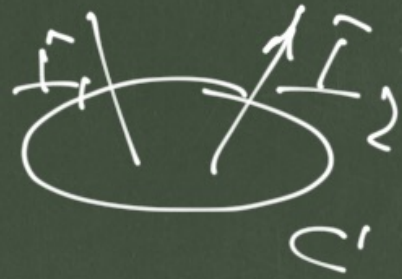
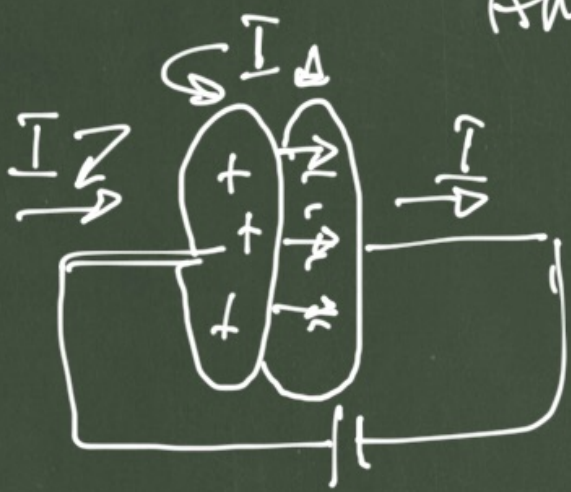


$$\oint_C \vec{B} \cdot d\vec{s} = \mu_0 I$$



AMPERE

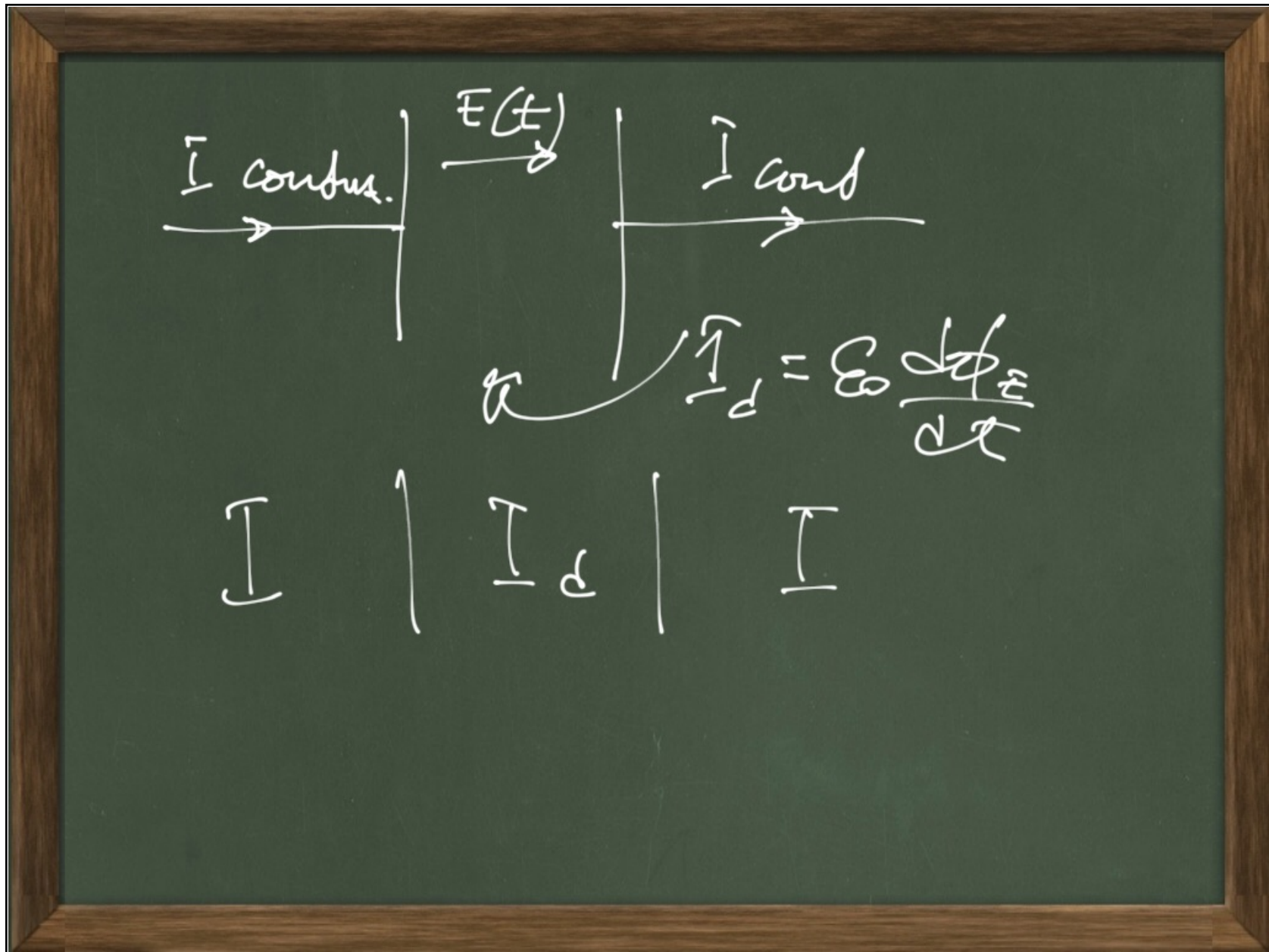


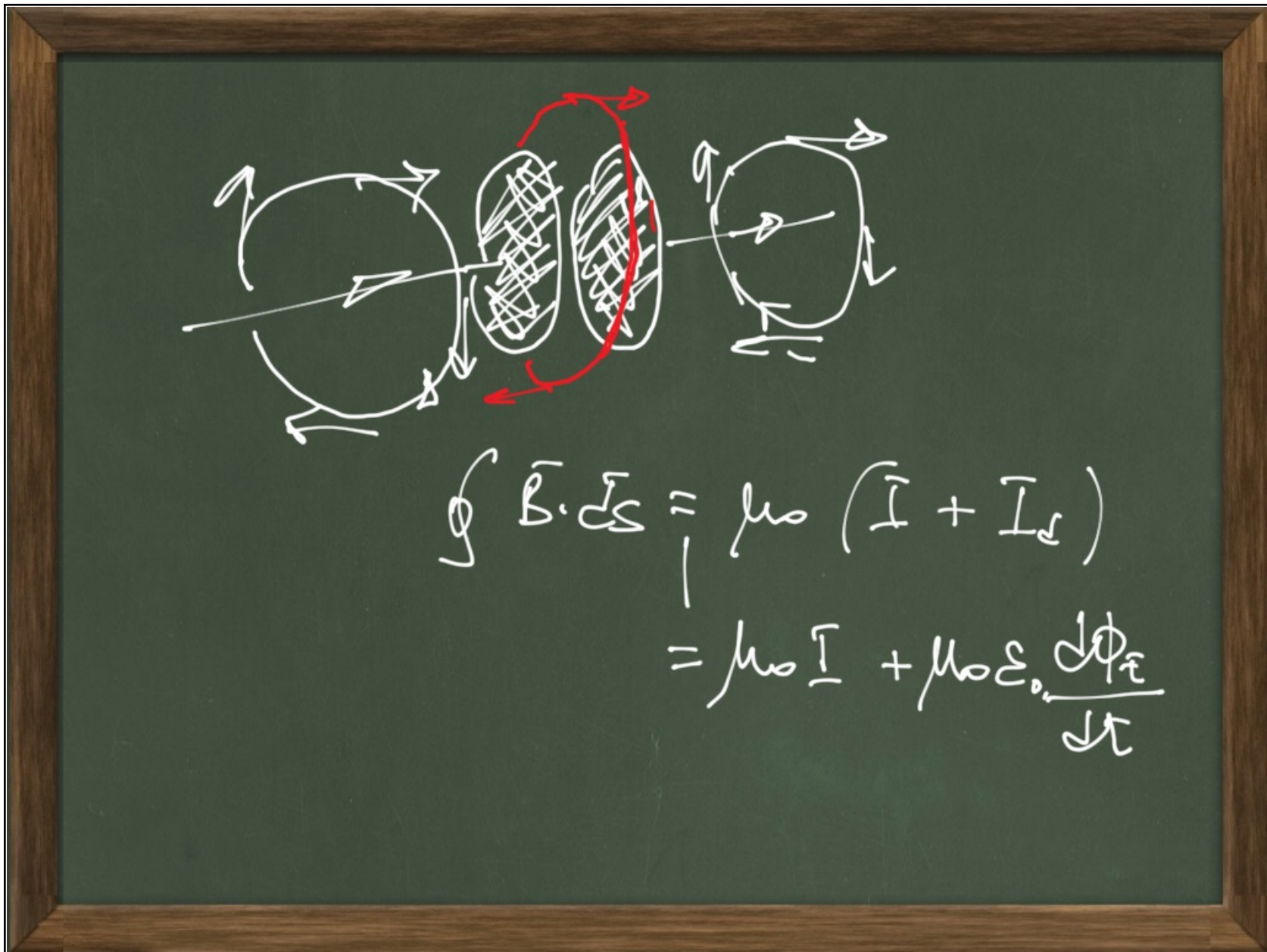
$$Q = CV = \frac{\epsilon_0 A}{h} E h$$

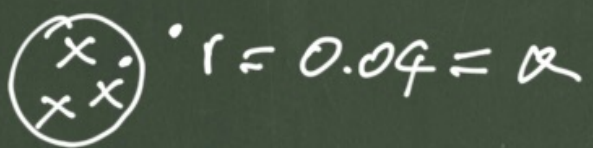
$$q = \epsilon_0 A E$$

$$\vec{I} = \frac{dq}{dt} = \epsilon_0 A \frac{dE}{dt} = \epsilon_0 \frac{d\Phi_E}{dt}$$

Displacement curr. $= I_d$






 $r = 0.04 = a$


$\mathcal{E} = V/h$

$V = V_m (1 - e^{-t/RC})$

$\oint_C \mathbf{B} \cdot d\mathbf{s} = \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$

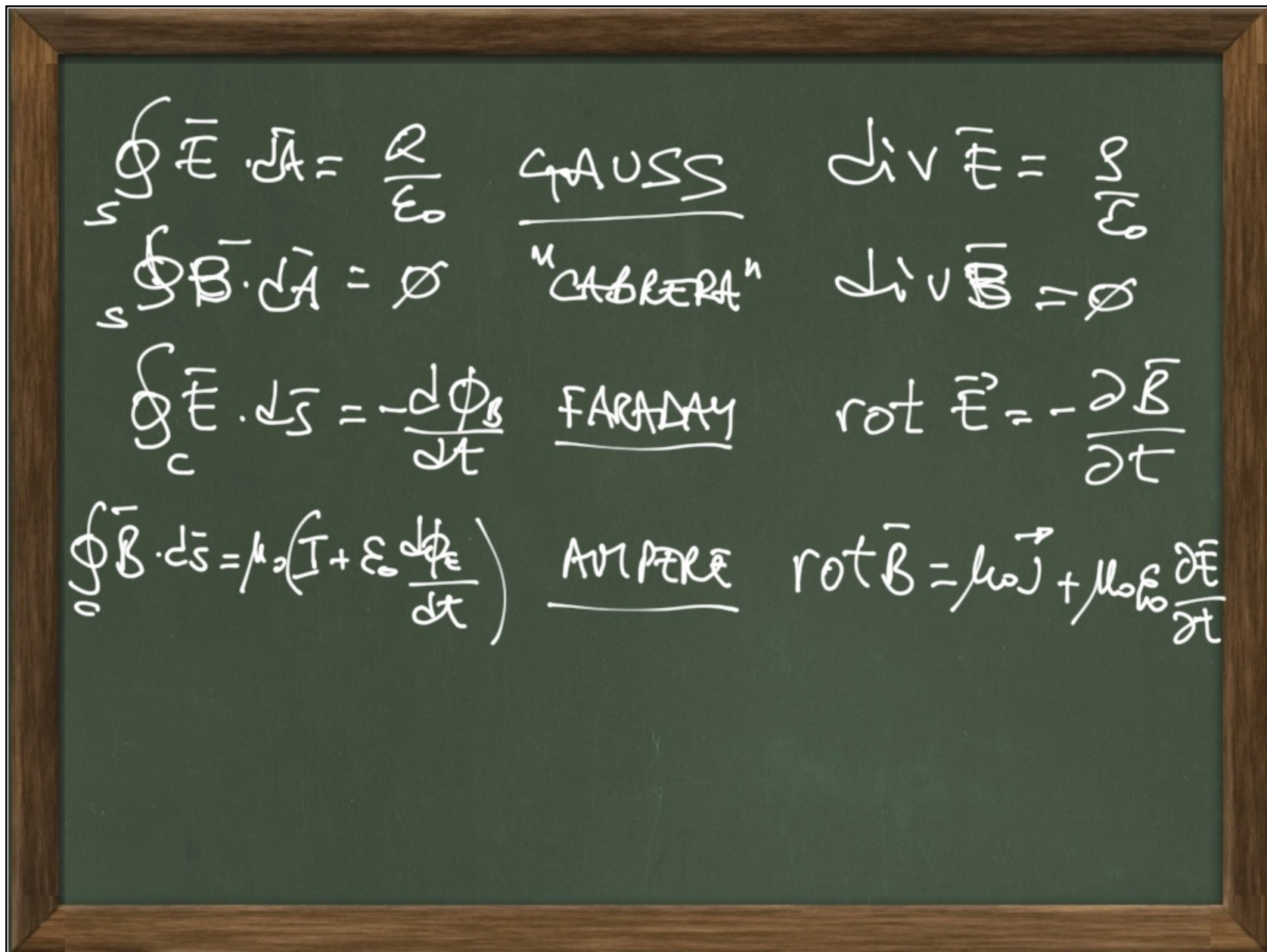
$2\pi r B = \mu_0 \epsilon_0 \pi a^2 \frac{d\mathcal{E}}{dt}$

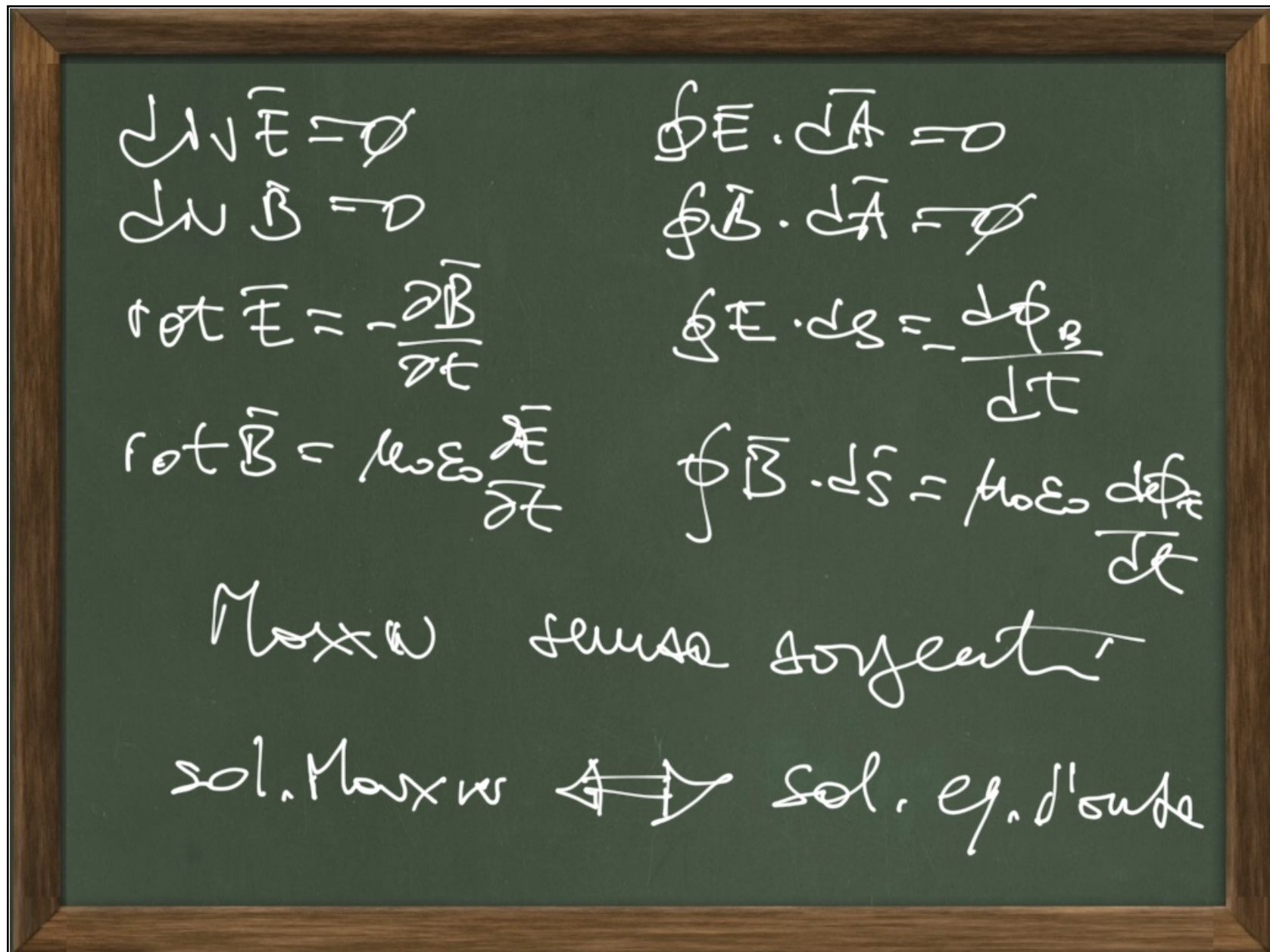
$B = \frac{\mu_0 \epsilon_0 \pi a^2}{2\pi r h RC} e^{-t/RC}$

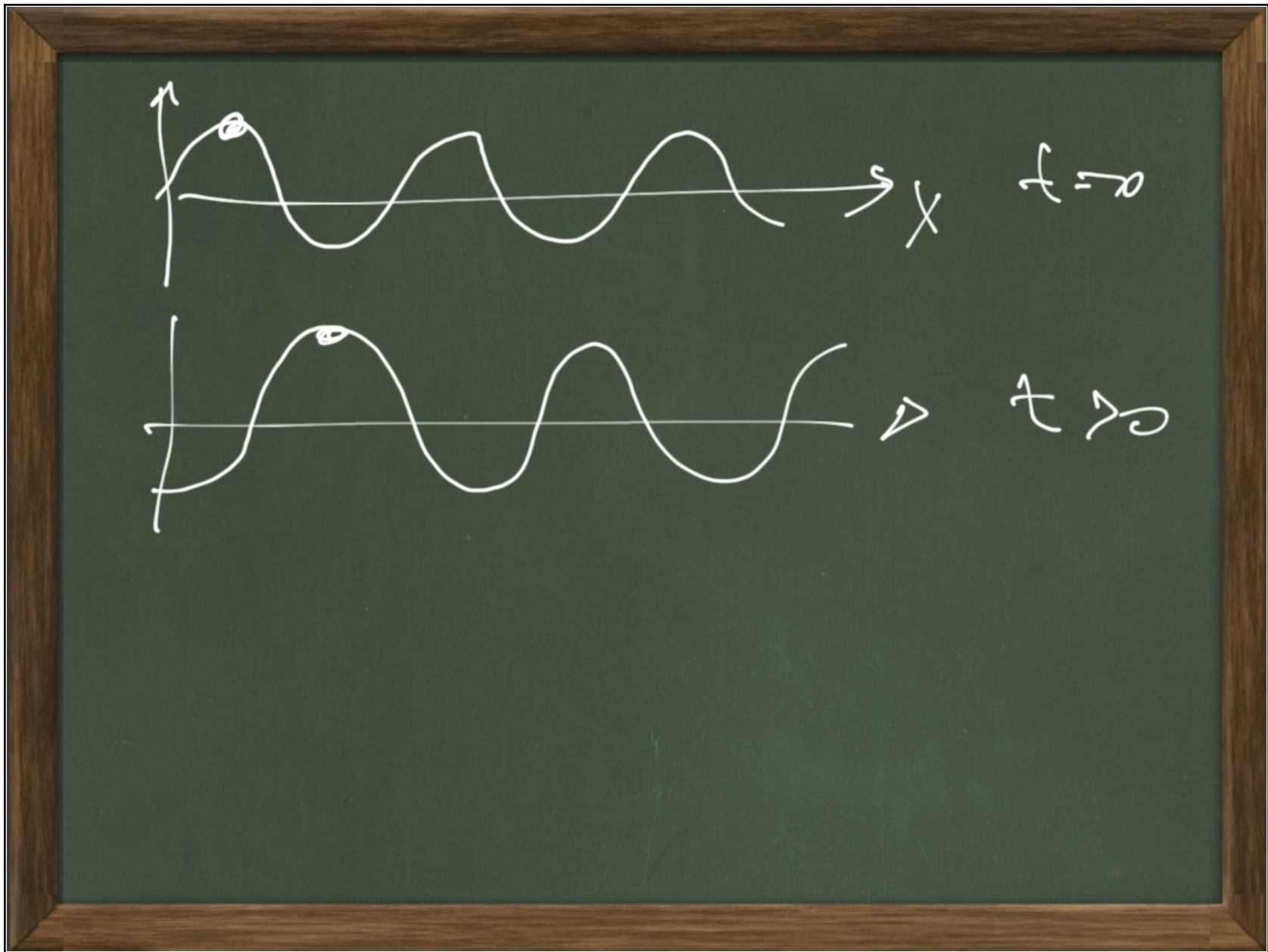


$\mathcal{E} = \mathcal{E}_0 + t^2$

$$\begin{aligned}
 RLC \quad R=1, C=21 \text{ nF} \quad L=13 \mu\text{H} \\
 I_0 = 5 \text{ A} \quad \text{RIS: } \omega = \omega_{LC} \\
 \omega_{LC} = \frac{1}{\sqrt{LC}} \\
 = \frac{1}{\sqrt{13 \cdot 21 \cdot 10^{-9} \cdot 10^{-3}}} \\
 = 0.0610^{-6} = 60 \text{ kHz} \\
 Z = R \quad \phi = 0 \rightarrow \omega \rightarrow \phi \\
 V_R = I_0 R \quad V_L = X_L I_0 \quad V_L = V_C \\
 V_C = X_C I_0
 \end{aligned}$$







$$y = y_0 \cos(kx - \omega t) \quad kx \equiv \bar{k} \cdot \bar{r}$$

$$x=0 \quad y_0 \cos \omega t$$

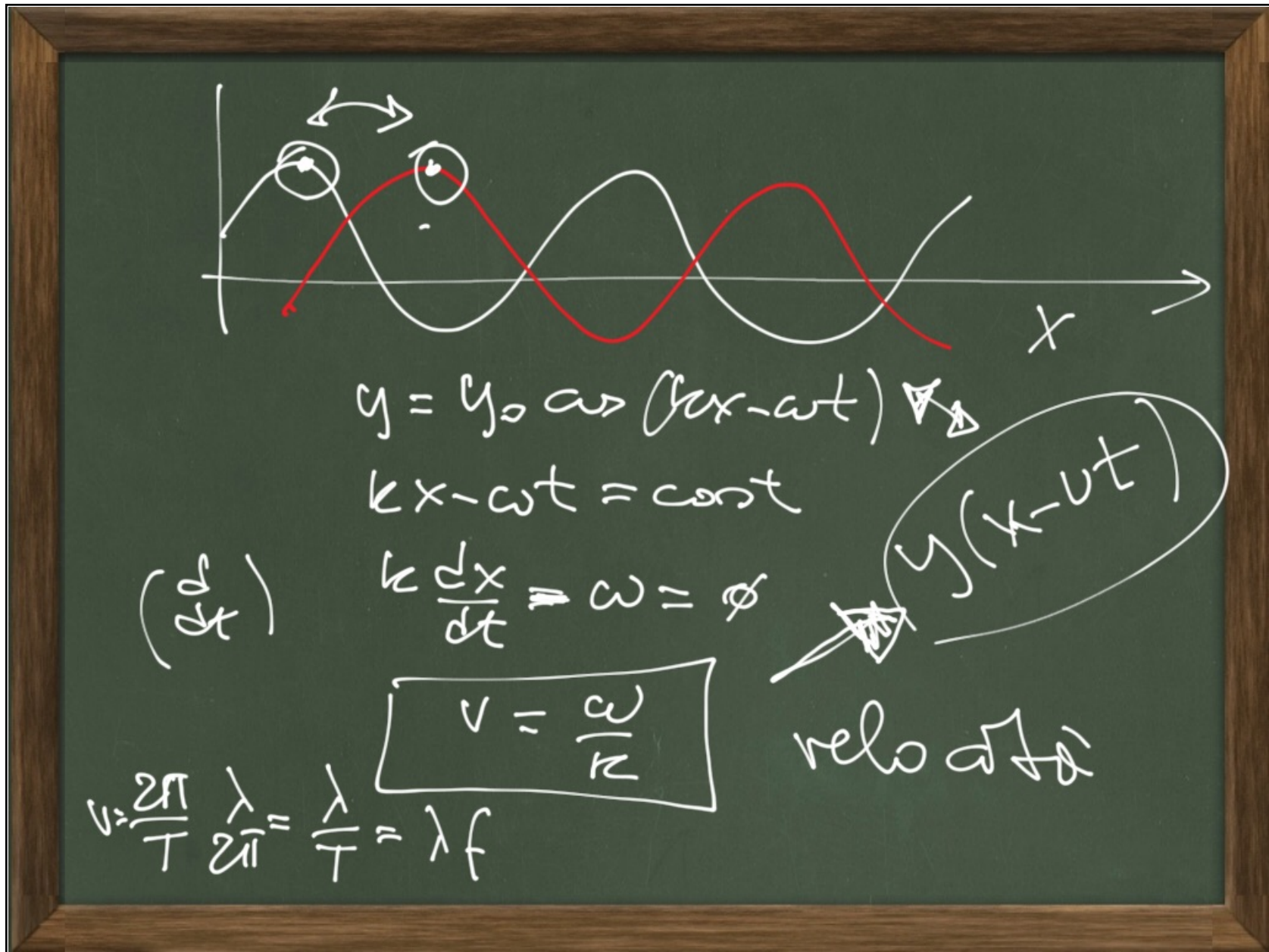
$$\cos(\omega(t+T)) = \cos(\omega t + 2\pi)$$

$$t=0 \quad y = y_0 \cos(kx) \quad \omega T = 2\pi$$

$$T = \frac{2\pi}{\omega}$$

$$\cos(k(x+\lambda)) = \cos(kx + 2\pi)$$

$$k\lambda = 2\pi \quad \lambda = \frac{2\pi}{k} \quad k = \frac{2\pi}{\lambda}$$



$F_n \sim T (\sin \theta_1 - \sin \theta_2)$
 $\theta \sim \sin \theta$
 $\theta \approx \phi$

$F_n \sim T (f \theta_1 - f \theta_2) = T \left(\left. \frac{dy}{dx} \right|_{x+dx} - \left. \frac{dy}{dx} \right|_x \right)$
 $= T \frac{d^2 y}{dx^2} dx$

$= \mu a = \mu dx \frac{\partial^2 y}{\partial t^2}$

$\mu dx = m$

$y_{xx} - \frac{1}{v^2} y_{tt} = 0$

$\frac{\partial^2 y}{\partial x^2} - \frac{\mu}{T} \frac{\partial^2 y}{\partial t^2} = 0$

$$y(x,t) \stackrel{\text{def}}{=} y(x-ut) \quad y = G \quad z = x-ut$$

$$G(z)$$

$$\frac{\partial y}{\partial x} = \frac{\partial G}{\partial z} \frac{\partial z}{\partial x} = \frac{\partial G}{\partial z}$$

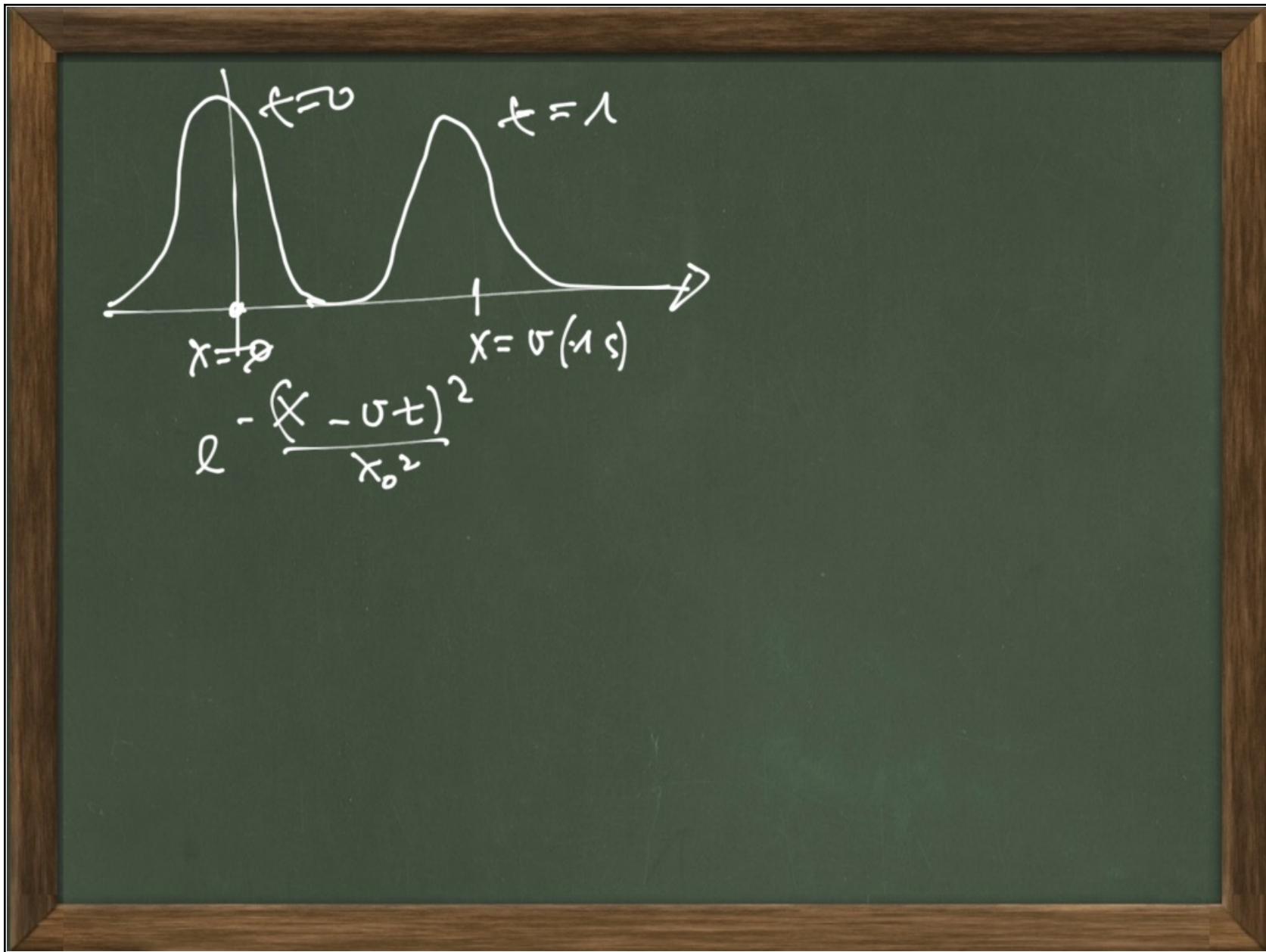
$$\frac{\partial^2 y}{\partial x^2} = \frac{\partial^2 G}{\partial z^2}$$

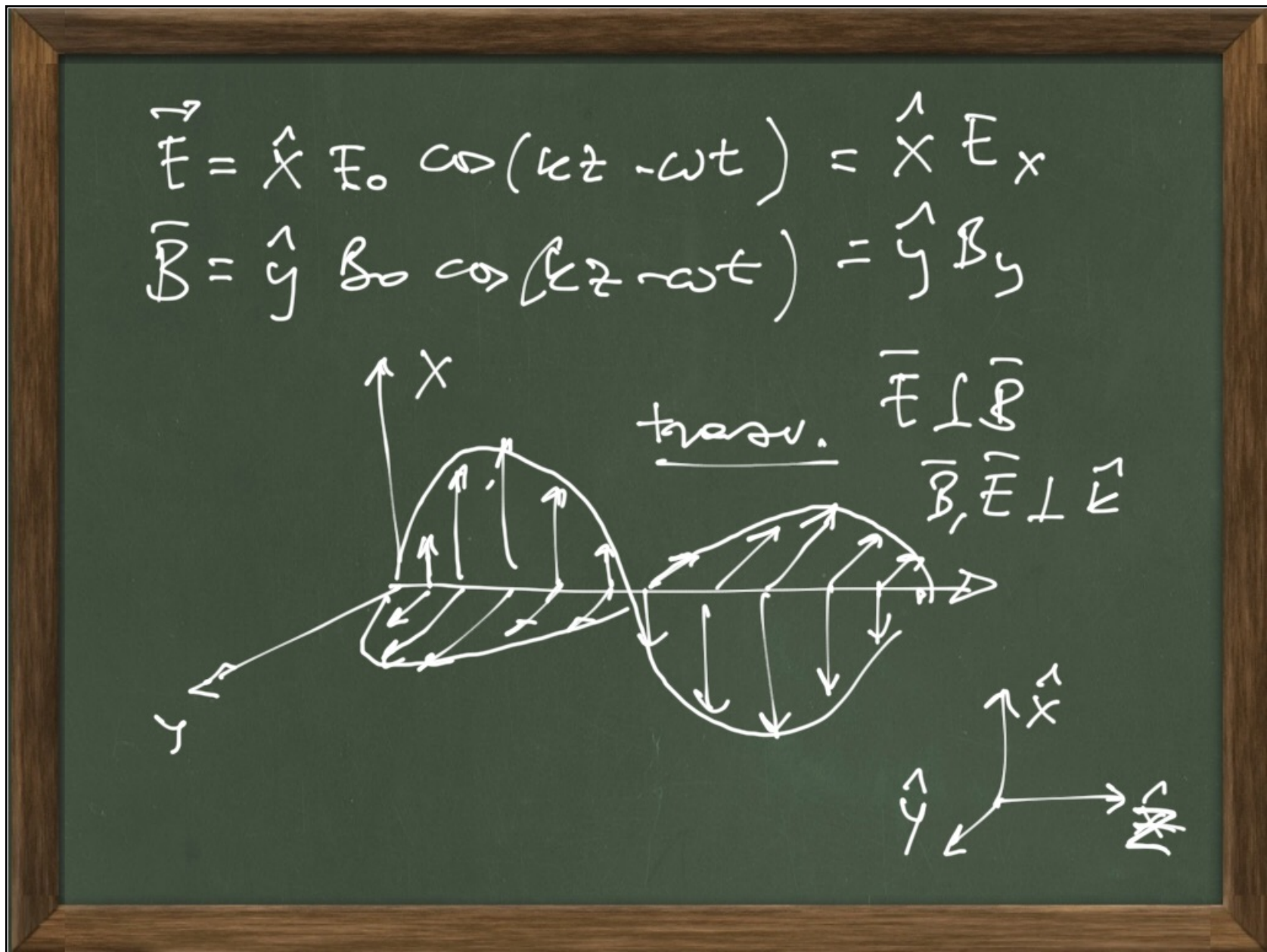
$$\frac{1}{v^2} \frac{\partial^2 y}{\partial t^2} = \frac{\partial^2 G}{\partial z^2}$$

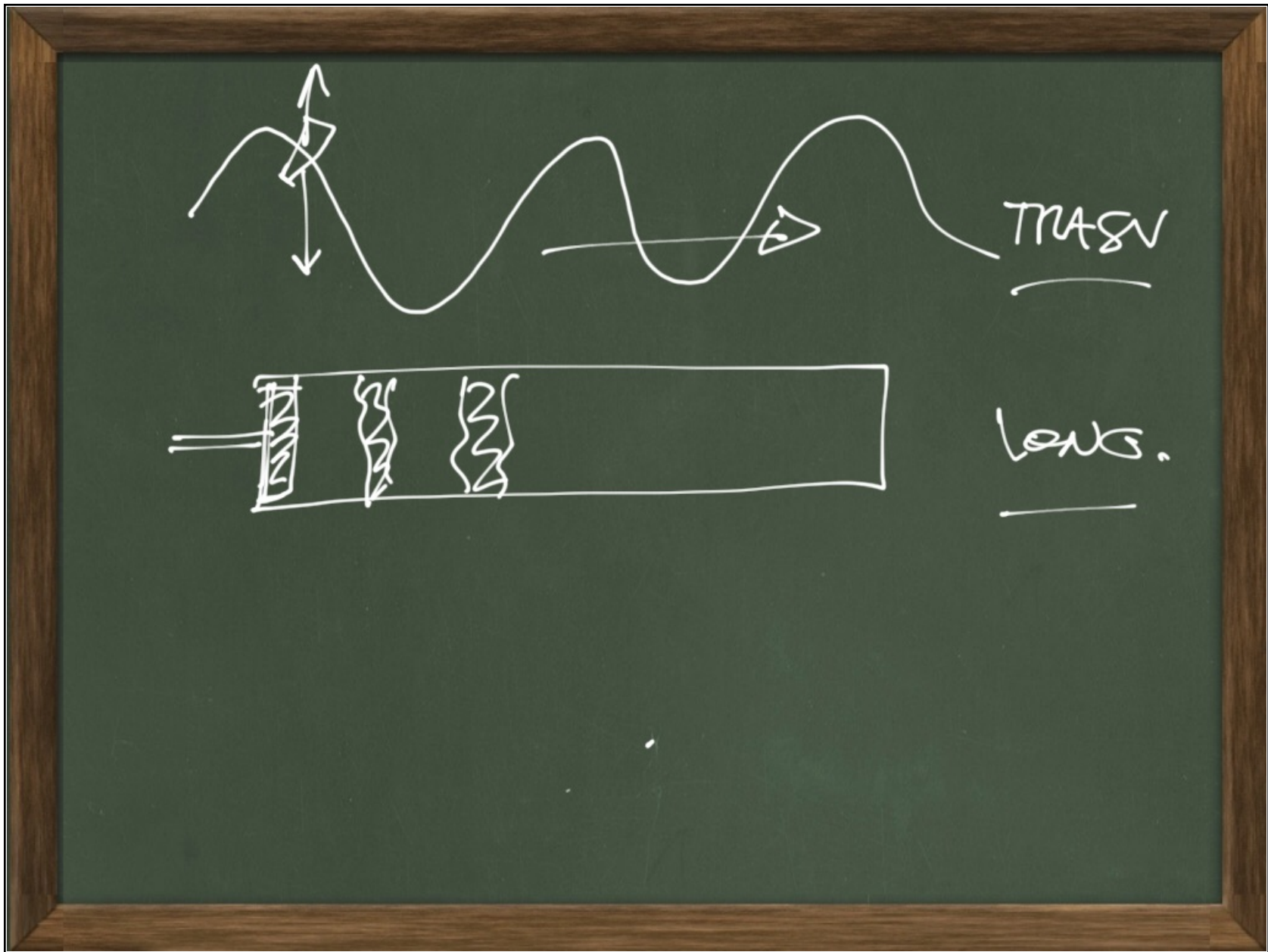
$$\frac{\partial y}{\partial t} = \frac{\partial G}{\partial z} \frac{\partial z}{\partial t} = (-v) \frac{\partial G}{\partial z}$$

$$\frac{\partial^2 y}{\partial t^2} = \frac{\partial^2 G}{\partial z^2} (-v)^2$$

$$\Psi = A y(x-ut) + B y(x+vt)$$







Eq. "della legge di Gauss" (flussi)

$$\operatorname{div} \vec{E} = \varnothing = \operatorname{div} \vec{B} =$$

$$\downarrow \quad \downarrow$$

$$= \frac{\partial E_x}{\partial x} + \dots = \varnothing = \dots + \frac{\partial B_y}{\partial y} + \dots$$

$$\frac{\partial}{\partial x} E_x = \frac{\partial}{\partial x} E_0 \cos(kz - \omega t) = \varnothing$$

$$\frac{\partial}{\partial y} B_y = \dots = \varnothing$$

$$\begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \partial_x & \partial_y & \partial_z \\ E_x & E_y & E_z \end{vmatrix} = \hat{x} (\partial_y E_z - \partial_z E_y) + \hat{y} (\partial_x E_z - \partial_z E_x) + \hat{z} (\partial_x E_y - \partial_y E_x)$$

\swarrow IV eq. III eq. \searrow

$$\vec{\nabla} \times \vec{E}$$

$$\begin{aligned} \text{rot } \vec{E} &= -\frac{\partial \vec{B}}{\partial t} = -\hat{y} B_0 \omega \sin(kz - \omega t) \\ &= \hat{y} \left(-\frac{\partial E_x}{\partial z} \right) = -\hat{y} k E_0 \sin(\dots) \end{aligned}$$

$$\frac{B_0 \omega}{k} = E_0 \qquad \frac{\omega}{k} \equiv c$$

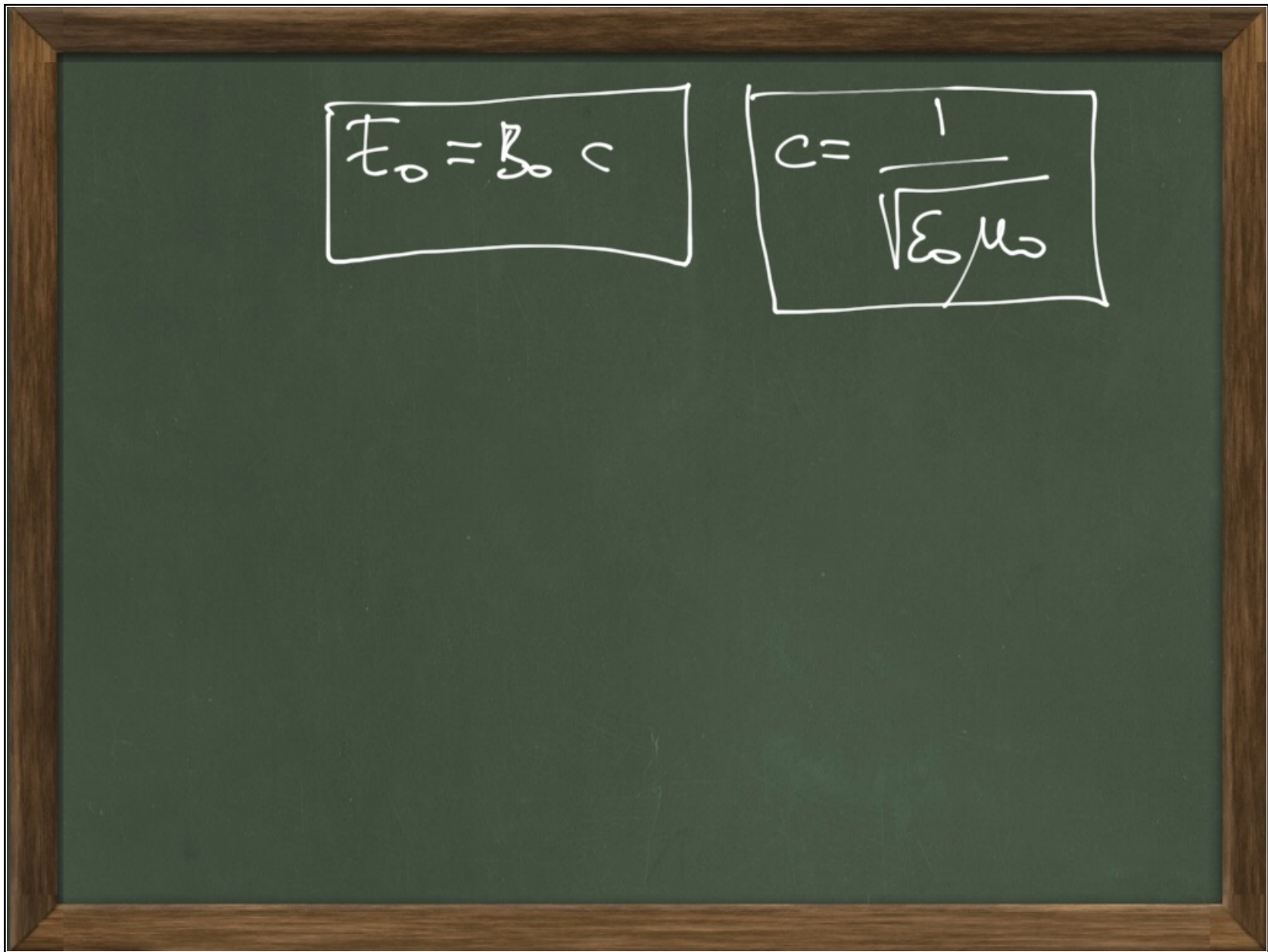
* $B_0 c = E_0$

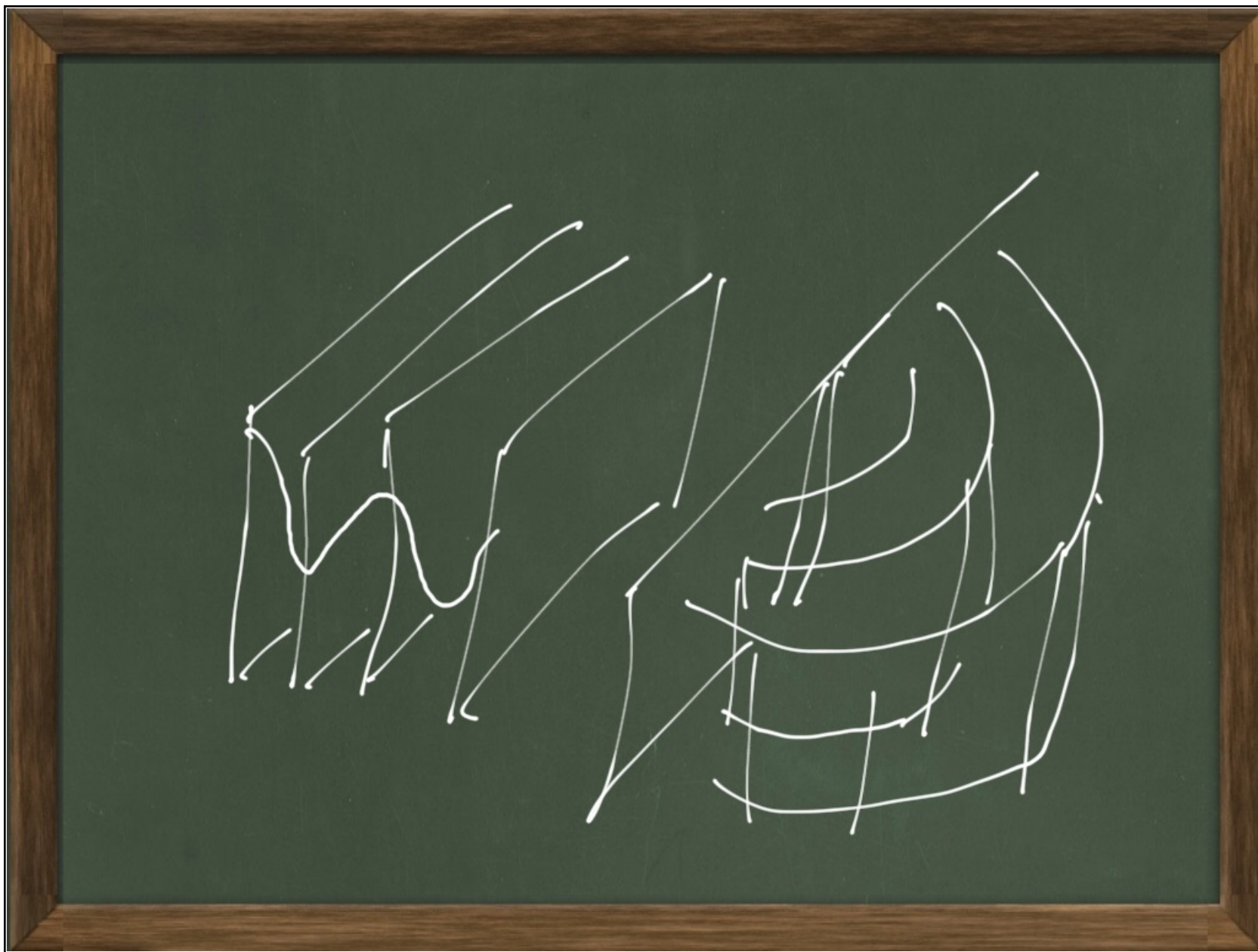
$$\begin{aligned}
 \text{rot } \vec{B} &= \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \mu_0 \epsilon_0 E_0 \hat{x} (\omega \sin(kz - \omega t)) \\
 &= -\hat{x} \frac{\partial B_y}{\partial z} = \\
 &= \hat{x} k B_0 \sin(kz - \omega t)
 \end{aligned}$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$\begin{aligned}
 B_0 &= \mu_0 \epsilon_0 E_0 \frac{\omega}{k} \\
 &= \mu_0 \epsilon_0 E_0 c \\
 &\approx \mu_0 \epsilon_0 B_0 c^2
 \end{aligned}$$

$$c^2 = \frac{1}{\mu_0 \epsilon_0}$$





$$\text{rot}(\text{rot } \bar{E}) = \text{rot} \left(-\frac{\partial \bar{B}}{\partial t} \right) = \quad \int \nabla \cdot \bar{E} = \rho / \epsilon_0$$

$$\cancel{\text{grad} \text{div} \bar{E} - \text{div} \text{grad} \bar{E}} = -\frac{\partial}{\partial t} (\text{rot } \bar{B}) = \frac{\partial}{\partial t} \left(\cancel{\mu_0 \bar{J}} + \mu_0 \epsilon_0 \frac{\partial \bar{E}}{\partial t} \right)$$

$$= -\frac{\partial^2 \bar{E}}{\partial t^2} \mu_0 \epsilon_0$$

$$\nabla \cdot \bar{A} = \left(\hat{x} \frac{\partial}{\partial x} + \dots \right) \left(\hat{x} A_x + \dots \right)$$

$$\frac{\partial A_x}{\partial x} + \dots$$

$$\begin{aligned}
 \nabla \cdot \nabla \vec{E} &= \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} \right) \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} \right) \vec{E} \\
 &= \frac{\partial^2}{\partial x^2} E_x + \dots \\
 &= \nabla^2 \vec{E} \\
 &= \Delta \vec{E}
 \end{aligned}$$

$$\nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\nabla^2 \vec{E} = \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2}$$

REIFIGARTE

$$\frac{\partial^2 E}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E}{\partial t^2}$$

~~Geschieb~~
~~X~~
~~X' = X + vt~~

Lorentz \leftarrow

$$u_E = \frac{\epsilon_0 E^2}{2} = \frac{E^2}{2\mu_0 c^2} = \frac{B^2}{2\mu_0} = u_B$$

$$u = \epsilon_0 E^2 = \epsilon_0 E B c$$

$$V = u c = \epsilon_0 E B c^2$$

$$l = c \Delta t = c$$

$$A = 1$$

$$\frac{E B}{\mu_0} \frac{m}{m} = \frac{V}{m} \frac{I}{m} = \frac{V}{m} \frac{A \Delta t}{m} = \frac{W}{m^2}$$

puissance
 are

