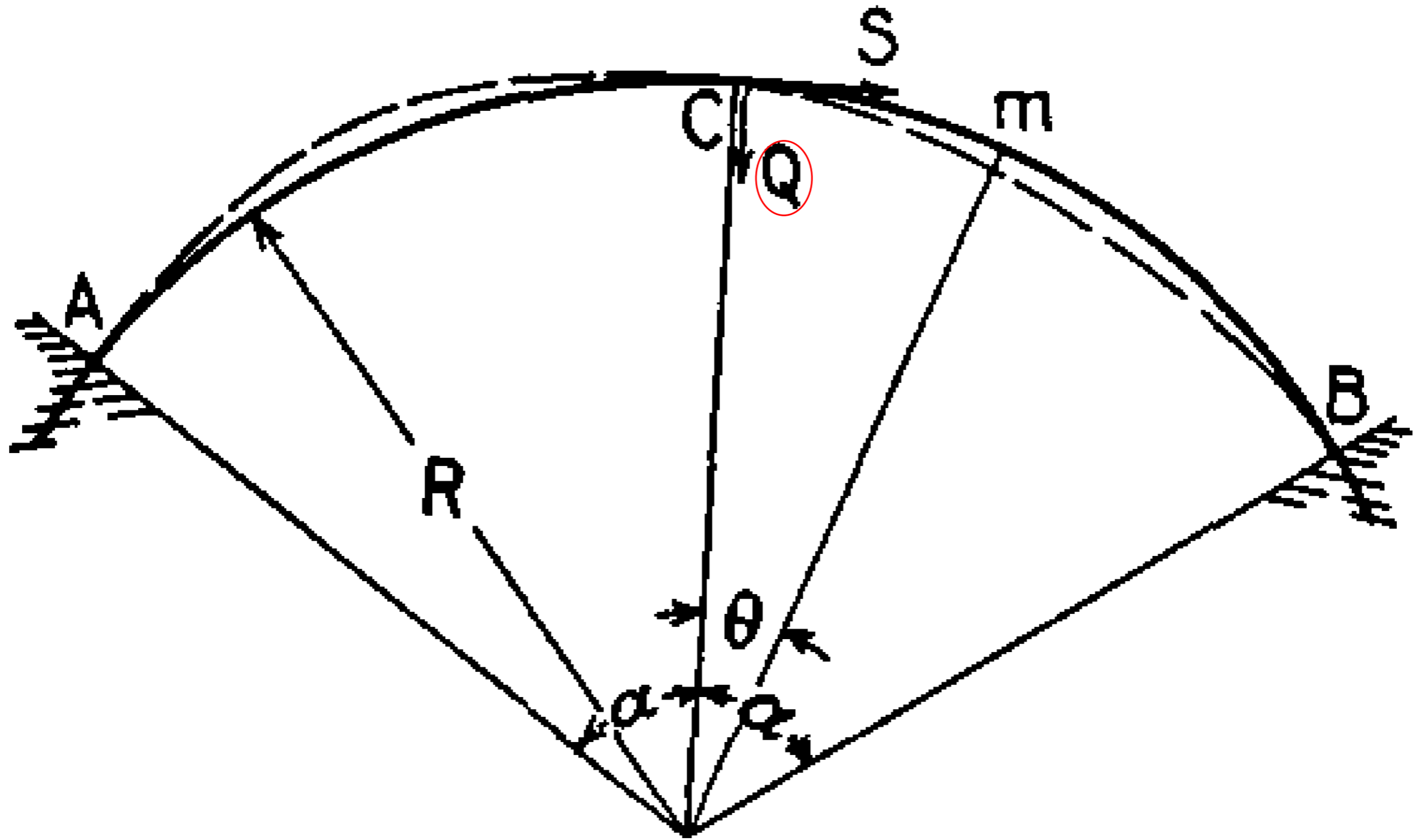
la cui soluzione

$$w = A \sin k\theta + B \cos k\theta$$

$$B = 0, \rightarrow \sin 2\alpha k = 0$$

$$k = \frac{\pi}{\alpha}$$

$$Q_{cr} = \frac{EI}{R^3} \left(\frac{\pi^2}{\alpha^2} - 1 \right)$$



$$M = Sw - QR \sin \theta$$

$$\frac{d^2w}{d\theta^2} + w = -\frac{R^2}{EI} (Sw - QR \sin \theta)$$

$$\frac{d^2w}{d\theta^2} + k^2w = \frac{QR^3 \sin \theta}{EI}$$

$$w = A \sin k\theta + B \cos k\theta + \frac{QR^3 \sin \theta}{(k^2 - 1)EI}$$

$$w = \frac{d^2w}{d\theta^2} = 0 \quad \text{at } \theta = 0$$

$$w = \frac{dw}{d\theta} = 0 \quad \text{at } \theta = \alpha$$

$$A \sin k\alpha + Q \frac{R^3 \sin \alpha}{(k^2 - 1)EI} = 0$$

$$Ak \cos k\alpha + Q \frac{R^3 \cos \alpha}{(k^2 - 1)EI} = 0$$

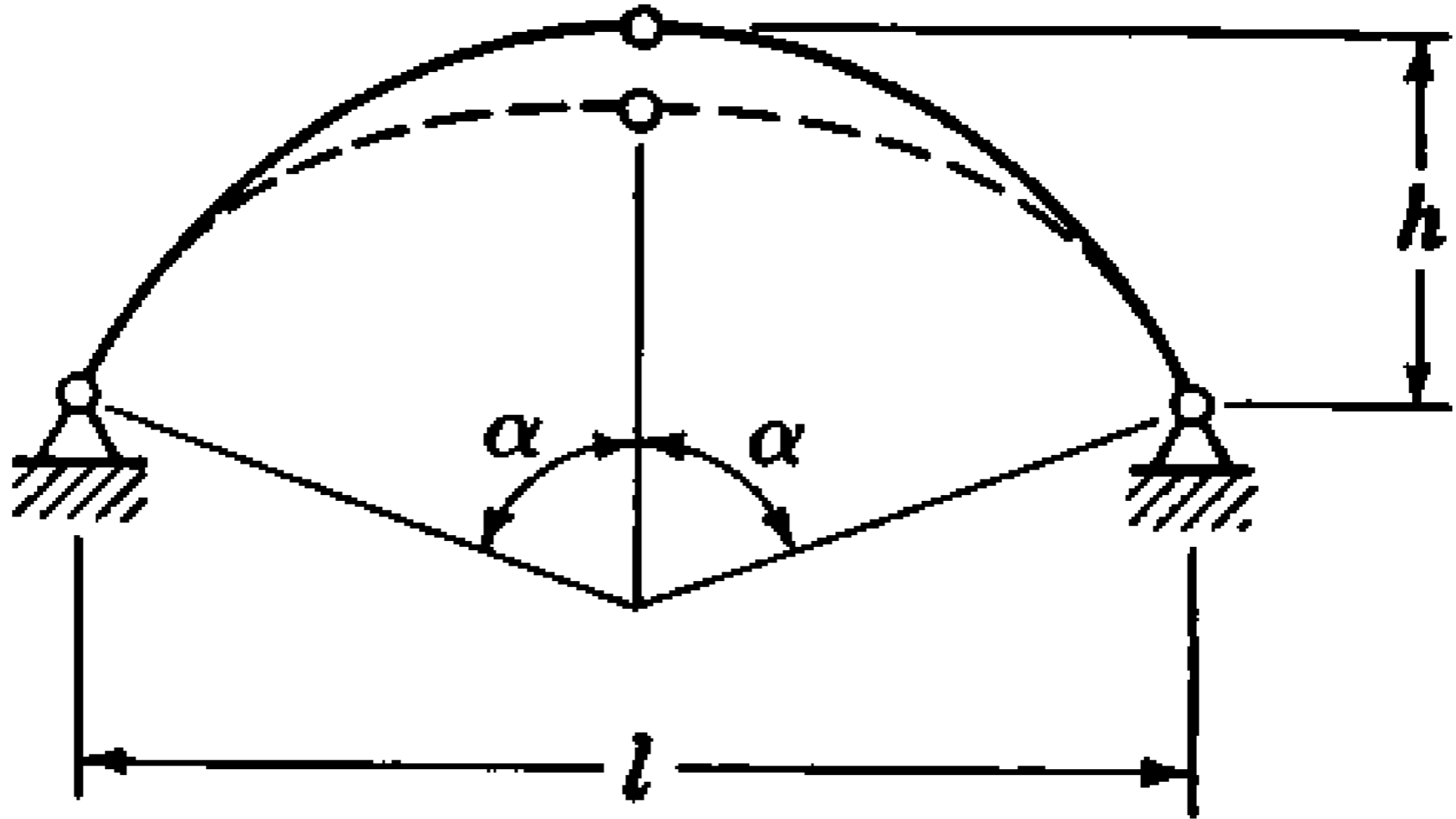
$$k \tan \alpha \cot k\alpha = 1$$

α	30°	60°	90°	120°	150°	180°
k	8.621	4.375	3	2.364	2.066	2

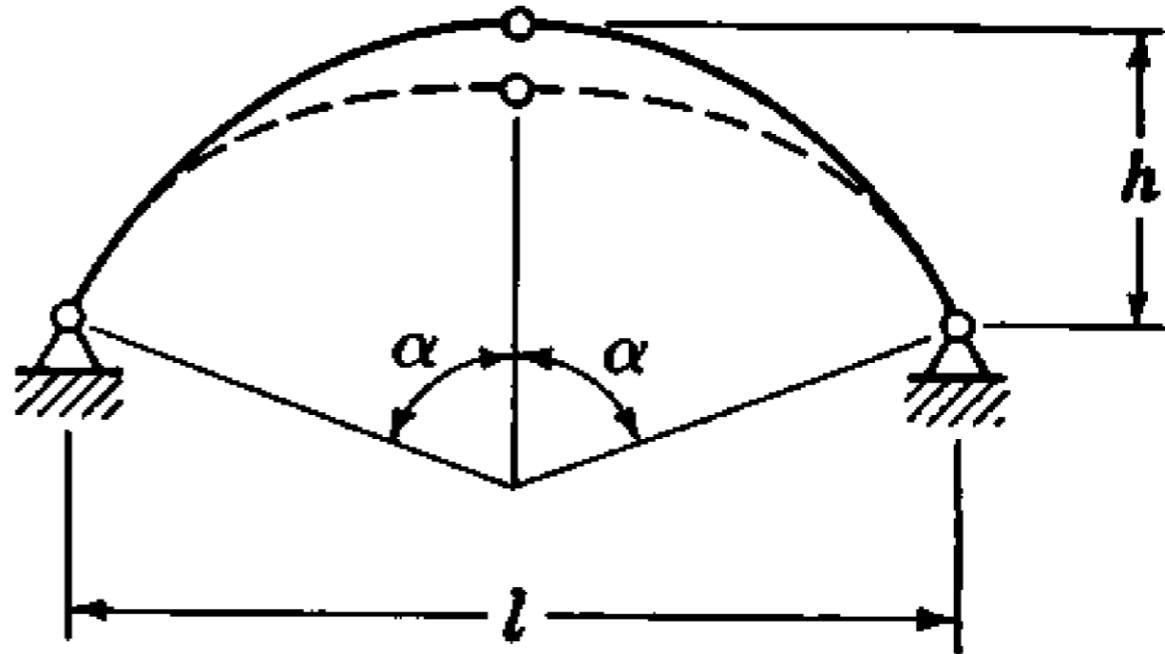
$$q_{cr} = \frac{EI}{R^3} (k^2 - 1)$$

$$Q_{cr} = \gamma_1 \frac{EI}{R^3}$$

2α (deg)	No hinges	One hinge	Two hinges	Three hinges
30	294	162	143	108
60	73.3	40.2	35	27.6
90	32.4	17.4	15	12.0
120	18.1	10.2	8	6.75
150	11.5	6.56	4.76	4.32
180	8.0	4.61	3.00	3.00



$$Q_{cr} = \gamma_2 \frac{EI}{l^3}$$

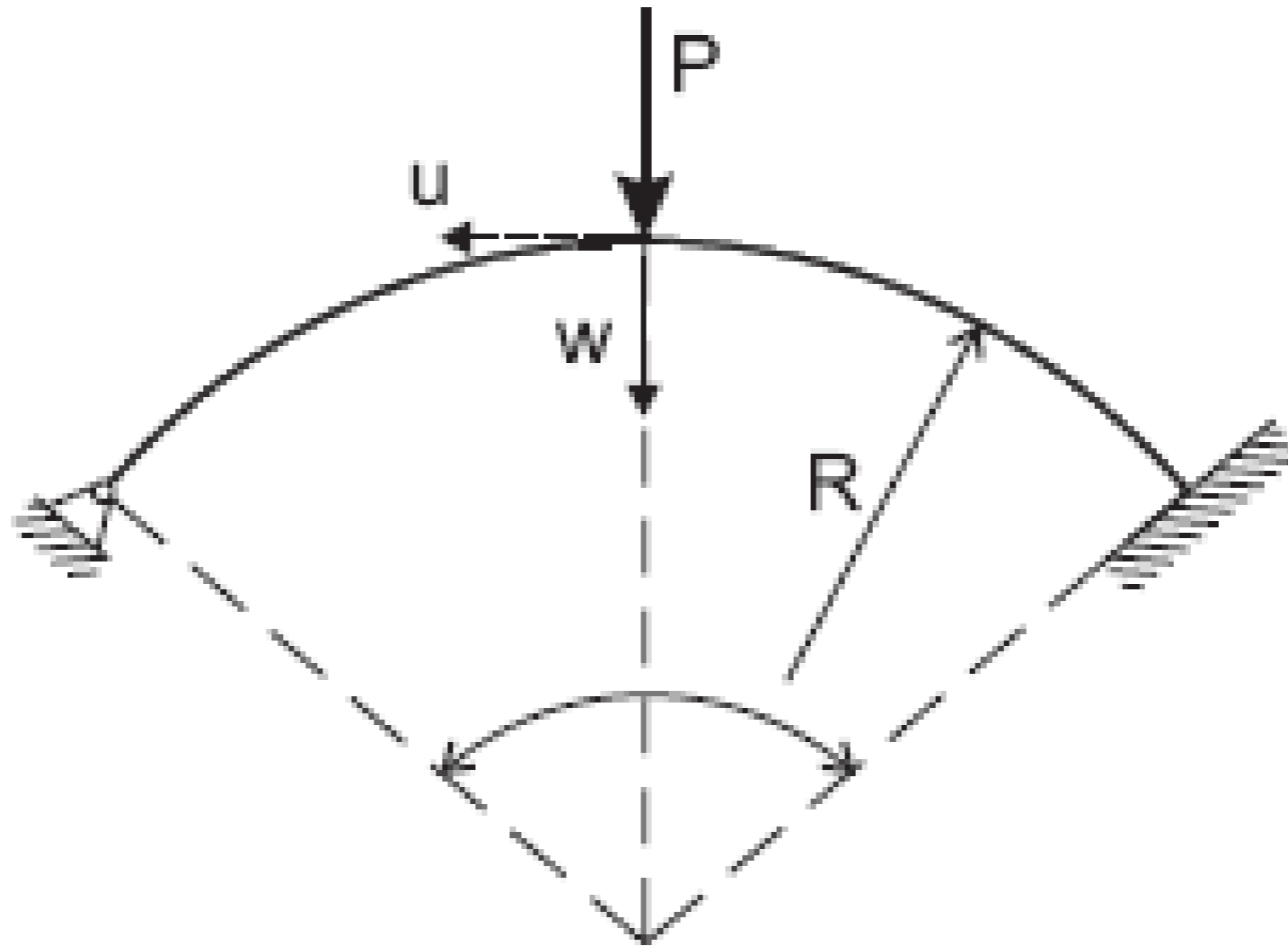


$\frac{h}{l}$	No hinges	One hinge	Two hinges	Three hinges
0.1	58.9	33	28.4	22.2
0.2	90.4	50	39.3	33.5
0.3	93.4	52	40.9	34.9
0.4	80.7	46	32.8	30.2
0.5	64.0	37	24.0	24.0

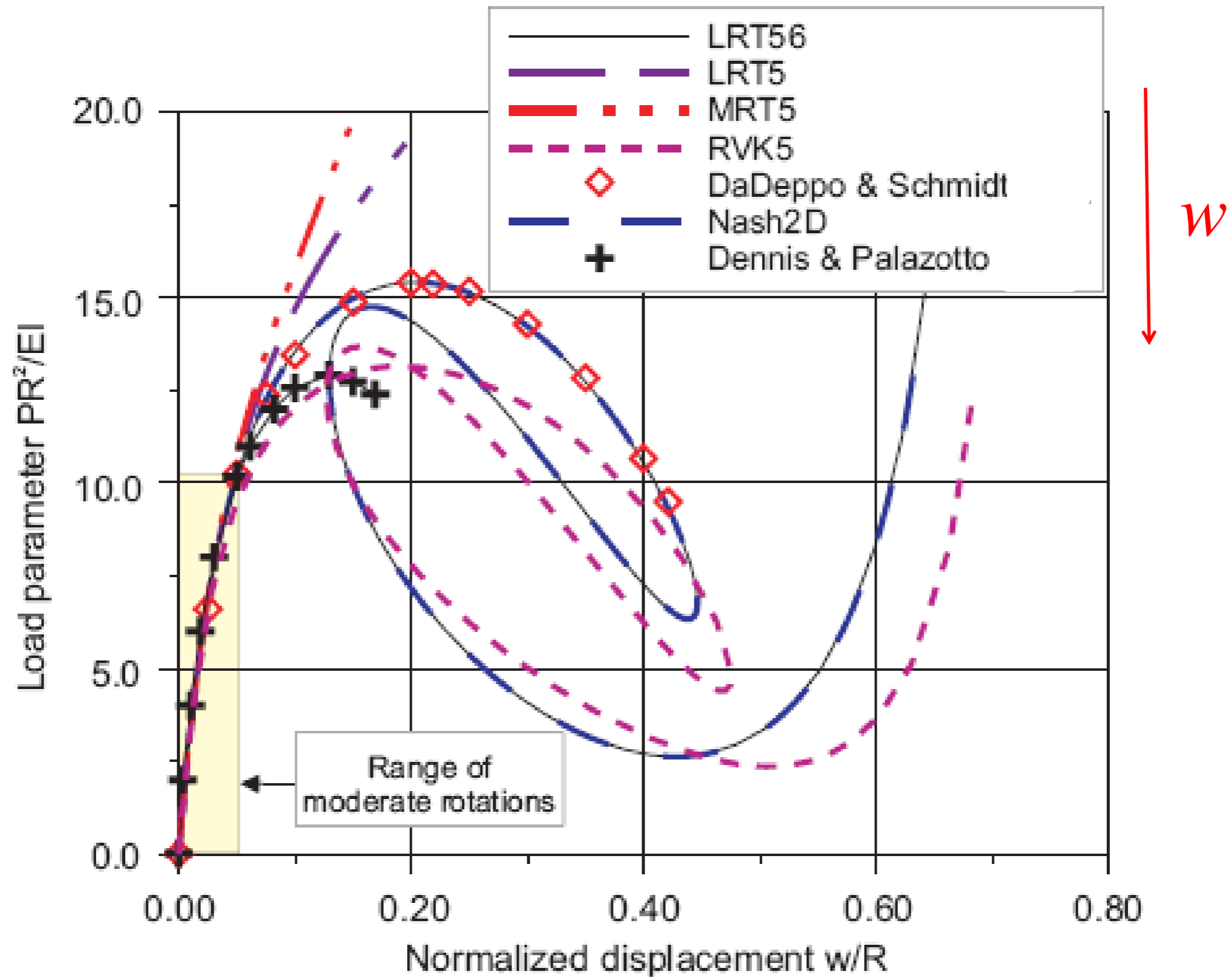


Buckling e postbuckling

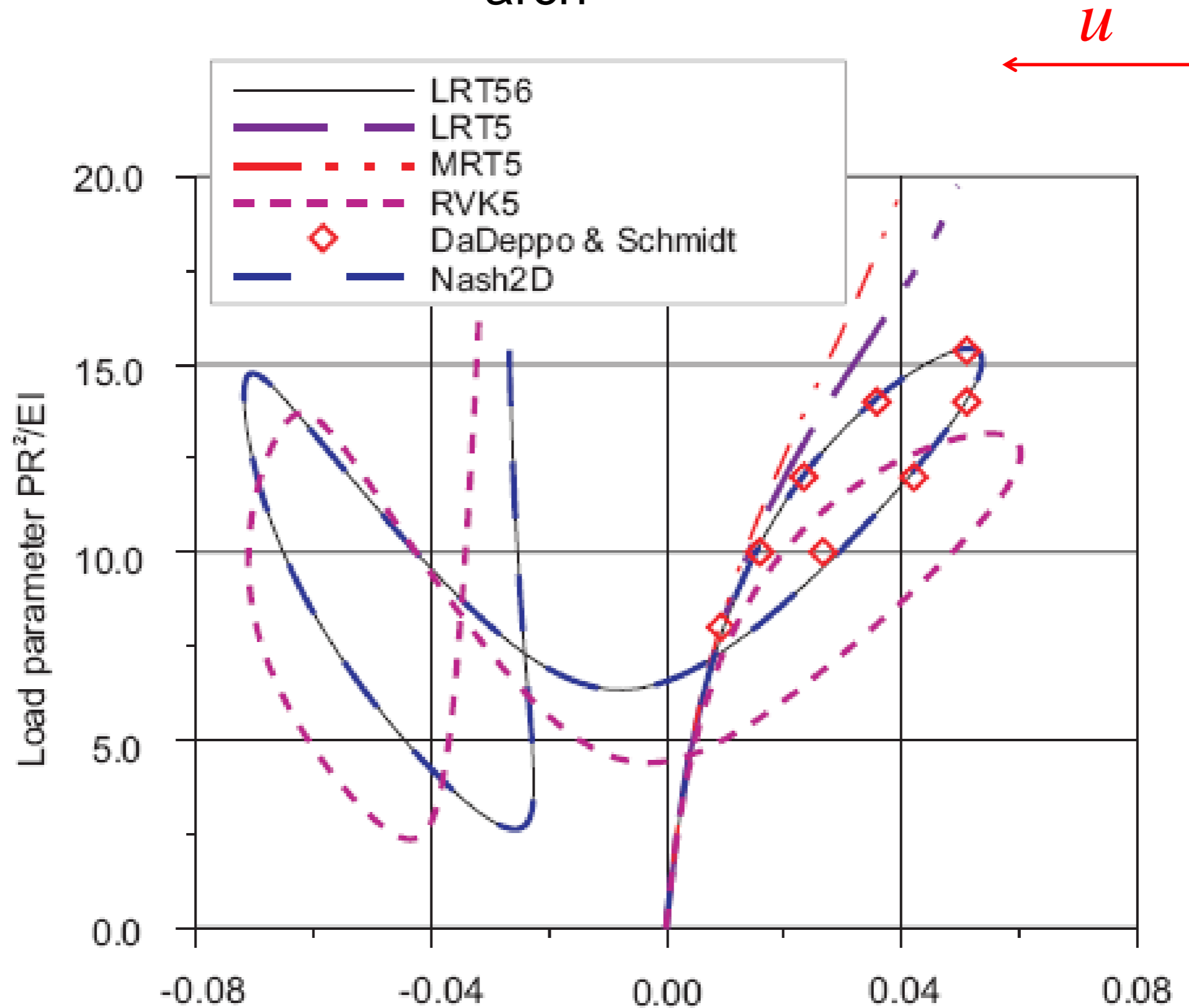
Instability of clamped-hinged circular arches



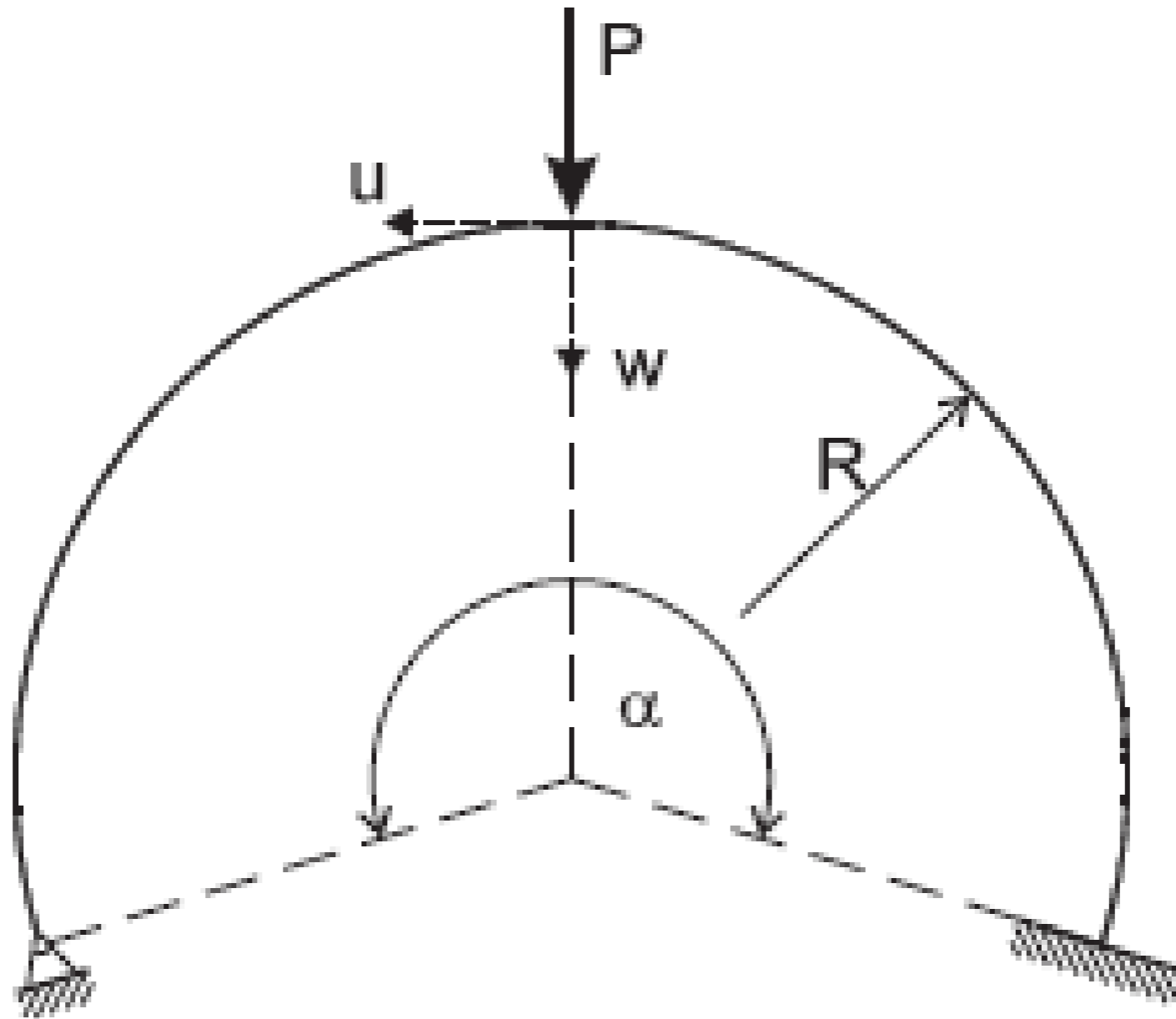
Normalized downward displacement at the crown for 100-degree arch

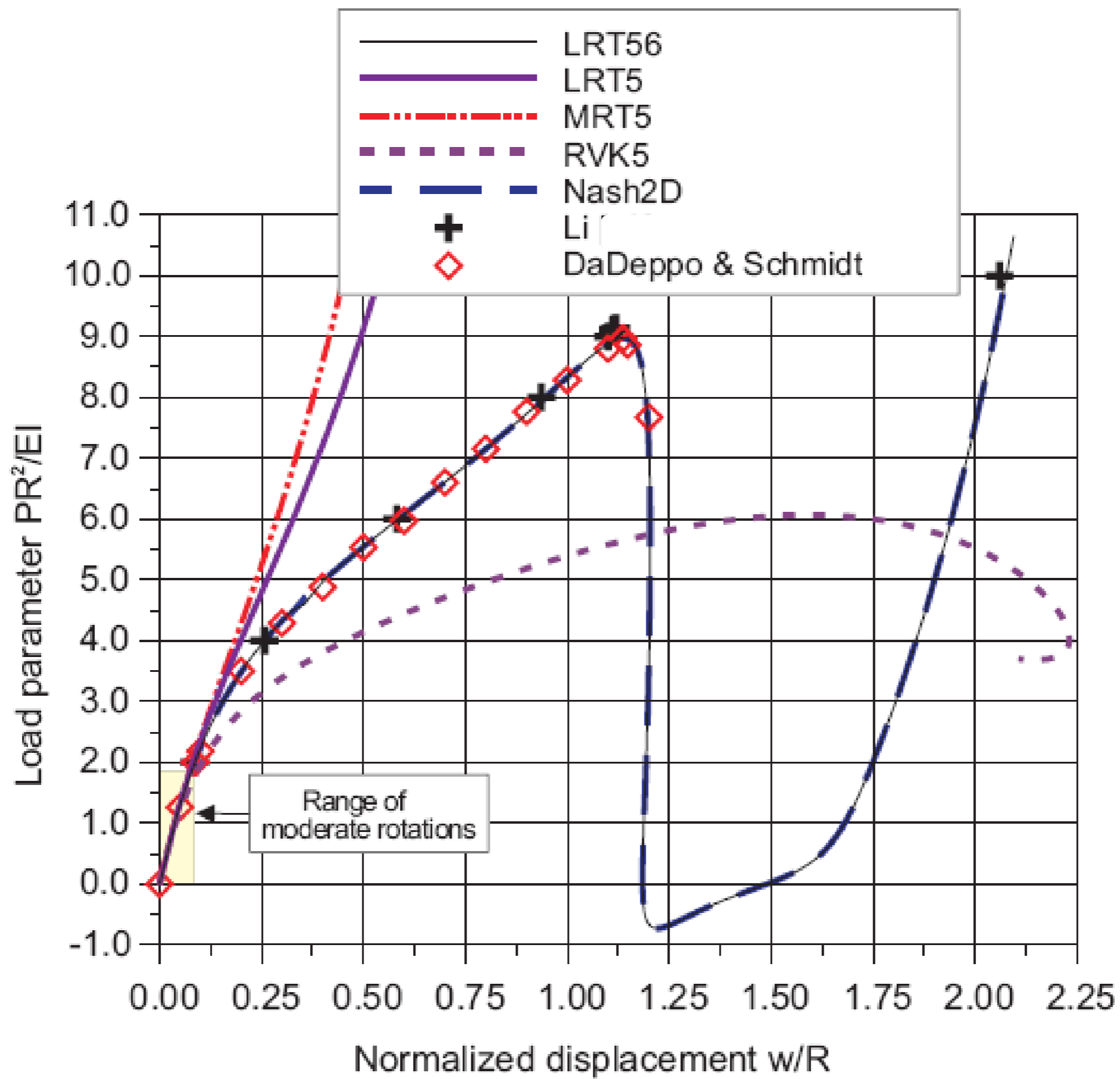


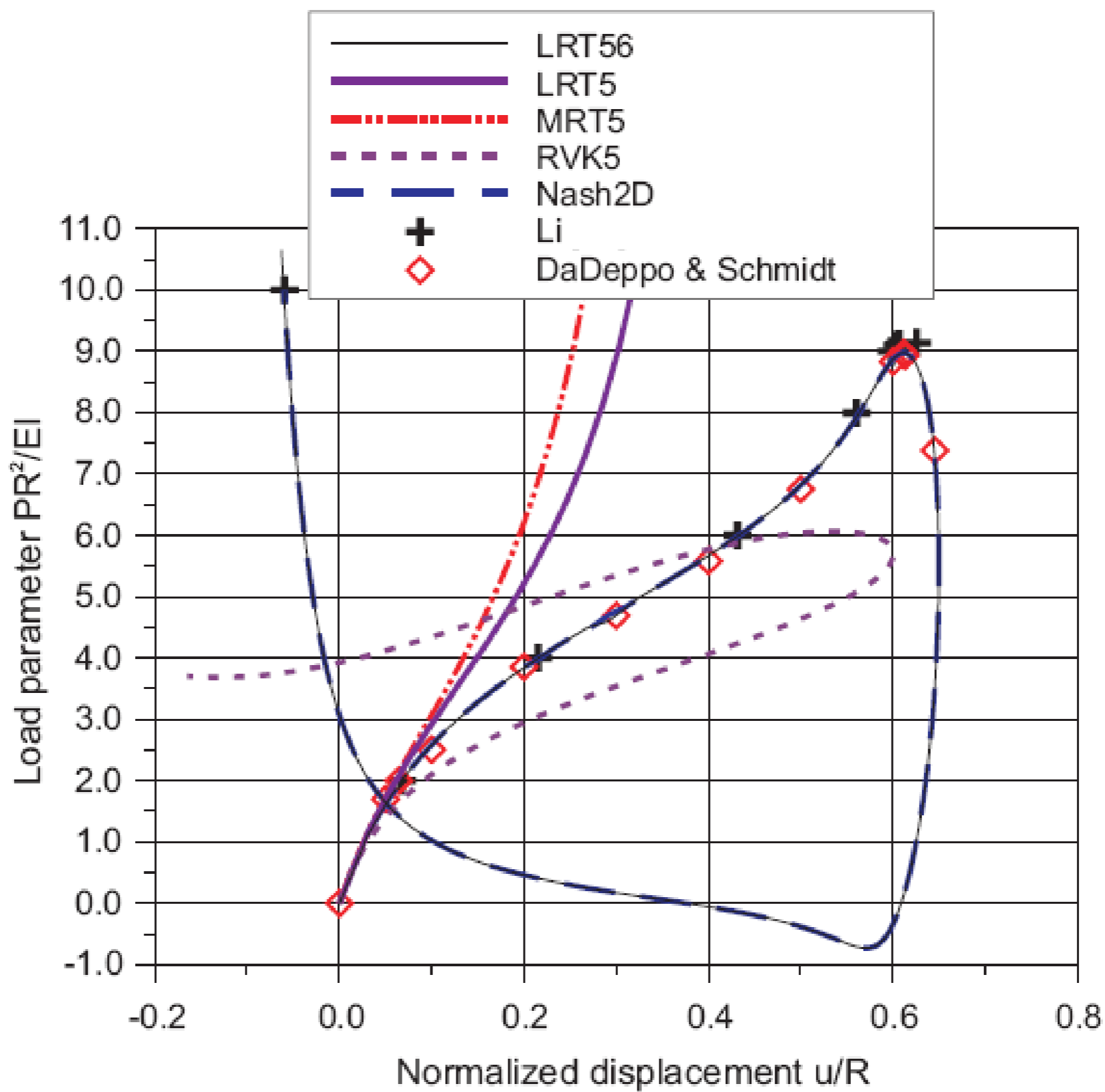
Normalized horizontal displacement at the crown for 100-degree arch



Clamped-hinged arch, $\alpha = 215$ degrees

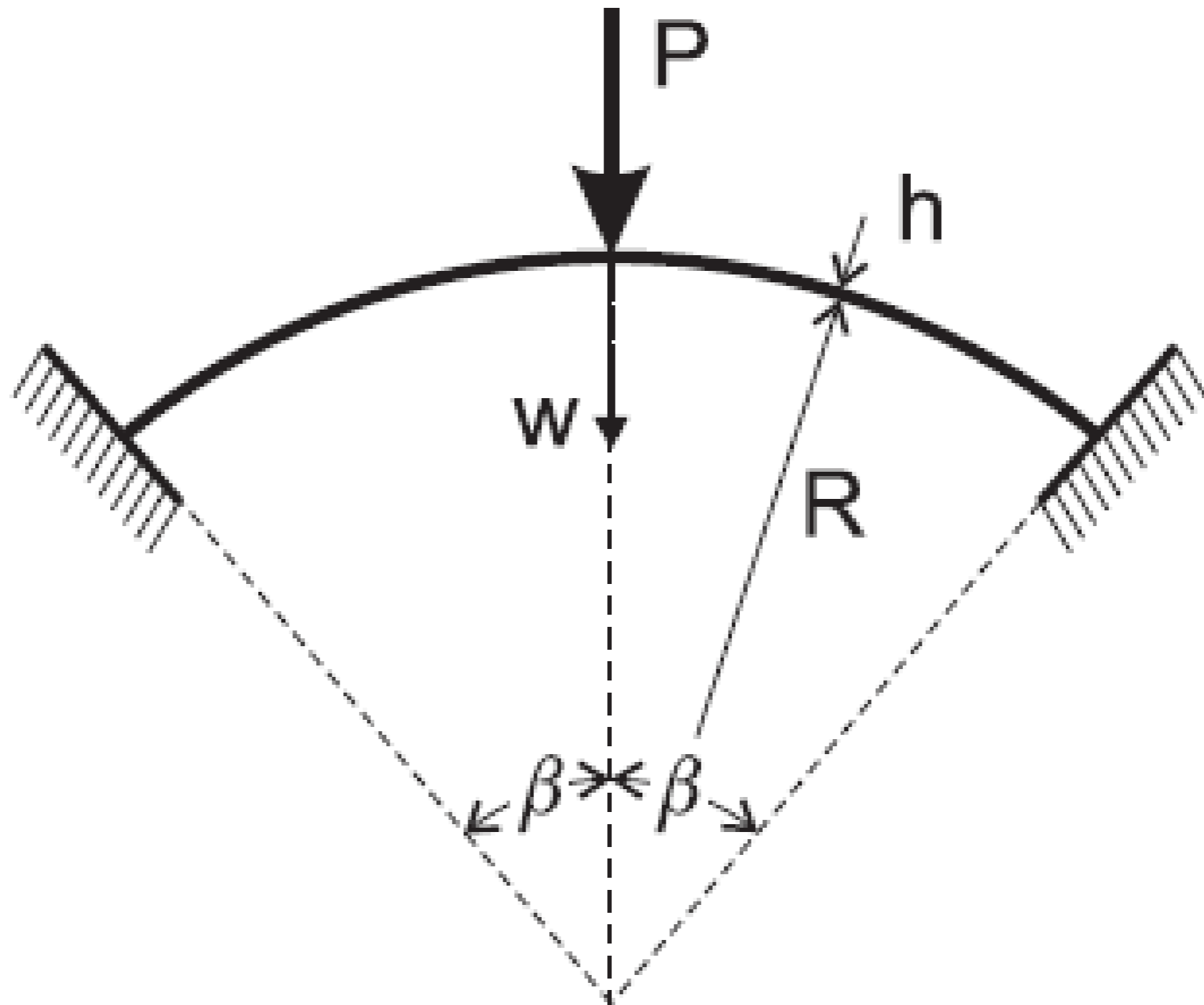


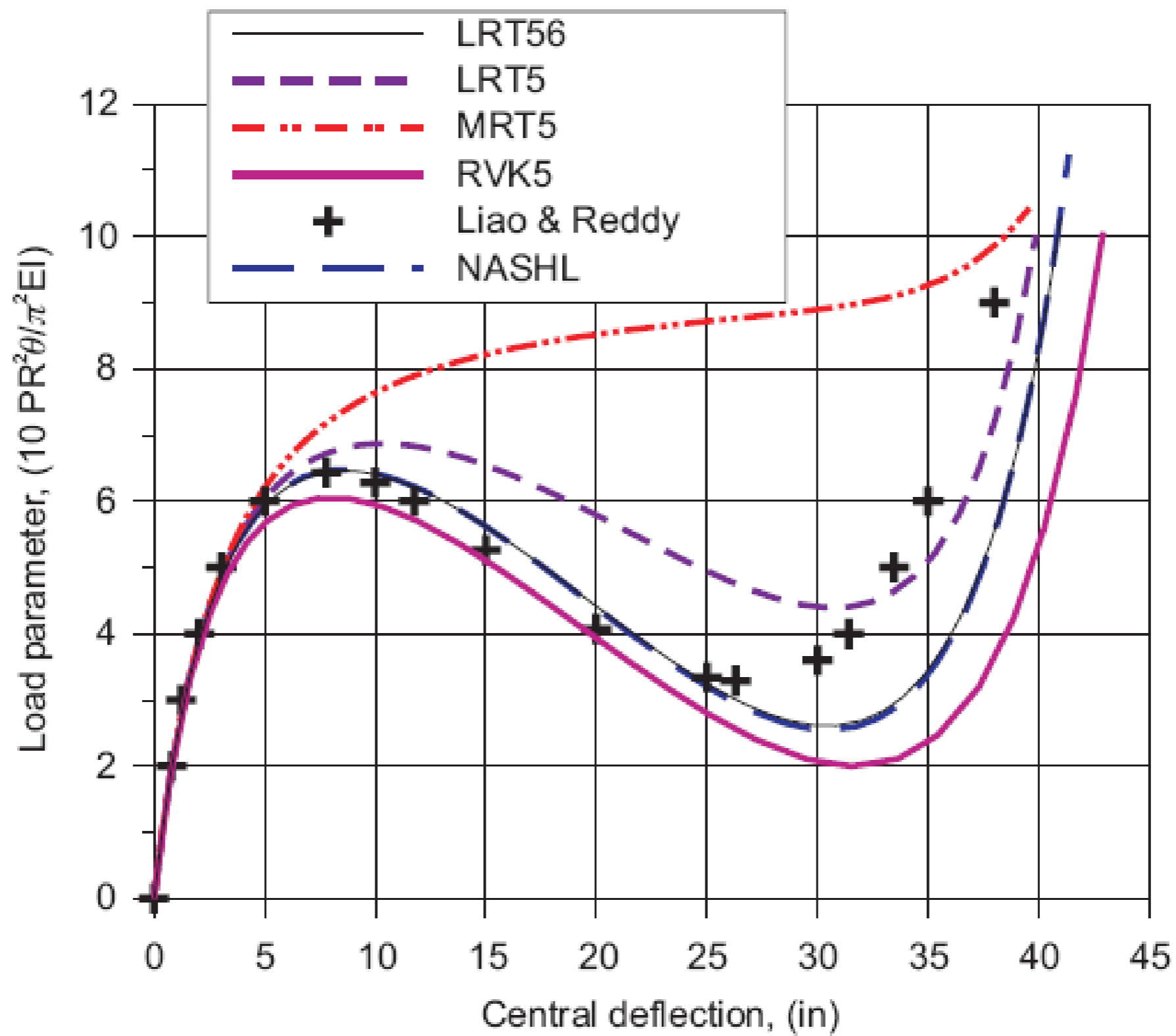




Normalized horizontal displacement at the crown for 215-degree arch

Clamped laminated shallow arch under point load





Central vertical deflection for clamped laminated arch